

Demonstration on VCCS. 10.30 am.

- (1) speeds window on its own
re-defs possible
- (2) state-script concept { privileges to redefine
boundaries for redefn.
- (3) put in context: how operates with rest
of architecture after dynamic model.
- (4) run simulation by changing state so that
autonomous agents take over / enter the scene

stop CLK = 0;
stop CLK = 1; agents representing concepts of the vehicle
(* .e files listed)

(5) actually can change state by redefn.

e.g. accelPos = ...

but also have sensitive buttons to generate defns

(6) in animation still retain privileges to redesign
super-user concept - limited by interpretability

Preface with info on where to find
how to run. (M2 p.2). [model not program]