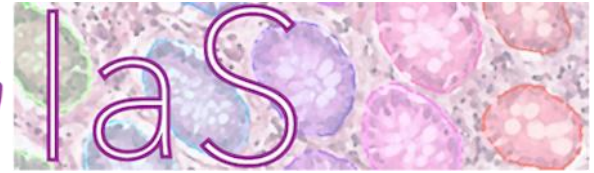




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Colon Gland Segmentation with Deep Convolutional Neural Networks and Total Variation Segmentation

Team vision4GlaS

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Colon Gland Segmentation Algorithm Overview

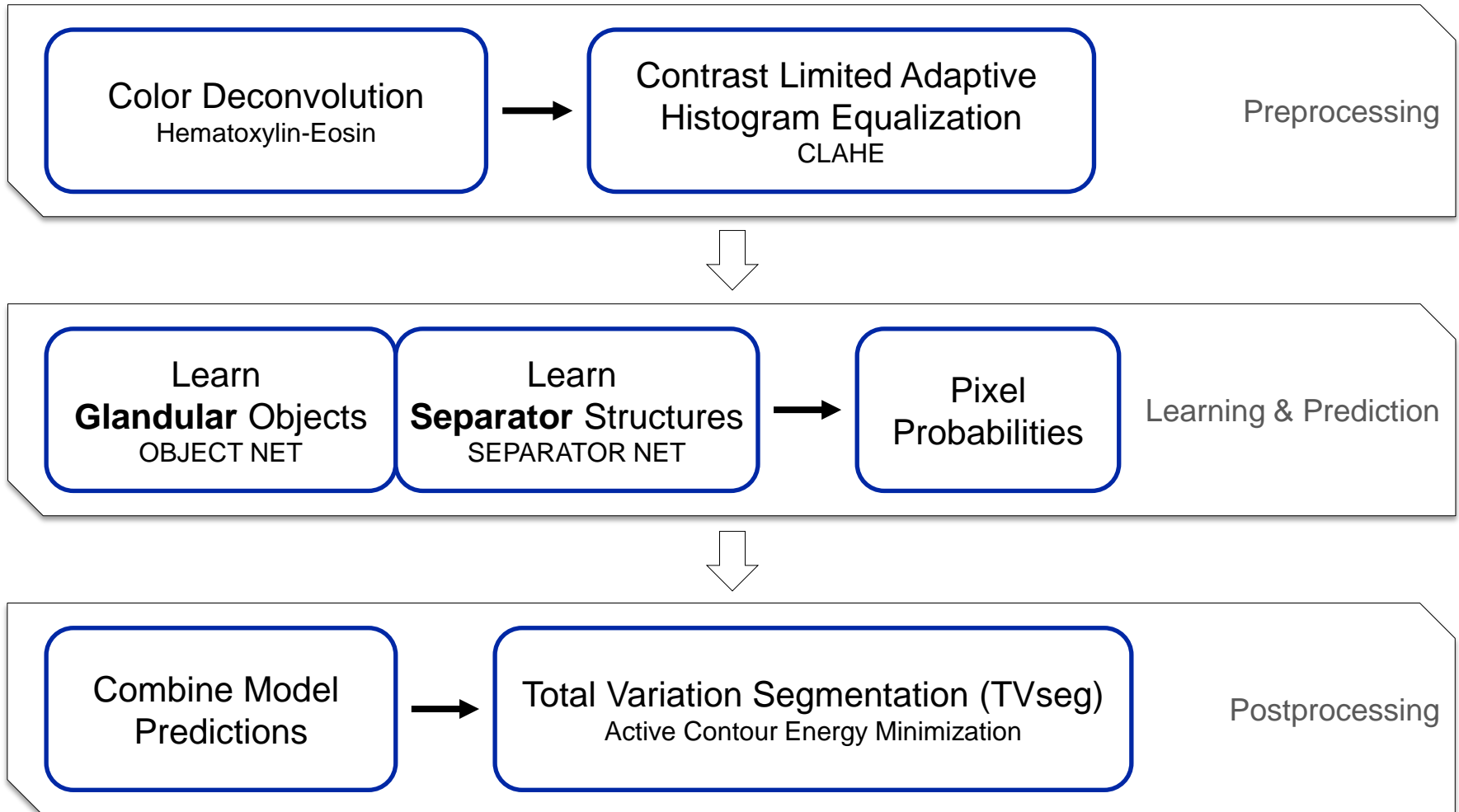
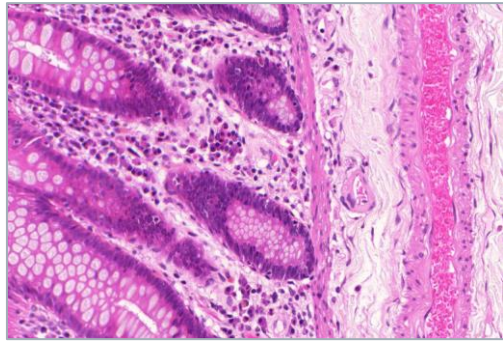
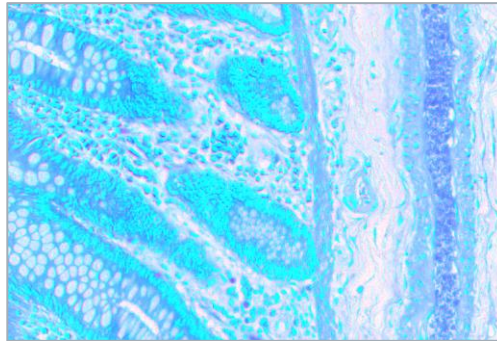


Image Preprocessing: Tissue Decomposition

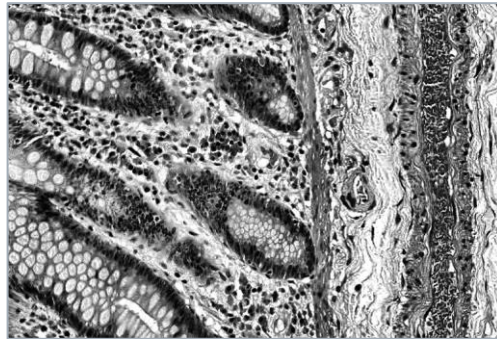
Color Deconvolution [Ruifrok and Johnston, 2001]



source image (RGB)

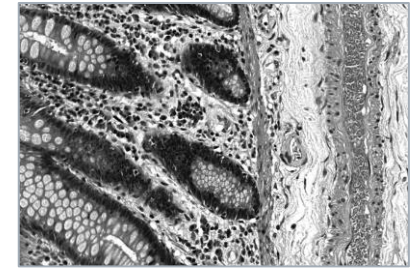


deconvolved image (RGB)

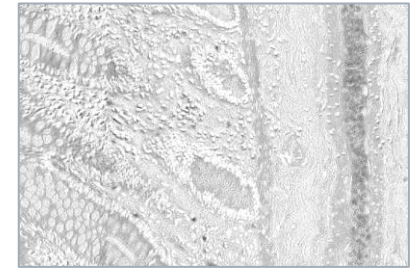


red channel, CLAHE

Contrast Limited Adaptive
Histogram Equalization
[Zuiderveld, 1994]



red channel

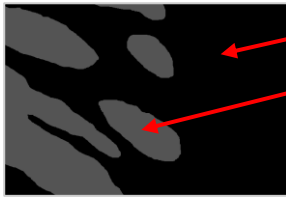
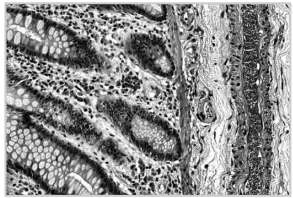


green channel

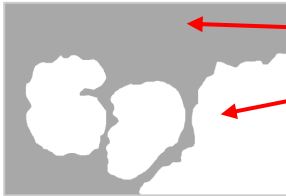
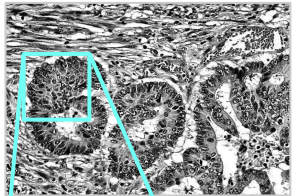


blue channel

Learning Glandular Objects



C_0 : background benign
 C_1 : gland benign

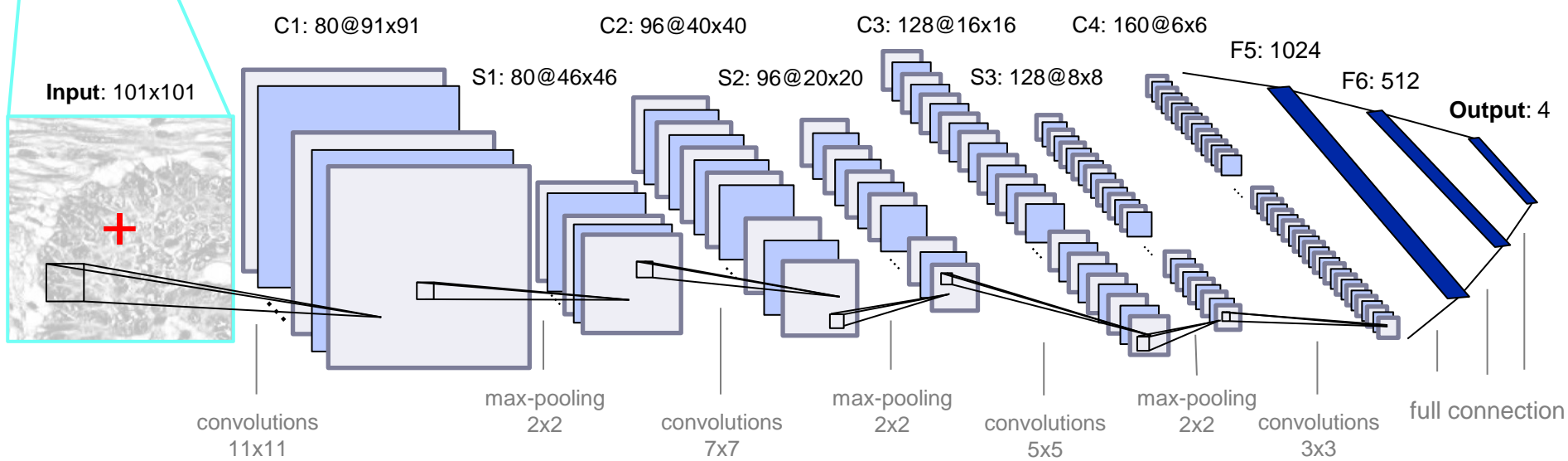


C_2 : background malignant
 C_3 : gland malignant

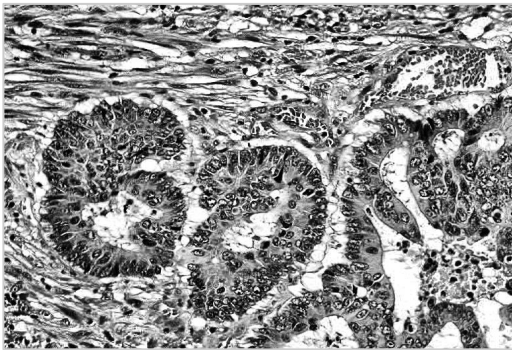
4-Class Classification

OBJECT NET
predicts the label of the center pixel in a 101x101 px patch

Deep Convolutional Neural Network [LeCun *et al.*, 2010]



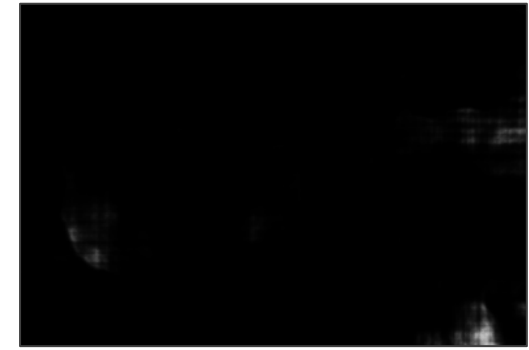
Predicting Glandular Objects



input image



background benign



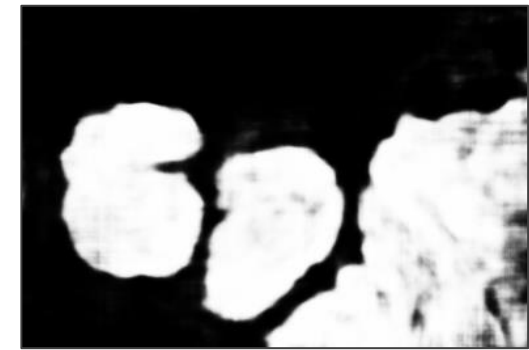
gland benign



annotation image

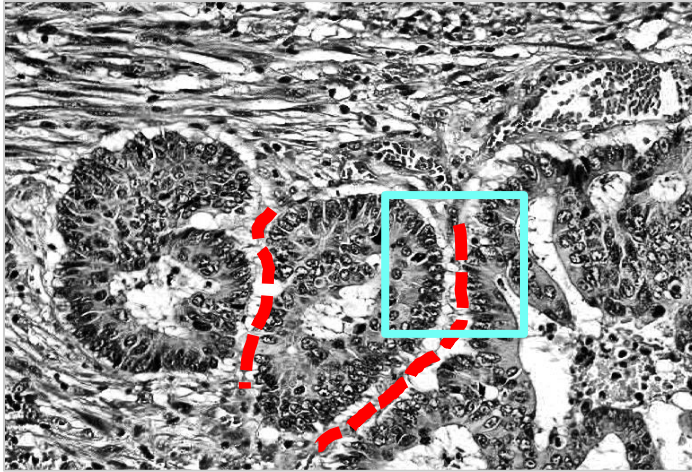


background malignant



gland malignant

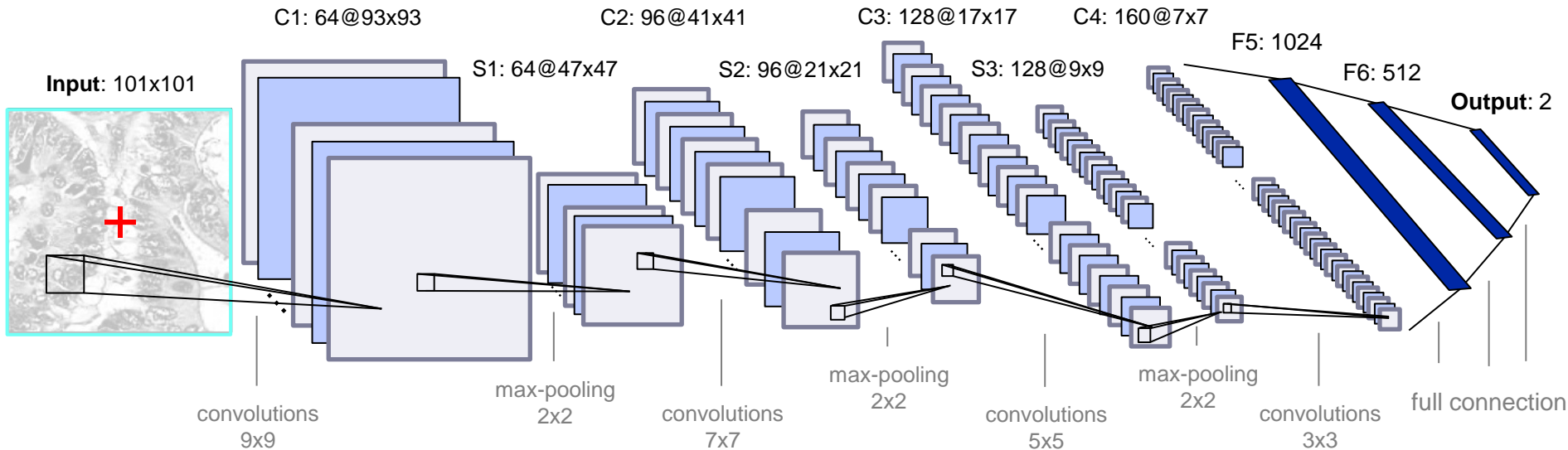
Learning Separator Structures



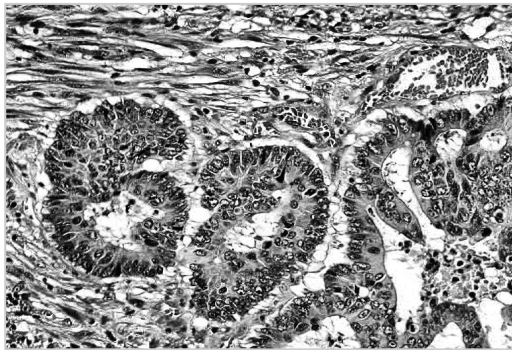
Binary Classification

SEPARATOR NET

predicts the label of the center pixel in a 101x101 px patch



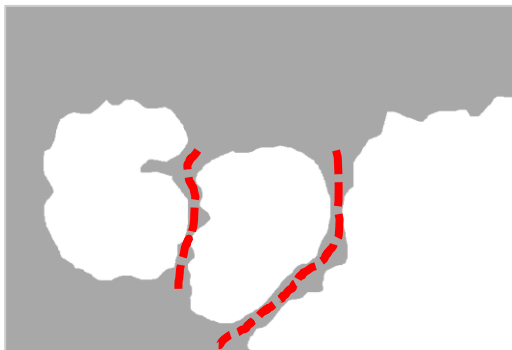
Predicting Separator Structures



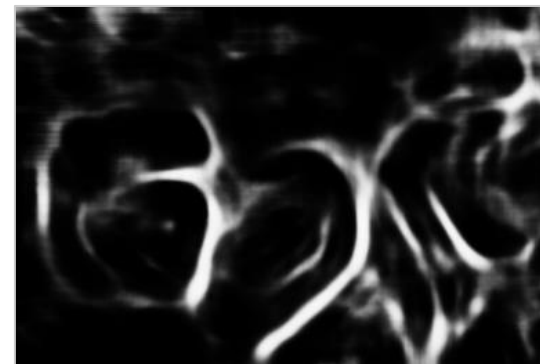
input image



non-separator structures

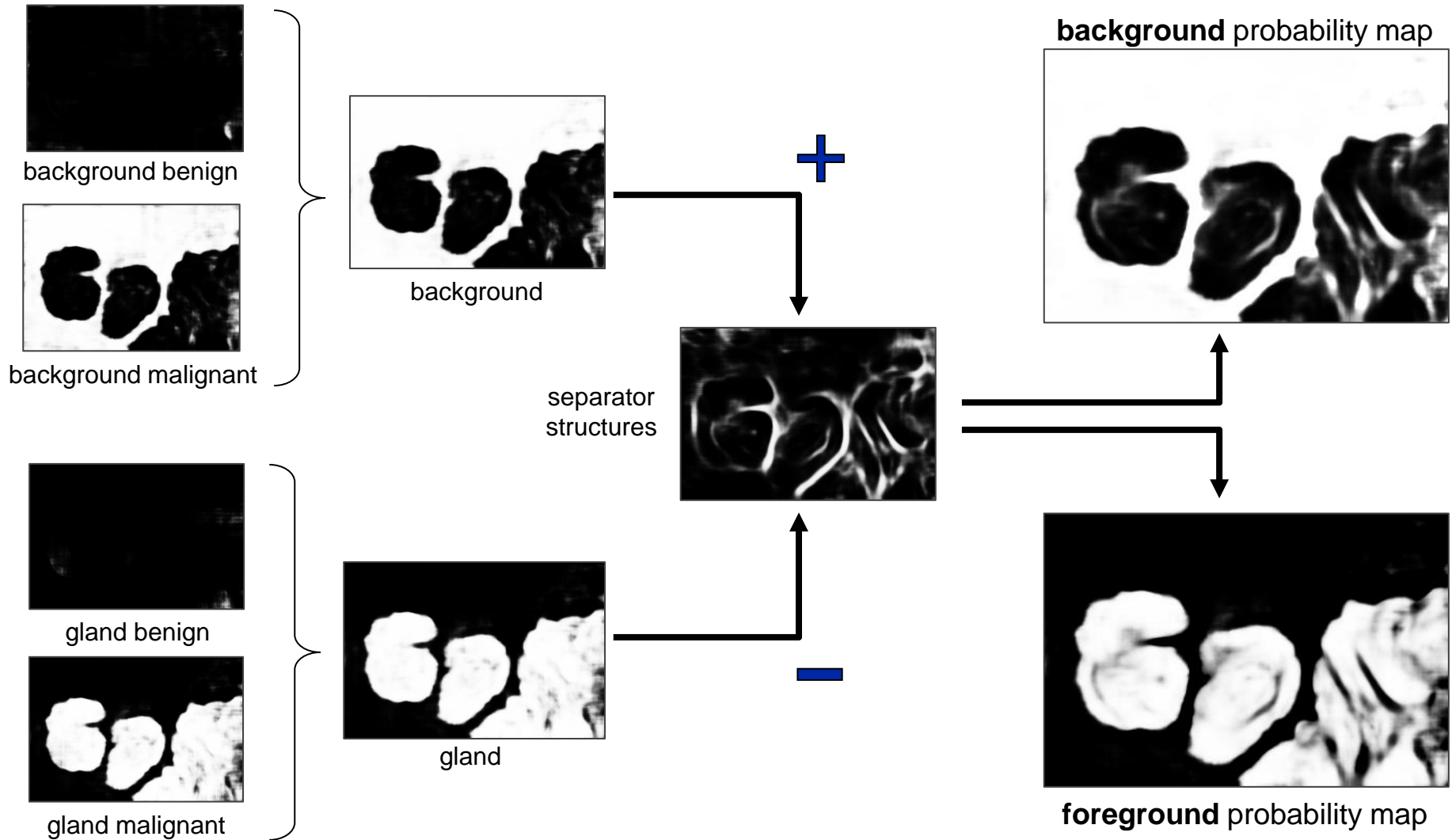


annotation image



separator structures

Combining Model Predictions

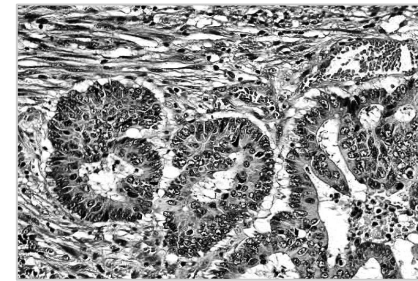


Total Variation Segmentation

Based on a **convex geodesic active contour** model, a figure-ground segmentation u is computed:

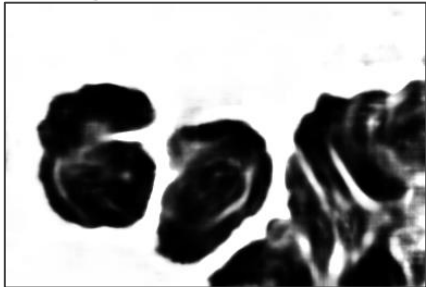
$$\min_u E_{seg}(u) = \min_u \int_{\Omega} g(x) |\nabla u(x)| dx + \lambda \int_{\Omega} u(x) \cdot w(x) dx$$

$$\text{s.t. } u \in C_{box} = \{u : u(x) \in [0, 1], \forall x \in \Omega\}$$



input $I(x)$

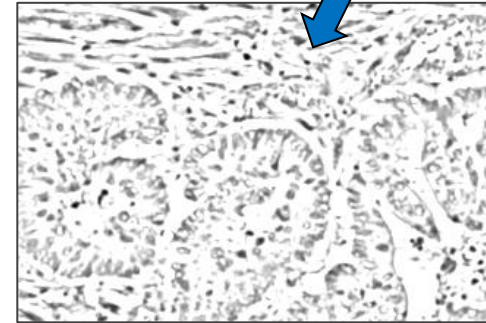
background probability map



foreground probability map



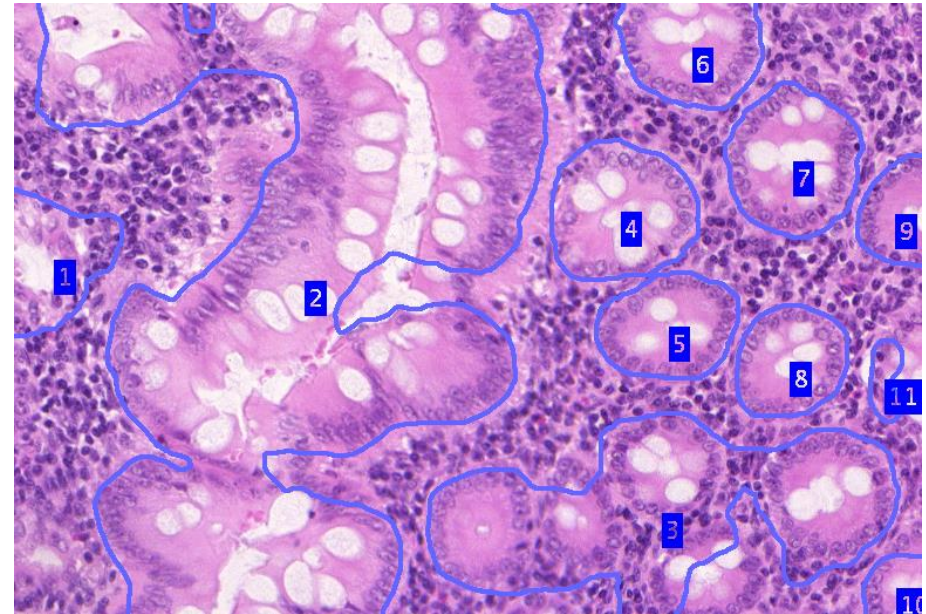
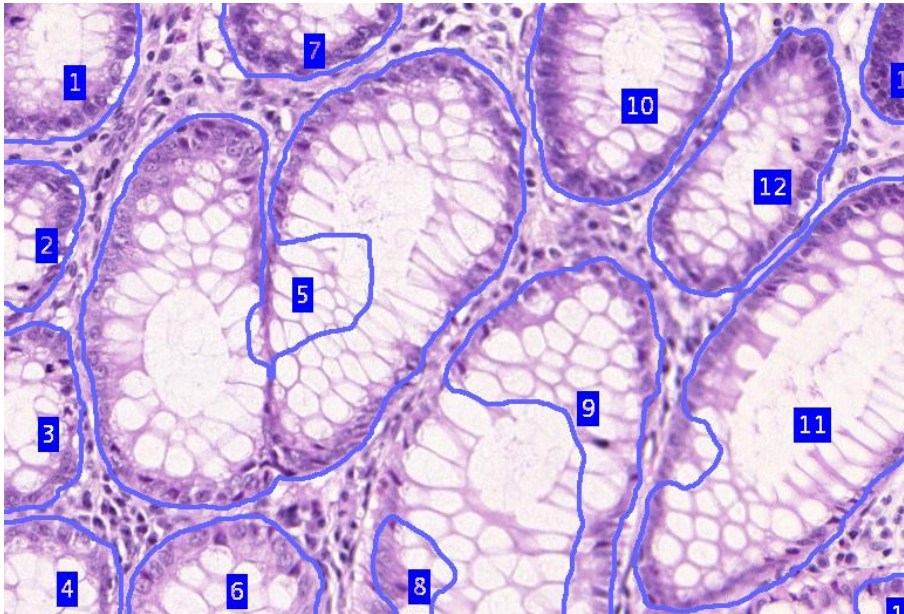
segmentation u



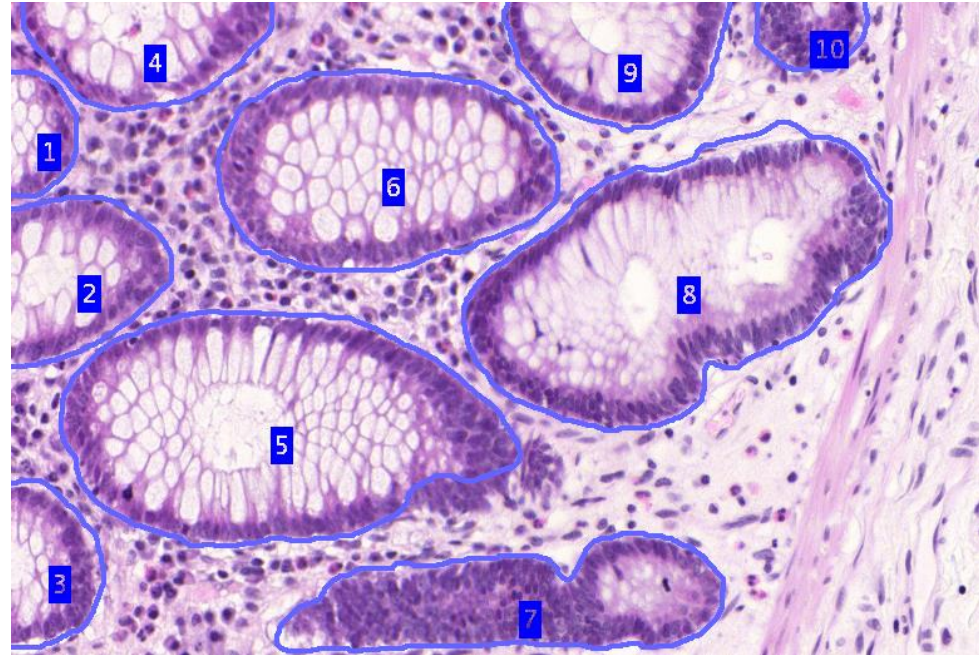
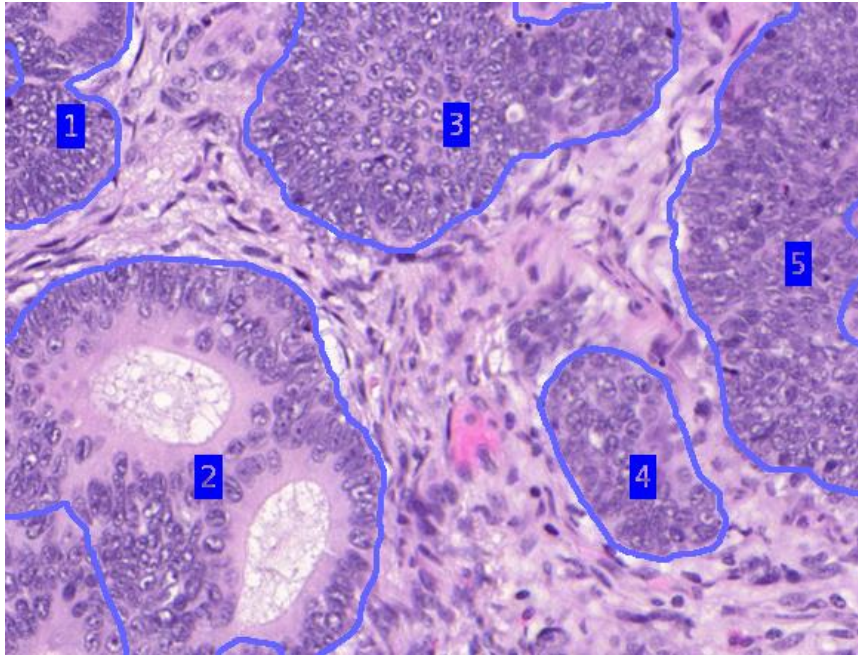
$$g(x) = e^{-\alpha \|\nabla I(x)\|^\beta}, \alpha, \beta > 0$$

Globally optimal solution giving minimal contour length

Segmentation Results: Test Set A (off-site)



Segmentation Results: Test Set A (off-site)

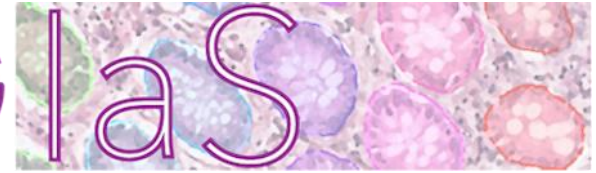




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Thanks for your attention!

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