

Draw

The next topic is a second example of a hyperbolic diffeomorphism ^{of a surface} exhibiting chaotic behavior. This example has a different flavor from the horseshoe, suggesting that the notion of hyperbolicity has a range of applications.

Hyperbolic automorphisms of the torus.

①

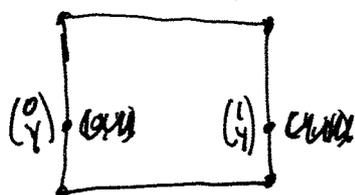
Let \mathbb{T}^2 be the ^{coset} quotient space $\mathbb{R}^2/\mathbb{Z}^2$.

An element of \mathbb{T}^2 is an equivalence class

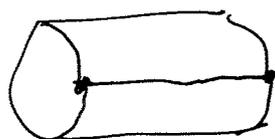
$\{ (x+n, y+m) : n, m \in \mathbb{Z} \}$ Write $\pi\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \left(\frac{x}{y}\right)$.

Any such equivalence class has a representative in the square $[0,1] \times [0,1]$.

Certain points have more than one representative.



$$\begin{aligned} (0,0) &\sim (1,0) & (0,1) &\sim (1,1) \\ (x,0) &\sim (x,1) & (y,1) &\sim (y,0) \\ (0,0) &\sim (0,1) \sim (1,0) \sim (1,1) & & \\ (y,1) &\sim (0,1) \sim (0,0) \sim (1,0) & & \end{aligned}$$



Note that $\mathbb{T}^2 = \mathbb{R}^2/\mathbb{Z}^2 = (\mathbb{R}/\mathbb{Z}) \times (\mathbb{R}/\mathbb{Z})$. For $\pi\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} x \pmod{\mathbb{Z}} \\ y \pmod{\mathbb{Z}} \end{pmatrix}$

Prop. A 2×2 matrix A with integral entries induces a linear or affine map from \mathbb{T}^2 to \mathbb{T}^2 .

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Def. We say that a matrix A is hyperbolic if it has no eigenvalue on the unit circle.

If $A: V \rightarrow V$ is hyperbolic then there are invariant subspaces V^u and V^s of V so that $V^u \cap V^s = \{0\}$, $V^u + V^s = V$

and

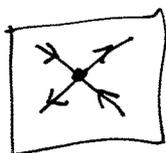
$$\lim_{k \rightarrow \infty} |A^k(v)| \rightarrow 0 \quad \lim_{k \rightarrow -\infty} |A^k(v)| \rightarrow \infty \quad \text{for } v \in V^s$$

$$\lim_{k \rightarrow \infty} |A^k(v)| \rightarrow \infty \quad \lim_{k \rightarrow -\infty} |A^k(v)| \rightarrow 0 \quad \text{for } v \in V^u$$

In the particular case that A is 2×2 with $\det = \pm 1$ and A is hyperbolic A has eigenvalues

λ^u, λ^s with $|\lambda^u| > 1$, $|\lambda^s| < 1$. V^u is the eigenspace for λ^u , V^s is the eigenspace for λ^s . In general V^s and V^u are sums of generalized eigenspaces.

The image of V^u and V^s are the unstable and stable manifolds of 0 .



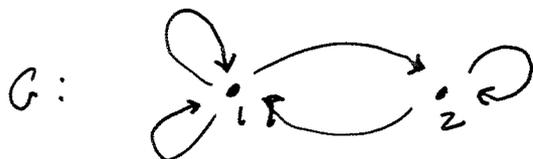
Example: $A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$.

$\text{Tr} = 3$ $\det = 1$
 $\lambda^2 - \text{Tr} \cdot \lambda + \det = 0$
 $\lambda = \frac{3 \pm \sqrt{5}}{2}$

$\lambda^u = \frac{3 + \sqrt{5}}{2}$ $\lambda^s = \frac{3 - \sqrt{5}}{2}$ $|\lambda^u| > 1 > |\lambda^s|$.

2nd example of "hyperbolic behavior".
 If p, q suff. close then $W_{loc}^s(p) \cap W_{loc}^u(q) = \text{pt.}$ (4)

Thm. Let $A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$ then $f_A: \mathbb{T}^2 \rightarrow \mathbb{T}^2$ is Topologically equivalent semi-conjugate to $G: G \rightarrow G$ the topological Markov chain $\sigma: G \rightarrow G$ where

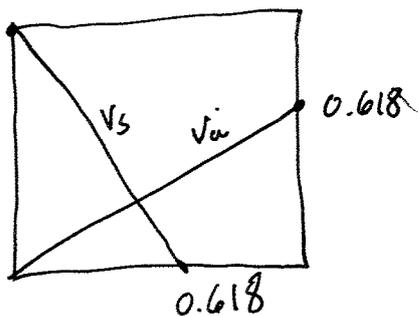


Proof. 0 is a fixed point for f_A .

We will use the local stable and unstable manifolds of 0 to divide \mathbb{T}^2 into two rectangles.

$V_u = \begin{pmatrix} \frac{1 + \sqrt{5}}{2} \\ 1 \end{pmatrix}$. Rescale to $\begin{pmatrix} \phi \\ 0.618.. \end{pmatrix}$.

$V_s = \begin{pmatrix} \frac{1 - \sqrt{5}}{2} \\ 1 \end{pmatrix}$. Rescale to $\begin{pmatrix} -0.618.. \\ 1 \end{pmatrix}$.



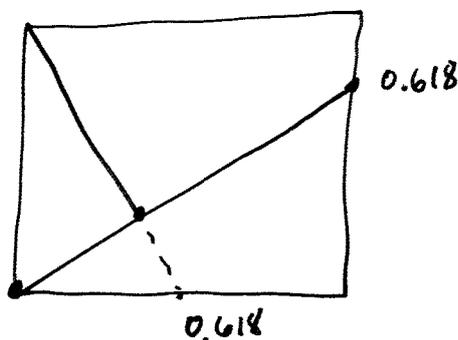
Recipe for Markov partition.

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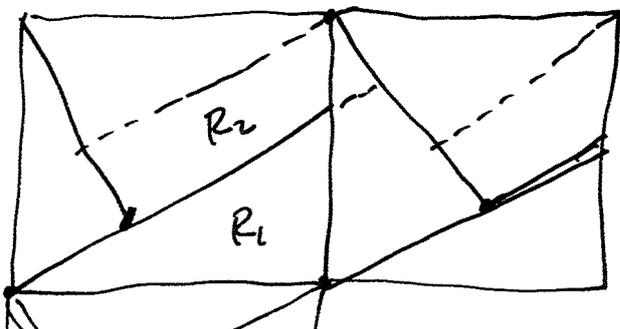
Expanding eigenvector: $\begin{pmatrix} \frac{1+\sqrt{5}}{2} \\ 1 \end{pmatrix}$ Rescale $\begin{pmatrix} 1 \\ 0.618034 \end{pmatrix}$

Contracting eigenvector: $\begin{pmatrix} \frac{1-\sqrt{5}}{2} \\ 1 \end{pmatrix}$ $\begin{pmatrix} -0.6180 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 0.618 \\ -1 \end{pmatrix}$

Slope of the expanding eigenvector is positive but less than 1. Take the branch in the first quadrant and extend it across the square.



The contracting eigenvalue has negative slope. Extend it until it hits the expanding segment.



Now extend the unstable segment in both directions until it hits the stable segment. Call the resulting rectangles R_1 and R_2 . The union of R_1 and R_2 is all of \mathbb{T}^2 . The images of the boundaries are not disjoint.

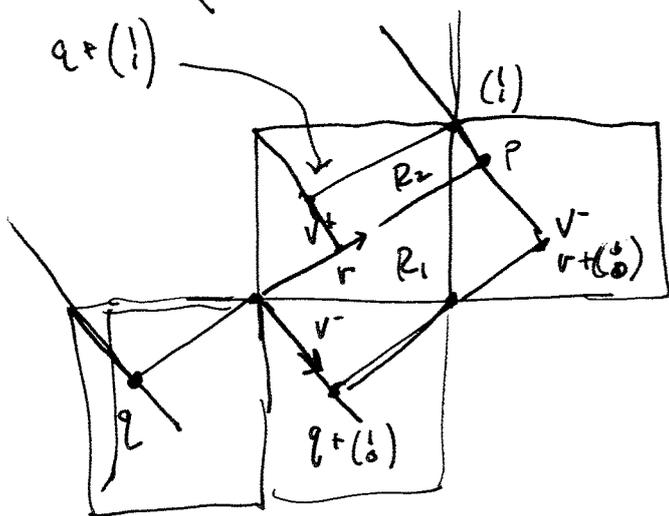
Let $v^+ = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

The eigenvectors of A are

Let $\begin{pmatrix} \frac{1+\sqrt{5}}{2} \\ 1 \end{pmatrix}$ and $\begin{pmatrix} \frac{1-\sqrt{5}}{2} \\ 1 \end{pmatrix}$

$$\frac{1+\sqrt{5}}{2} \cdot \frac{1-\sqrt{5}}{2} = \frac{1-5}{4} = -1$$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 1.618\dots \\ 1 \end{pmatrix}$ $\begin{pmatrix} -0.618\dots \\ 1 \end{pmatrix}$

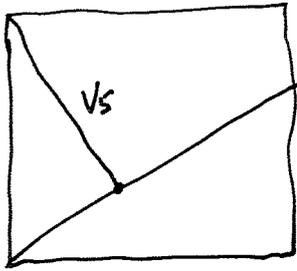


Eigenvectors give local stable and unstable manifolds of δ .

~~Note that the boundaries $R_1 \cup R_2$ is the whole torus.~~

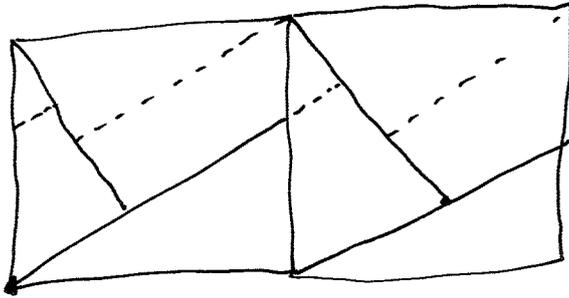
Now ~~Note that~~

Let J^+R_1, J^+R_2 be the pieces of the boundaries which intersect the unstable manifolds. Let J^-R_1, J^-R_2 be the intersections of boundaries with stable manifolds. Then $f(J^-R_1 \cup J^-R_2) \subset J^-R_1 \cup J^-R_2$ and $f(J^+R_1 \cup J^+R_2) \subset J^+R_1 \cup J^+R_2$. This is the Moeckel condition in the invertible case.

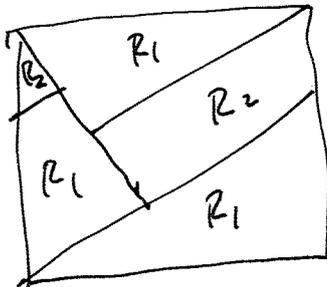


Cut off V_s at the intersection point. ⑤

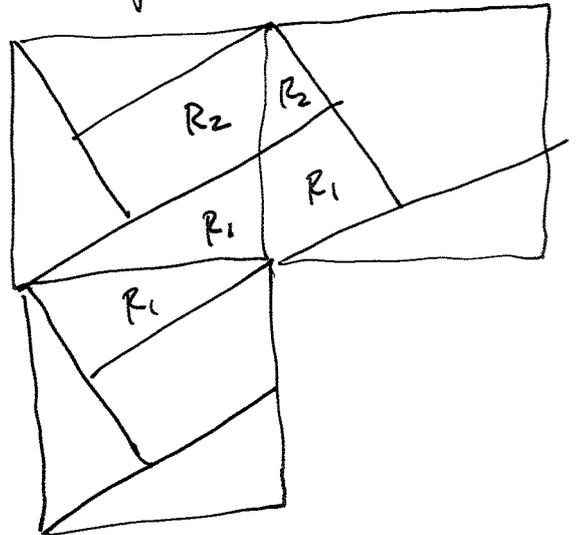
Now extend V_u in both directions until it hits V_s again.



This divides \mathbb{T}^2 into two rectangles R_1 and R_2 .



or



This picture shows that R_1 and R_2 fill \mathbb{T}^2 .

This picture shows that R_1 and R_2 are rectangles.

Keep track of the image as follows:

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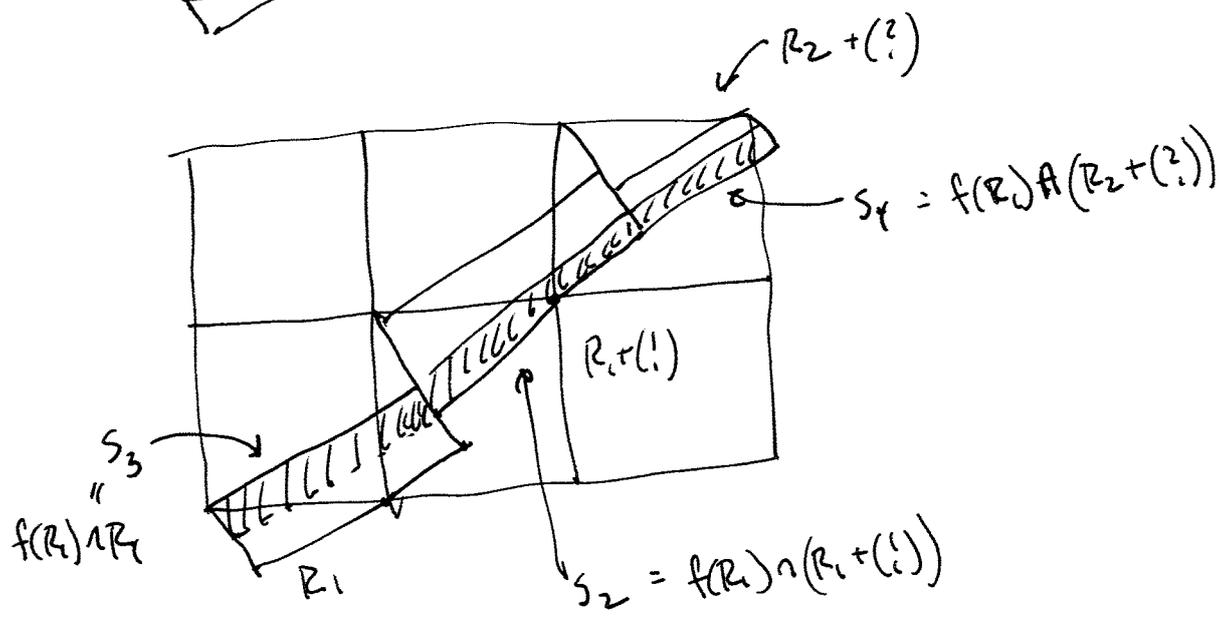
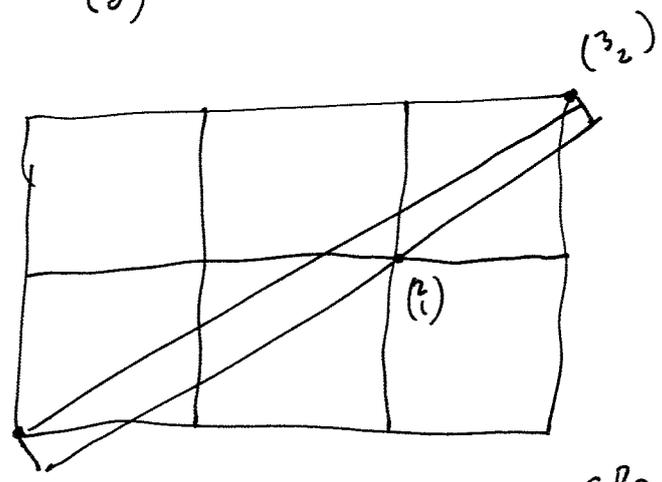
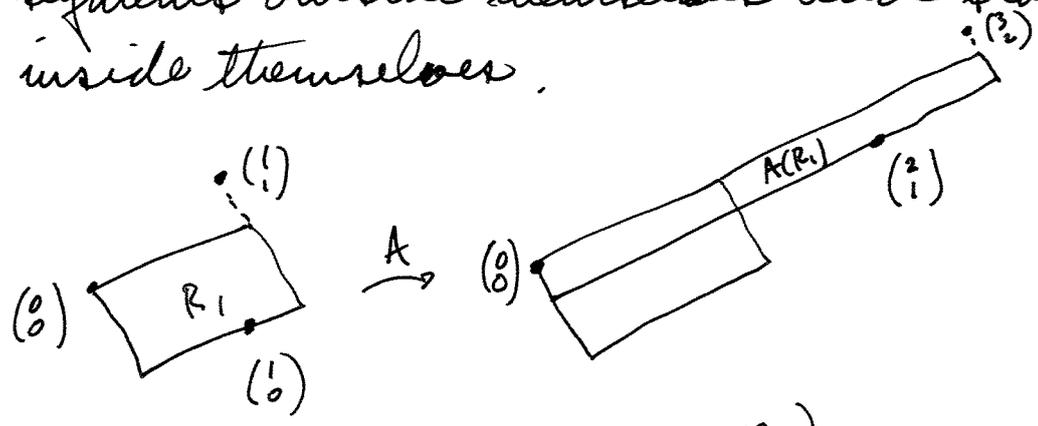
Stable boundaries

Keep track of the image of R_1 . The top boundary is part of the unstable manifold of (\emptyset) . This gets mapped to a longer part of the unstable manifold of $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}(\emptyset) = (\emptyset)$. The r.h. stable boundary is part of the stable manifold of (i) . This gets mapped to part of the stable manifold of $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}(i) = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$.

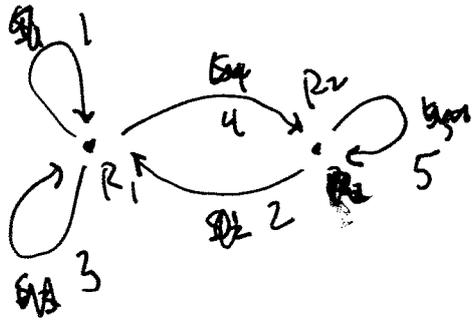
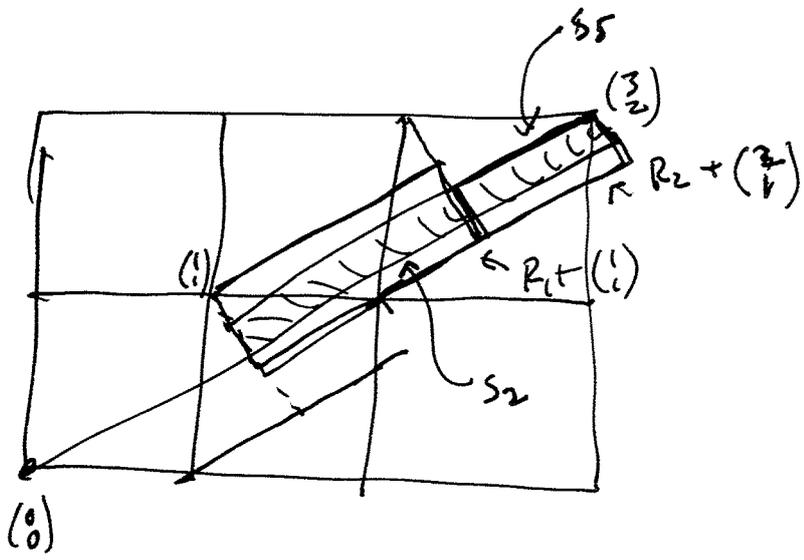
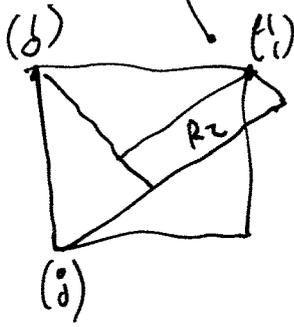
The bottom unstable boundary of R_1 goes through (\emptyset) . This gets mapped to an unstable segment through $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}(\emptyset) = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

Left hand stable segment gets mapped into itself.

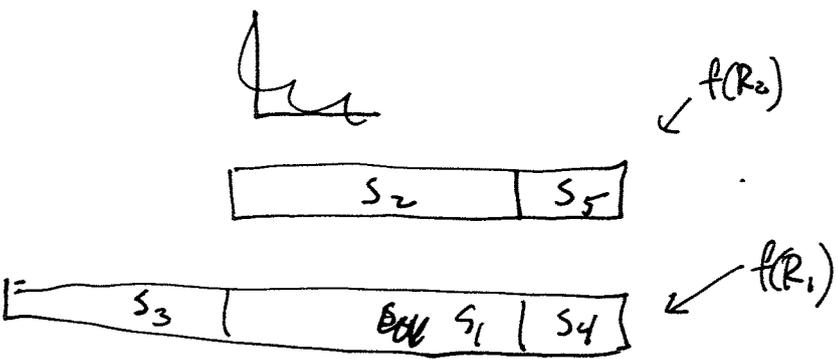
We will now calculate the images of R_1 and R_2 in \mathbb{R}^2 . We use 3 facts. A fixed (0) and takes integral points to integral points. A takes unstable segments outside themselves and stable segments inside themselves.



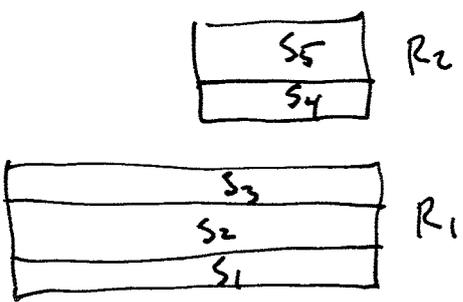
of



Write the images of R_1 and R_2 horizontally:



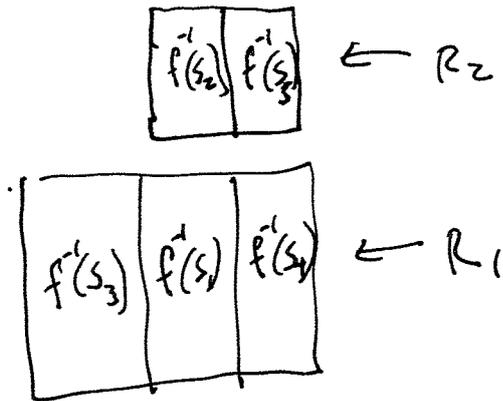
Arrange these rectangles inside R_1 and R_2



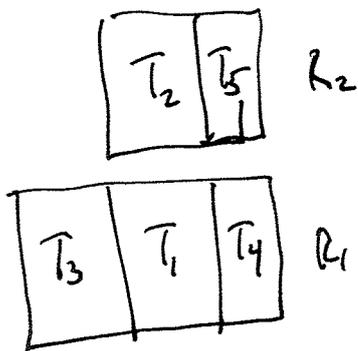
The S_j give a partition of R_i 's based on the location of $f^{-1}(p)$.
Corresponds to arrows landing at R_1, R_2 .

Apply f^{-1} to previous picture

(8)



Let T_i denote $f^{-1}(s_j)$ so $s_j = f(T_i)$.



The T_i 's give a partition of the R_i 's based on the location of $f(p)$.

Partition of R_j corresponds to arrows leaving R_j .

Note that the s_j 's have full width in the R_i 's and the T_i 's have full height.

Coding of orbits:

Coding of orbits by paths in G :

For any $p \in \mathbb{T}^2$. We set

$$\dots \xrightarrow{\alpha_{-2}} w_{-2} \xrightarrow{\alpha_{-1}} w_{-1} \xrightarrow{\alpha_0} w_0 \xrightarrow{\alpha_1} w_1 \xrightarrow{\alpha_2} w_2 \dots$$

Recall our conventions. A path in G is given by as above where the w 's correspond to vertices and α 's correspond to edges.

Let $p \in \mathbb{T}^2$. Let $\{p^j\}$. Define $w_j = w_j(p)$ and $\alpha_j = \alpha_j(p)$ as follows.

$$w_j(p) = \begin{cases} 1 & \text{if } f^j(p) \in R_1 \\ 2 & \text{if } f^j(p) \in R_2. \end{cases}$$

$$\alpha_j(p) = \begin{cases} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{cases} \text{ if } f^j(p) \in \begin{cases} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{cases} \text{ or } f^{j-1}(p) \in \begin{cases} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \end{cases} \text{ equiv.}$$

$\alpha_j(p)$ determines $w_{j-1}(p), w_j(p)$

Applying f to p shifts the sequence to the left.

Now say that we have a finite word

$$w = \overset{\alpha_{j+1}}{\omega_j} \dots \omega_{-1} \omega_0 \dots \overset{\alpha_k}{\omega_k} \omega_{k+1} \quad j \leq 0 \quad k \geq 0,$$

w determines a cylinder set $C(w)$ in G_∞ of infinite words which agree with w where w is defined.

w determines a set $B(w)$ in \mathbb{T}^2 of points whose codings agree with the entries of w where they are defined.

Example:

$w = .1$	$B(w) = R_1$
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$w = .2$	$B(w) = R_2$
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$w = \overset{1}{1}.1$	$B(w) = S_1$
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$w = \overset{2}{2}.1$	$B(w) = S_2$
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$w = .\overset{1}{1}$	$B(w) = T_1$
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$w = .\overset{2}{2}$	$B(w) = T_2$
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The strategy for the construction of the semi-conjugacy h is the same as that for the horseshoe. We will show that as $i \rightarrow \infty, j \rightarrow -\infty$ the set $B(\omega) \cap B(\bar{\omega})$ is a rectangle and as $i \rightarrow \infty, j \rightarrow -\infty$ the height and width of $B(\bar{\omega})$ goes to 0. We then define $h(\bar{\omega})$ as an intersection of a nested sequence of rectangles.

Let $\bar{w} = \tilde{w}_j \dots \tilde{w}_{-1} \cdot \tilde{w}_0 \dots \tilde{w}_k$ $j \leq 0, k \geq 0$

be a word. Note that the w_0 location is always included. $|j|$ is the number of specified positions to the left of 0, k is the number of specified positions to the right of 0.

Let h_j be the width of B_j and w_j be the height of B_j .

Claim. $B(\bar{w})$ is a rectangle with height

$$\frac{h w_j}{\lambda^{|j|}} \text{ and width } \frac{w w_k}{\lambda^k}.$$

Note that the height and width depends only on the w 's not the d 's.

Note that the claim implies that if $j=0$ then $B(\bar{w})$ has full height and if $k=0$ then $B(\bar{w})$ has full width.

$$S_2 = B(\overset{\sim}{2} \cdot \overset{\sim}{1}) \quad k=0 \quad j=-1 \quad S_2 \text{ has full width}$$

$$T_2 = B(\overset{\sim}{.} \overset{\sim}{2} \overset{\sim}{1}) \quad j=0 \quad k=1 \quad T_2 \text{ has full height}$$

To find the width of T_2 we can apply
 f . f multiplies widths by λ^u . $f(T_2) = S_2$
 has width w_1 . So T_2 has width $\frac{w_1}{\lambda}$ as
 was predicted by the claim.

Proof of the claim by induction on the length of the word. If the word has length 1 then the claim is true.

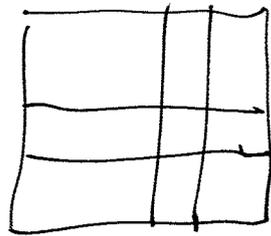
If the word has length 2 say $\cdot z \cdot$ then it has full height. If we shift left then we get $\cdot z \cdot$ corresponds to shrinking vertically by λ so the height is $\frac{h_2}{\lambda}$ as predicted.

$$\frac{h_2}{\lambda^{|\lambda|}} = \frac{h_2}{\lambda}$$

If the assertion is true for words of length $n-1$ and we have a word $w_j \dots w_{-1} \cdot w_0 \dots w_k$ with $j \leq -1$ and $k \geq 1$ then we consider the words

$w_{-j} \dots w_{-1} \cdot w_0$ and $\cdot w_0 \dots w_k$. These words

are shorter. One corresponds to a rectangle of full width, the other to a rectangle of full height.



The intersection is again a rectangle.

Its height and width is its height corresponds to the word $w_{-j} \dots w_0$. Its width is the width of $\cdot w_0 \dots w_k$.

If we have a word with say $k=0$

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$w_j \dots w_{i-1} \overset{\alpha-1}{w_i} w_0$ then it is contained in a

rectangle $S_{\alpha-1}$. If we apply f^{-1} we shift the word right, and we $f^{-1}S$ multiplies widths by λ and contracts heights by λ . Furthermore we can analyze this set by means of the previous argument.