

Distributed Minimum Vertex Coloring Approximation

Workshop on Data Summarization, University of Warwick

Christian Konrad



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Joint work with Victor Zamaraev (Durham)

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Outline:

- 1 Introduction: LOCAL Model and Vertex Coloring
- 2 Coloring Chordal Graphs
- 3 Discussion: Tree Decomposition and Distributed Computing

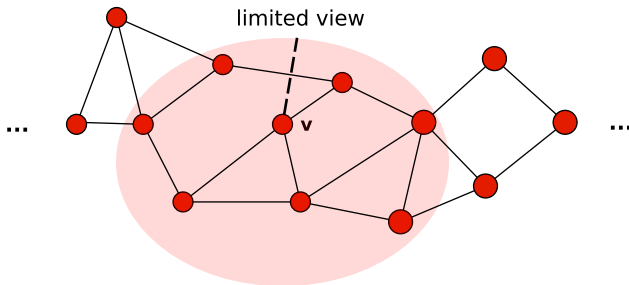
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The LOCAL Model

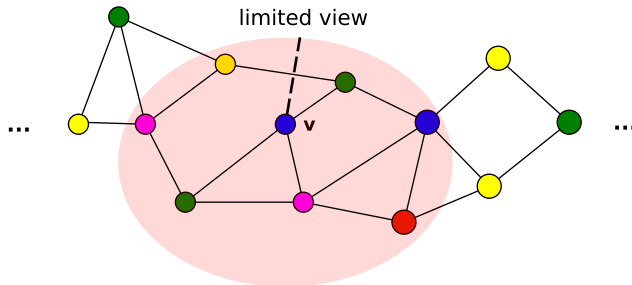
Input: Network $G = (V, E)$, $n = |V|$, max degree Δ



- Nodes host processors and have unique IDs
- Synchronous communication along edges, individual messages of unbounded sizes
- **Running time:** Number of communication rounds
- r rounds \Leftrightarrow compute output from distance- r neighborhood

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Vertex Coloring Problems

$(\Delta + 1)$ -coloring:

- Easy sequentially: GREEDY algorithm
- Ring: $\Theta(\log^* n)$ [Cole, Vishkin, 1986], [Linial, 1992]
- General Graphs: $2^{O(\sqrt{\log \log n})}$ [Chang, Li, Pettie, 2018]

Δ -coloring: (assuming no $\Delta + 1$ clique, $\Delta \geq 3$)

- Not achievable by a GREEDY coloring
- $\Theta(\log^3 n / \log \Delta)$ [Panconesi, Srinivasan, 1993]
- $O(\log \Delta) + 2^{O(\sqrt{\log \log n})}$ [Ghaffari et al., 2018]

Fewer colors:

- Arboricity a : $O(a)$ -coloring in $O(a \log n)$ rounds [Barenb., Elkin, 2010]
- 3-coloring trees, 6-coloring planar graphs, ...

Minimum Vertex Coloring

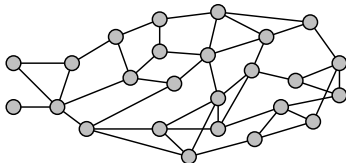
Chromatic number $\chi(G)$: smallest c such that there is a c -coloring

Minimum Vertex Coloring (MVC): find $\chi(G)$ -coloring

- NP-hard [Karp, 1972]
- Hard to approximate within factor $n^{1-\epsilon}$ [Håstad, 1999]

Distributed MVC: Network-decomposition [Linial, Saks, 1993]

- Partition vertices $V = V_1 \dot{\cup} \dots \dot{\cup} V_k$ into clusters, $O(\log^2 n)$ rounds
- Each cluster $G[V_i]$ has diameter $O(\log n)$
- Cluster graph colored with $O(\log n)$ colors:



Minimum Vertex Coloring

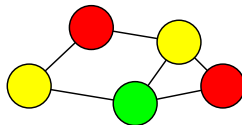
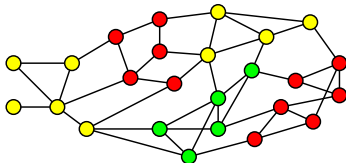
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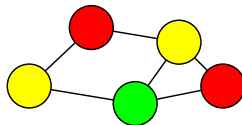
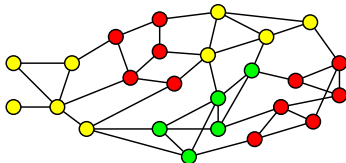
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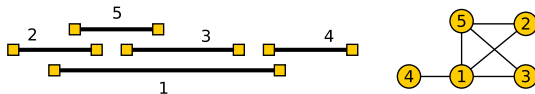
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- $O(\log n)$ -approximation in $O(\log^2 n)$ rounds to MVC
- Poly-time if graph class admits poly-time approximations

Interval Graphs: Intersection graph of intervals on the line



[Halldórsson, Konrad, 2014,2017] :

- $(1 + \epsilon)$ -approximation in $O(\frac{1}{\epsilon} \log^* n)$ rounds (for $\epsilon > \frac{2}{\chi(G)}$)
- Lower Bound: $\Omega(\frac{1}{\epsilon} + \log^* n)$ rounds

Research Questions: Can we...

- Improve approximation factor $O(\log n)$ on general graphs?
- Get $O(1)$ or $(1 + \epsilon)$ -approximations on other graph classes?

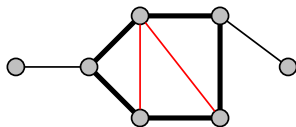
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MVC on Chordal Graphs

Chordal Graphs: Every cycle of at least 4 vertices contains a **chord**:

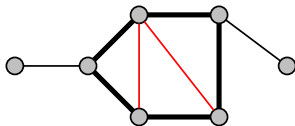


[Konrad, Zamaraev, 2018] : **MVC**

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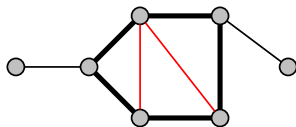
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Chordal Graphs vs. Interval Graphs:

- Chordal graphs contain trees, interval graphs don't
- Linial's tree coloring LB applies: coloring trees with $O(1)$ colors requires $\Omega(\log n)$ rounds [Linial, 1992]

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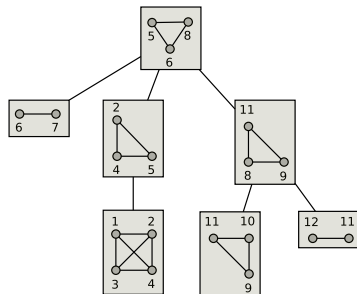
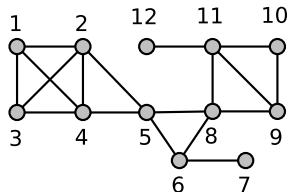
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Technique: Tree Decomposition

Tree Decomposition of Chordal Graphs

Chordal Graph: Clique Tree



- 1 Set of bags = set of maximal cliques
- 2 Bags containing any vertex v induces a subtree

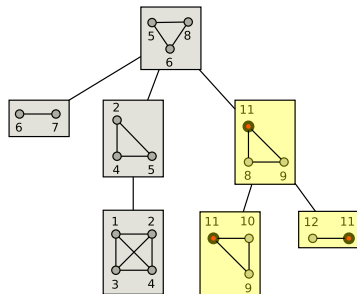
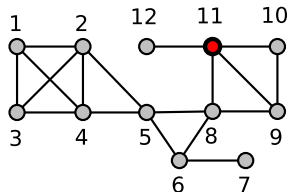
Distributed Processing:

- Nodes compute local view of (global) clique tree
- Locality property: Diameter of each bag is 1

Interval Graph: Clique tree is a path

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Weighted Clique Intersection Graph:

- Let \mathcal{C} be the maximal cliques in chordal graph G
- Let $W_G = (\mathcal{C}, \mathcal{E})$ be the *weighted clique intersection graph* of G , i.e., there is an edge of weight k ($k \geq 1$) between cliques C_i, C_j if $|C_i \cap C_j| = k$

\mathcal{T} is a clique tree $\Leftrightarrow \mathcal{T}$ is a maximum weight spanning tree in W_G

Technicalities:

- Clique tree unique if W_G has unique maximum weight spanning tree
- Local View of v : For each $u \in \Gamma^k(v)$:
 - 1 Compute maximal cliques that u is contained in;
 - 2 Compute maximum weight spanning tree \mathcal{T}_u in clique intersection graph of these cliques;
 - 3 Add \mathcal{T}_u to local view of global spanning tree .

$(1 + \epsilon)$ -approximation Algorithm for MVC:

- 1 **Peeling Phase:** Partition vertex set V into layers $V_1, V_2, \dots, V_{\log n}$ such that $G[V_i]$ is an interval graph in $O(\frac{1}{\epsilon} \log n)$ rounds
- 2 **Coloring Phase:** Color each interval graph $G[V_i]$ independently and separately (compute a $(1 + \epsilon)$ -approximation to MVC) in $O(\frac{1}{\epsilon} \log^* n)$ rounds using [Halldórsson, Konrad, 2017]
- 3 **Color Correction Phase:** Resolve coloring conflicts between the layers in $O(\frac{1}{\epsilon} \log n)$ rounds

Overall Runtime: $O(\frac{1}{\epsilon} \log n)$ rounds

Peeling Phase

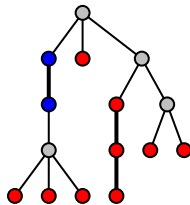
Definition: Let \mathcal{T} be the clique tree of G

- **Pendant Path:** incident to a leaf, degrees at most 2
- **Internal Path:** not incident to a leaf, degrees at most 2

Lemma: Set of vertices whose corresponding subtrees are contained in a pendant or internal path forms an interval graph

Peeling Process: Let $\mathcal{T}_1 = \mathcal{T}$. For $i = 1 \dots \log n$ do:

- Remove all pendant paths, and all “long enough” internal paths from \mathcal{T}_i . (nodes can decide this in $O(\frac{1}{\epsilon})$ rounds)
- Let V_i be all vertices whose corresponding subtree in \mathcal{T}_i is included in a pendant/long enough internal path
- Let \mathcal{T}_{i+1} be clique tree of residual graph (can be obtained by removing pendant/internal paths)



Lemma: Peeling process terminates after $\log n$ rounds.
(each step number of nodes of degree ≥ 3 halves)

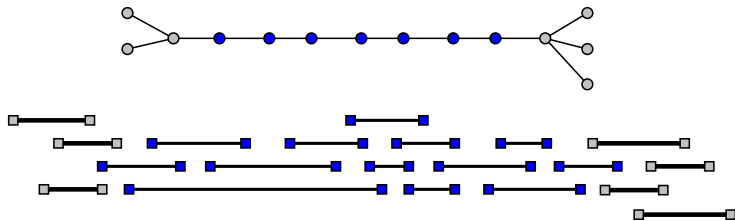
Color Correction Phase

Algorithm:

- 1 Leave colors of layer $V_{\log n}$ unchanged
- 2 Correct colors layer by layer from $V_{\log n-1}$ downwards to layer V_1

Correcting layer i :

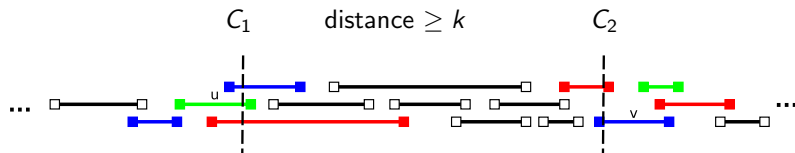
Layer i corresponds to pendant and internal paths in \mathcal{T}_i



Lemma: Only intervals at distance $O(\frac{1}{\epsilon})$ from boundary cliques need to change colors to resolve all coloring conflicts

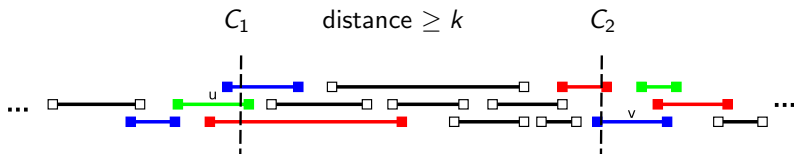
Coloring Interval Graphs with Precolored Boundary Cliques

Goal: Prove that color completion with few colors exists



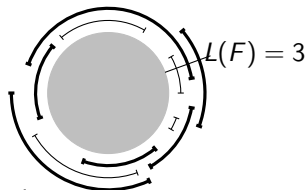
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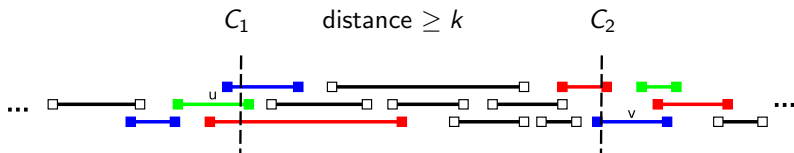
Circular Arc Graphs:

- Load $L(G)$: Largest subset containing the same point
- Circular cover length $I(G)$: cardinality of smallest subset of arcs covering the circle



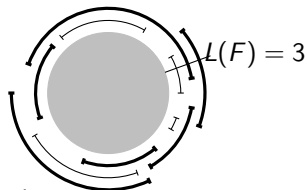
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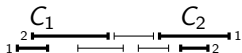
[Valencia-Pabon, 2003] :

$\lfloor \left(1 + \frac{1}{I(G)-2}\right) L(G) \rfloor + 1$ colors suffice to color circular arc graph G

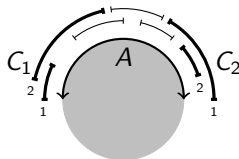
Approximation Factor (2)

Pre-colored Interval Graph G to Circular Arc Graph F :

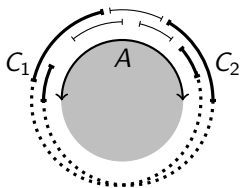
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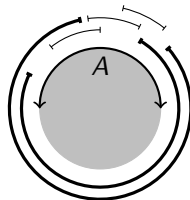
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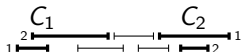
- 1 Load: $L(F) \leq \chi(G)$
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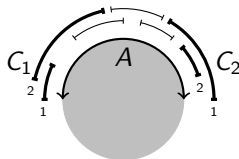
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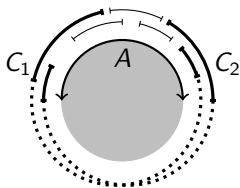
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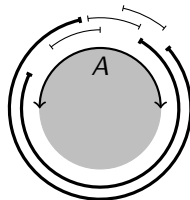
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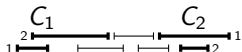
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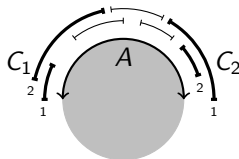
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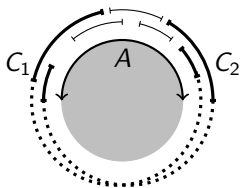
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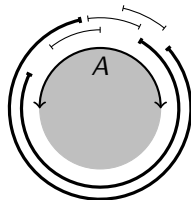
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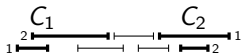
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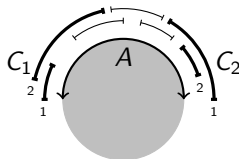
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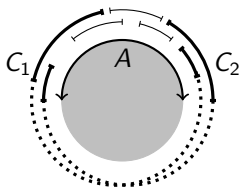
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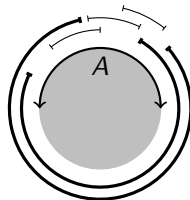
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Three phases:

- 1 Peeling Phase: $\log n$ iterations, each requiring $O(\frac{1}{\epsilon})$ rounds
- 2 Coloring Phase: $O(\frac{1}{\epsilon} \log^* n)$
- 3 Color Correction Phase: $\log n$ iterations, each requiring $O(\frac{1}{\epsilon})$ rounds

Adapt Technique to Maximum Independent Set: (MaxIS)

- $(1 + \epsilon)$ -approximation to MaxIS on chordal graphs in $O(\frac{1}{\epsilon} \log(\frac{1}{\epsilon}) \log^* n)$ rounds
- On the way: $(1 + \epsilon)$ -approximation to MaxIS on interval graphs in $O(\frac{1}{\epsilon} \log^* n)$ rounds
- Lower Bound: $\Omega(\frac{1}{\epsilon})$

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How useful are Tree Decompositions for Distributed Algorithms?

- Only few papers make use of tree decompositions
- Perfect tool for chordal graphs
- Can we handle other graph classes as well using tree decompositions?

Obstacle:

- Tree decomposition of cycle of length k contains bags that are at distance $\Omega(k)$ in the original graph
- Impossible for nodes to obtain coherent local views of global tree decomposition in $o(k)$ rounds

Tree Length

- Graph of tree length k has tree decomposition where diameter of every bag is at most k
- Contains k -chordal graphs

Thank you very much.