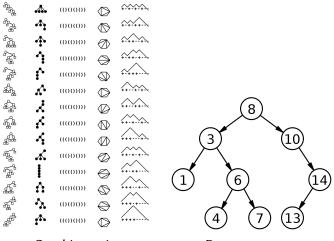
Trees on Trees



Jean Cardinal, Université libre de Bruxelles (ULB) Joint work with Jit Bose (Carleton), John Iacono, Greg Koumoutsos, Stefan Langerman, and Pablo Pérez-Lantero (USACH)

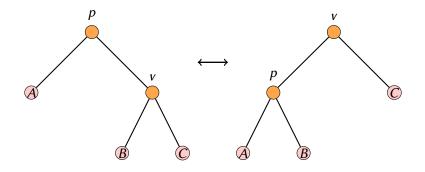
Binary Trees



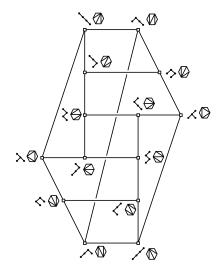
Combinatorics

Data structures

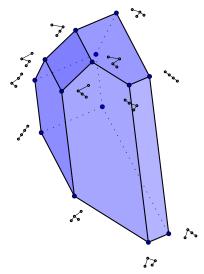
Rotations



Rotations and Flips



Associahedra



Tamari 1951 - Stasheff 1963 - Lee 1989 - Loday 2004

Diameter of Associahedra

What is the maximum number of rotations required to transform one binary tree on *n* internal nodes into another?

The diameter of the associahedron is 2n - 6.

Sleator, Tarjan, Thurston 1988

Pournin 2014

Online Binary Search Trees

- BST search model: finger moves and rotations are unit-cost operations
- Given an *access sequence* of nodes, what is the minimum sequence of unit-cost operations that touch these nodes in order?
- Is there an *O*(1)-competitive online BST?

Sleator and Tarjan 1985

Demaine et al. 2009

• Dynamic optimality conjecture: *Splay trees* are *O*(1)-competitive.

Sleator and Tarjan 1985

• *Tango trees* are *O*(log log *n*)-competitive.

Demaine, Harmon, Iacono, Pătrașcu 2007

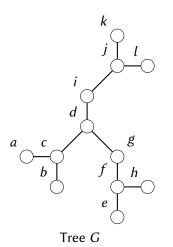
Trees on Trees?

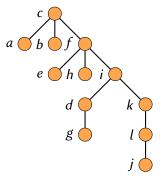
- Binary search trees deal with a linearly ordered search space.
- Generalize the notion of search trees to a *tree-structured* search space.
- Rotations and associahedra are well-defined.

Two questions:

- 1. Diameter of tree associahedra?
- 2. Competitive online search trees on trees?

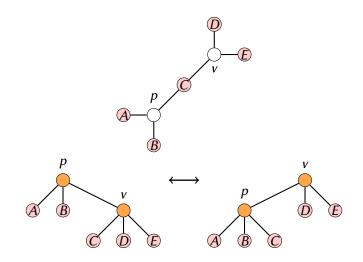
Trees on Trees





Search tree T on G

Rotations



Related Notions

Vertex ranking

Schäffer 1989 Bodlaender et al. 1998

- Tree-depth
- Graph associahedra

Nešetřil and Ossona de Mendez 2012

Carr and Devadoss 2006 Postnikov 2009

• Optimal search in trees

Ben-Asher, Farchi, Newman 1999 Cicalese et al. 2011, 2014, 2016 Emamjomeh-Zadeh, Kempe, Singhal 2016

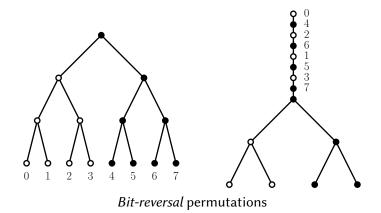
Diameter of Tree Associahedra

The diameter of graph associahedra is at least |E| and at most $O(n^2)$. Is the diameter of tree associahedra O(n)?

Manneville and Pilaud 2015

The diameter of tree associahedra is $\Theta(n \log n)$. C., Langerman, Pérez-Lantero 2018

Diametral Pair



Online Search Trees on Trees

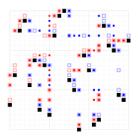
- GST search model: finger moves and rotations are unit-cost operations
- Given an *access sequence* of nodes of *G*, what is the minimum sequence of unit-cost operations that touch these nodes in order?
- Can we design competitive online search trees on trees?

Tentative Generalizations

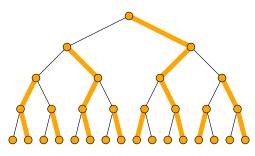
Many previous techniques / ideas do not generalize immediately:

- Splay trees
- Greedy algorithm
- Geometric view





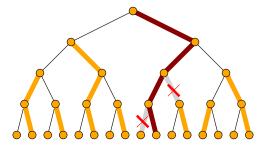
Preferred Paths and Lower Bound



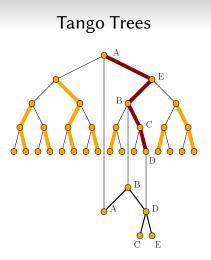
- Consider a fixed *balanced reference tree*.
- Preferred children keep track of last accesses.
- Interleave bound: total number of times some preferred child changes.

The interleave bound is a lower bound on the cost of an access sequence in the BST model.

Tango Trees



• Changes in the preferred children are implemented via *splitting and merging* the preferred paths.



• Preferred paths are maintained using *red-black trees*, that can be split and merged in *O*(log log *n*) time, since the reference tree has height *O*(log *n*).

Tango Trees on Trees

The interleave bound is a lower bound on the cost of an access sequence in the GST model.

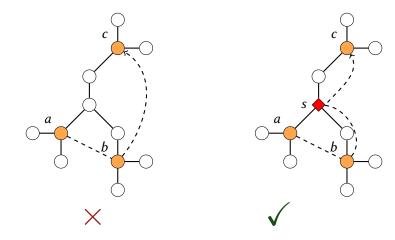
Bose et al. 2019

Generalize Tango trees:

- Balanced reference tree via centroid decomposition.
- The reference tree needs to be *Steiner-closed*.
- Splits and merges of paths can be handled by *link-cut trees*.

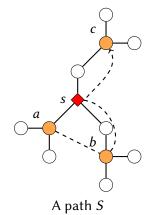
Steiner-Closed Trees on Trees

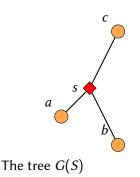
A path *S* in a search tree is Steiner-closed if every vertex in $CH(S) \setminus S$ has degree exactly two in CH(S).



Merges and Splits of Preferred Paths

- If every path *S* in the reference tree is Steiner-closed, then it can be associated with a tree *G*(*S*),
- and merges and splits of the preferred paths correspond to at most two *links* and *cuts* of the corresponding trees *G*(*S*).





A Swiss Army Knife

• These can be implemented with *link-cut* trees.

Sleator and Tarjan 1983

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A Data Structure for Dynamic Trees

DANIEL D. SLEATOR AND ROBERT ENDRE TARJAN

Bell Laboratories, Murray Hill, New Jersey 07974

Received May 8, 1982; revised October 18, 1982

A data structure is proposed to maintain a collection of vertex-disjoint trees under a sequence of two kinds of operations: a *link* operation that combines two trees into one by adding an edge, and a *cut* operation that divides one tree into two by deleting an edge. Each operation requires $O(\log n)$ time. Using this data structure, new fast algorithms are obtained

Overview

- Construct a balanced Steiner-closed reference tree P on G.
- First-level decomposition of *P* into preferred paths *S*, each corresponding to an unrooted tree *G*(*S*).
- As searches are performed, preferred paths are updated, and these updates correspond to linking and cutting trees *G*(*S*).
- Link-cut trees use a second-level decomposition of the trees *G*(*S*) into paths.
- Operations on those paths are eventually handled by splay trees. Together, they form a search tree on *G*.

Summary and Perspectives

- The diameter of tree associahedra is $\Theta(n \log n)$.
- There exist $O(\log \log n)$ -competitive online search trees on trees.

Dynamic optimality for online search trees on trees?

Pointers

(click on the title)

- Jean Cardinal, Stefan Langerman, Pablo Pérez-Lantero: On the Diameter of Tree Associahedra. Electron. J. Comb. 25(4): P4.18 (2018).
- Prosenjit Bose, Jean Cardinal, John Iacono, Grigorios Koumoutsos, Stefan Langerman: Competitive Online Search Trees on Trees. SODA 2020: 1878-1891.