

Historical motivation for studying ^{in the 19th century} Riemann surfaces was the evaluation of integrals. There was a well developed theory of the integral $\int \frac{dx}{\sqrt{1-x^2}}$ but the integral $\int \frac{dx}{\sqrt{1-x^3}}$ was a mystery. ①

We will describe the theory of these "elliptic integrals". Involves the study of "elliptic curves" like $w^2 = 1 - z^3$ and $w = (z^2 - 1)(z^2 - k)$.

\mathbb{C} varieties in \mathbb{C}^2

In the 19th-20th centuries there was a shift in mathematical style away from concrete description of ~~some~~ polynomial equations to abstract definitions like Riemann surfaces. The question then ~~becomes~~ ~~given~~ arises given an abstract object when can you embed it as a variety? The route to answering this question is through studying the collection of ~~meromorphic~~ ^{meromorphic} functions on our abstract object. ~~Given, p~~

What can you say about their zeros, poles? (2)

Phew We use these functions to embed
our abstract Riemann surface in \mathbb{C}^n or $\mathbb{C}P^n$.
meromorphic P. functions

In the 20th-21st centuries Riemann surfaces
have been applied to new areas of study,
hyp. 3-manifolds, polygonal billiards
One of the outcomes is new geometric language
for ~~less~~ describing ~~what~~ them. I will
try to convey ~~some~~ ~~limits~~ of ~~to~~ some of
this as well. Language of "geometric structures".

Connections between translation structures
and holomorphic differentials, half-translation
structures and quadratic differentials.

Overview?
 complex analysis. Repackaging ~~the~~ ³
 of an old notion.

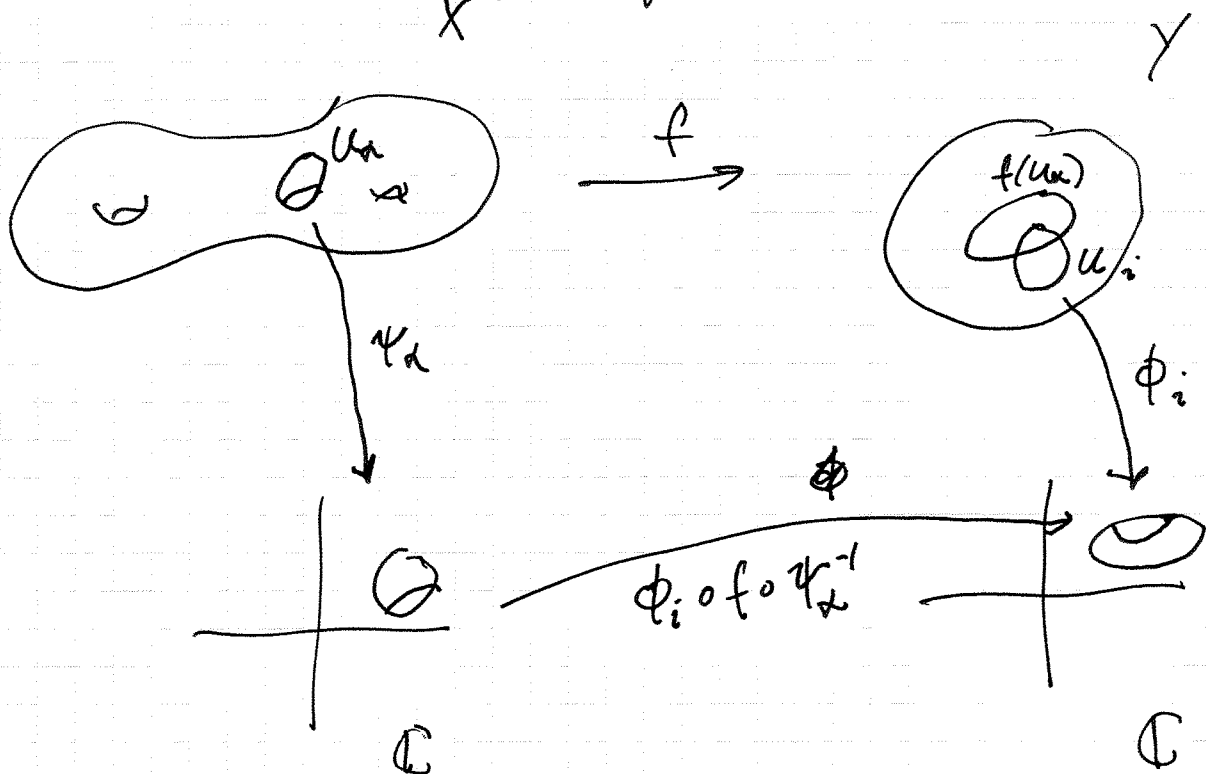
(16)

(17)

Defn. Returning to Riemann surfaces.

Definition. Let X be a Riemann surface with an atlas $(U_\alpha, \bar{U}_\alpha, \psi_\alpha)$ and Y another Riemann surface with an atlas $(V_\beta, \bar{V}_\beta, \phi_\beta)$. A map $f: X \rightarrow Y$ is said to be holomorphic if for each α and i the composition

$\phi_i \circ f \circ \psi_\alpha^{-1}$ is holomorphic on its domain of definition.



(2) (4) (5) (6)

Note that $\phi_i \circ f \circ \psi_i^{-1}$ is mapping an open set in \mathbb{C} into another open set in \mathbb{C} so that the notion of "holomorphic" is the usual notion.

Using the same formalism we can talk about smooth maps between smooth surfaces etc.

Definition. We say that two Riemann surfaces X and Y are equivalent if there is a holomorphic bijection $f: X \rightarrow Y$ with holomorphic inverse.

Definition. Two atlases $\mathcal{A} = (U_\alpha, \tilde{U}_\alpha, \psi_\alpha)$ and $\mathcal{A}' = (V_i, \tilde{V}_i, \phi_i)$ on the same space X are equivalent if the identity map is $\text{id}: X \xrightarrow{\mathcal{A}} X \xleftarrow{\mathcal{A}'}$ is an equivalence.

Recall that a function $f: U \rightarrow \mathbb{C} \cup \{\infty\}$ is meromorphic if it is holomorphic where it is finite valued and at each $z_0 \in U$ where $f(z_0) = \infty$ the function can be written as a convergent power series

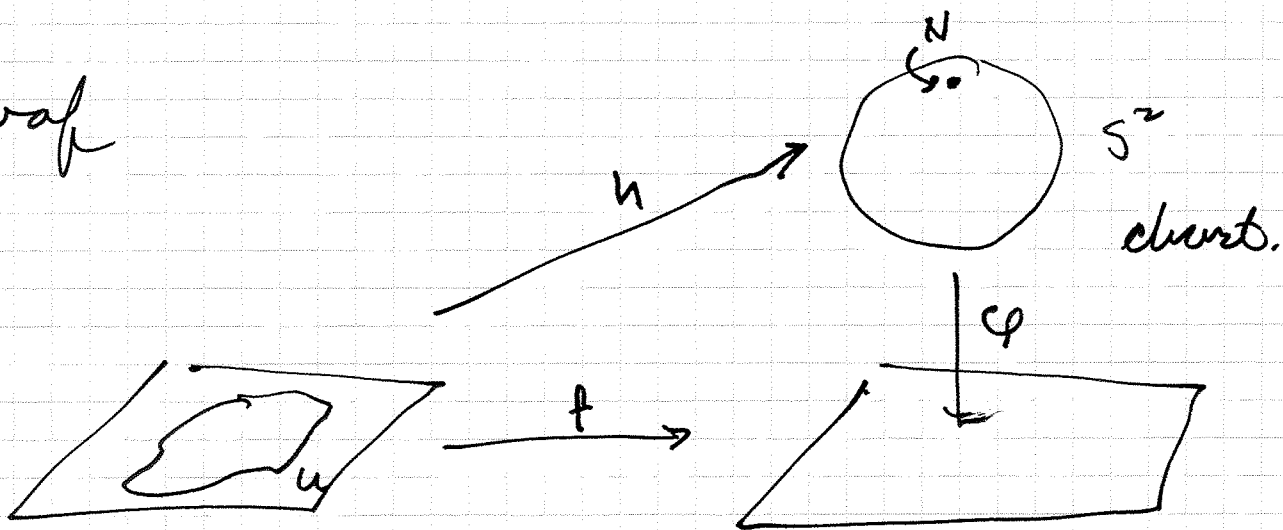
$$f(z) = \sum_{n=-k}^{\infty} a_n (z-z_0)^n \quad (\text{any } a_k \neq 0).$$

Equivalently $f(z) = \frac{g(z)}{(z-z_0)^n}$ where g is holomorphic and $g(z_0) \neq 0$.

⑥

Proposition. A holomorphic map $h: U \subset \mathbb{C} \rightarrow S^2$ which is not the constant ∞ corresponds to a meromorphic function and conversely.

Proof



Say we are given a meromorphic function f then we define h so that $h(z) = \varphi^{-1}(f(z))$ where $f(z)$ is finite and $h(z) = N$ where $f(z) = \infty$.

Want to check that h is holomorphic at these points z_0 where $h(z_0) = N$.

Use the other chart $\psi: S^2 - \{N\} \rightarrow \mathbb{C}$.

$$\begin{aligned}
 \text{For } z \text{ near } z_0 \quad \psi \circ h(z) &= \psi \circ \varphi^{-1}(f(z)) \\
 &= \frac{1}{f(z)}
 \end{aligned}$$

$$\psi \circ h(z_0) = \psi(N) = 0.$$

Now ~~$f(z)$~~ $f(z) = \frac{g(z)}{(z-z_0)^n}$ so

②

$$\text{Res}(z) = \frac{1}{f(z)} = \frac{(z-z_0)^n}{g(z)}$$

is holomorphic.

Converse is similar.

(8) (2/11) (1/10)

Example: Given two translation surfaces we can ask whether they are equivalent as Riemann surfaces or whether they are equivalent as translation surfaces.

For open sets in \mathbb{C} new style holomorphic is old style holomorphic (one chart.)

Example: The unit disk is equivalent to the upper half-plane by way of the

$$\begin{array}{ccc} \text{maps} & \mathbb{H} & \xrightarrow{\quad} & \frac{w-i}{w+i} \\ & \uparrow & & \uparrow \\ & \mathbb{C} & & \mathbb{D} \end{array}$$

Example: The unit disk \mathbb{D} is not equivalent to the complex plane.

Proof. If they were equivalent we could find a ~~low~~ holomorphic map $f: \mathbb{C} \rightarrow \mathbb{D}$ which was surjective and invertible.

By Liouville's theorem a bounded holomorphic function is constant so f would have to be constant. In particular, it is neither injective nor surjective.

This is a very flexible and powerful idea. If we take the word "holomorphic" in our discussion and replace it with another class of maps between open sets in \mathbb{C} we get another type of mathematical object. $\&$

We can consider, for example, the class of smooth (C^∞) functions.

In this case ~~was~~ if we replace the word "holomorphic" by the word "smooth" we have defined a " C^∞ atlas" or "smooth atlas" on a surface and hence the notion of a smooth surface.

If we replace \mathbb{C} by \mathbb{R}^n we get the notion of a "smooth n -dimensional manifold".

If we ~~replace~~ replace \mathbb{C} by \mathbb{C}^n and holomorphic map functions by the notion of holomorphic maps used in several complex variables we get the notion of a "complex n -manifold".

From this ~~over~~ point of view we see that a Riemann surface is a complex 1-manifold. Call S^2 , P^1 or P because it corresponds to complex lines in \mathbb{C}^2 . Define P^n as space of lines in \mathbb{C}^{n+1} . Example. A Riemann surface has a

~~translata~~ A "translation structure" on a Riemann surface is given by an atlas where all change of coordinate maps have the form $\psi_\alpha \circ \psi_\beta^{-1}(z) = z + c$.

A "half translation structure" is given by an atlas where all change of coordinate maps have the form $\psi_\alpha \circ \psi_\beta^{-1}(z) = \pm z + c$.

Note that in the case of translation structures the fact that $f' = g$ does make sense independently of the coordinate chart.

Remarks: The terminology "translation structure" and "half-translation structure" was invented relatively recently but it corresponds to classic notions in

Atlases and geometric structures.

Example

We can use an atlas to give our Riemann surface additional ~~structures~~ geometric structure (or to recognizing additional structure that our surface already has).

This is a viewpoint which was popularized by Thurston (~~The geometry and topology of three manifolds~~) but it is of historical and contemporary importance in Riemann surface theory.

We will see a

gives a nice perspective on ~~clarifies some~~ classical work.

Connection with elliptic integrals for example.

(Gauss, Riemann, Weierstrass)

Here is the idea.

get the structure

Without loss of generality, we can assume that our system of charts lie in some Riemann surface $M = \mathbb{C}, \mathbb{H}, \mathbb{D}$.

Choose a group G that acts on M by ~~invertible~~ conformal automorphisms.

eg. ① $G =$ group of translations acting on \mathbb{C} , $a = \pm 1$ translation structure

② $G = \{z \mapsto az + b : \text{acting on } \mathbb{C}\}$

③ $G = \{ \text{linear fractional transformations acting on } \mathbb{H} \}$

half translation structure

(14) $G = \{ \text{linear fractional transformations acting on } \mathbb{D} \}$

We say

Let R be a Riemann surface with an atlas \mathcal{A} . We say that \mathcal{A} gives R a

G -structure if all of the changes of coordinate functions $\phi_\beta \circ \phi_\alpha^{-1}$ are restrictions of have the form $\phi_\beta \circ \phi_\alpha^{-1}(z) = g(z)$, where defined for $g \in G$.

The names associated to the examples are:

① Translation structure

② ~~half translation structure~~

③ ~~complex projective structures~~

similarity structures,

④ ~~hyperbolic structures.~~

I will give some examples of known Riemann surfaces having some of these structures.

Torus, cylinder

some G structures have compatible metrics.

Connection with the between translation structures and integration.

half-translation structures
pillowcase, half cylinder.

$$\int \sqrt{g(z)} dz.$$