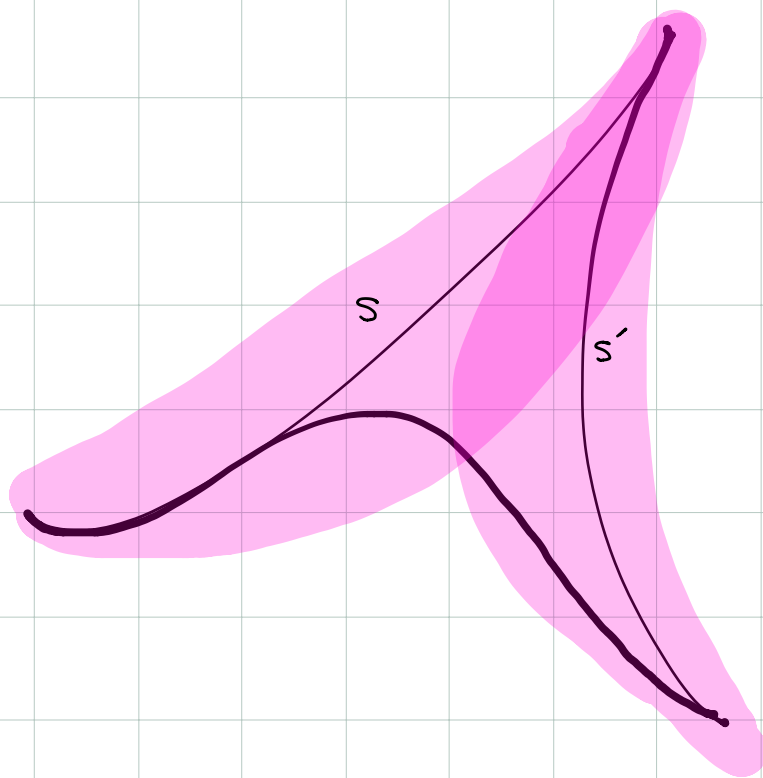


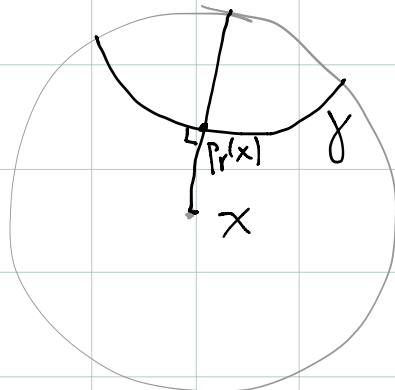
Thurs Jun 23

Last thing we did Tuesday was to show geodesic triangles in \mathbb{H}^2 are $\log 3$ -thin

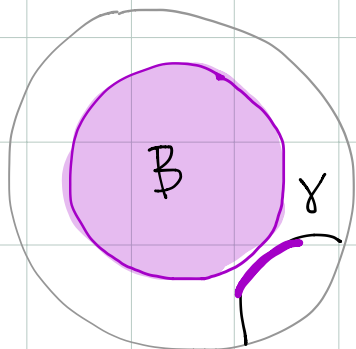
Another way to say C -thin: Let s and s' be any two sides of Δ . Then $\Delta \subset N_c(s \cup s')$:



Recall we defined Projection onto a geodesic:
 $x \in \mathbb{H}^2$ and $\gamma \subset \mathbb{H}^2$ a geodesic $\mapsto P_\gamma(x)$

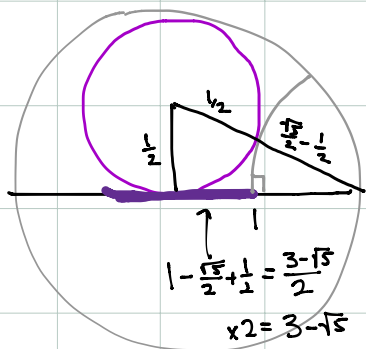
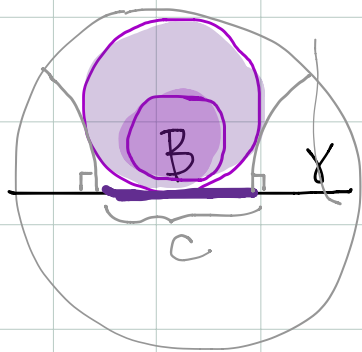


Claim. $B \subset \mathbb{H}^2$ a ball disjoint from γ . Then
there is a constant C st. $P_\gamma(B)$ has diameter $< C$.



Terminology: γ is contracting.

Proof: Move γ to the x-axis by an isometry of \mathbb{H}^2
 Then move the center of B to the y-axis by an isometry
 preserving γ . B is contained in the ball tangent to S^1 ,
 so its projection is bounded by the projection of that arc:



$$\begin{aligned}
 & (\approx .76) \\
 & r = 3 - \sqrt{5} \Rightarrow \\
 & C = \ln\left(\frac{1+r}{1-r}\right) = \ln\left(\frac{4-\sqrt{5}}{\sqrt{5}-2}\right) \\
 & \approx 2.01 \\
 & \text{(that's hyperbolic distance)}
 \end{aligned}$$

One more observation about the geometry of \mathbb{H}^2 :

geodesics starting at x diverge very fast:

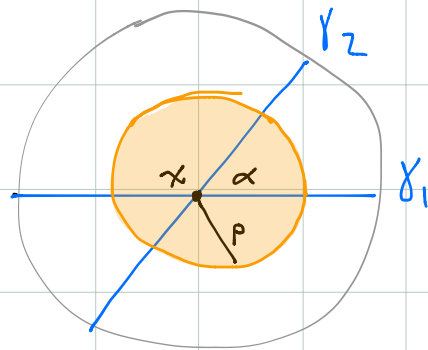
Put x at origin with

an isometry.

Measure divergence by

shortest path from γ_1 to γ_2

outside the ball B_p



We've calculated circumference = $2\pi \sinh(p)$

so length of arc subtended by α is $\alpha \sinh p$

= $\alpha \left(\frac{e^p - e^{-p}}{2} \right)$: Grows exponentially fast

as a function of p .

Summary: In \mathbb{H}^2

- triangles are thin
- geodesics are contracting
- geodesics diverge exponentially fast.

Negative curvature in groups?

How do you think of a group as a metric space?

We will confine ourselves to finitely generated groups
ie there is a finite set $S \subseteq G$ such that the
homomorphism $F(S) \rightarrow G$ is surjective.

Def Let S be a finite generating set for G .

The Cayley graph $\mathcal{C}(G, S)$ is defined by:

vertices = elements of G

edges: There is an edge from g to gs
for each $g \in G, s \in S \cup S^{-1}$

involution: $\overline{(g, gs)} = (gs, g) = ((gs), (gs)s^{-1})$

Notation: $i(g, gs) = g$ $\tau(g, gs) = gs$

Note wma there are no loops $g \xrightarrow{s} g \Rightarrow gs = g \Rightarrow s = \text{id}$

similarly, wma there are no multiple edges

$$g \begin{array}{c} \xrightarrow{s_1} \\ \xrightarrow{s_2} \end{array} \Rightarrow \begin{array}{l} gs_1 = gs_2 \\ \Rightarrow s_1 = s_2 \end{array}$$

Usually, the two oriented edges $g \rightleftarrows gs$ are considered a single unoriented edge

$\mathcal{C}(G, S)$ is made into a metric space by:

- each edge is isometric to $[0, 1]$
- The distance between two points is the length of the shortest path joining them.

G acts on $\mathcal{C}(G, S)$ on the left:

$$x \in G \text{ Then } x \text{ acts by} \quad \begin{array}{ccc} g & \xrightarrow{gs} & \\ & \downarrow x & \\ xg & \xrightarrow{xgs} & \end{array}$$

left multiplication:

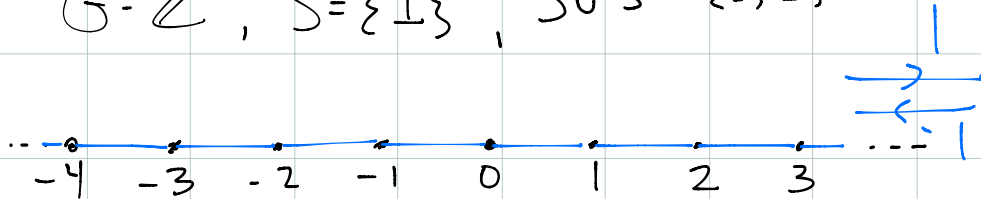
$(xy)g = x(yg)$, so this is an action,

ie a homomorphism $G \rightarrow \text{Isom}(\mathcal{C}(G, S))$

Remark: This is a free action: $\text{stab}(x) = 1 \ \forall x$, i.e.
 $gx = x \Rightarrow g = 1$

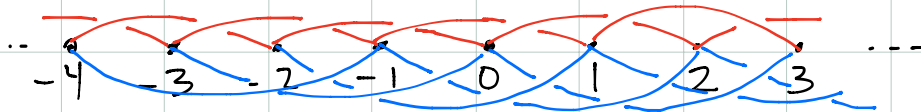
Examples

$$G = \mathbb{Z}, \quad S = \{1\}, \quad S \cup S^{-1} = \{1, -1\}$$



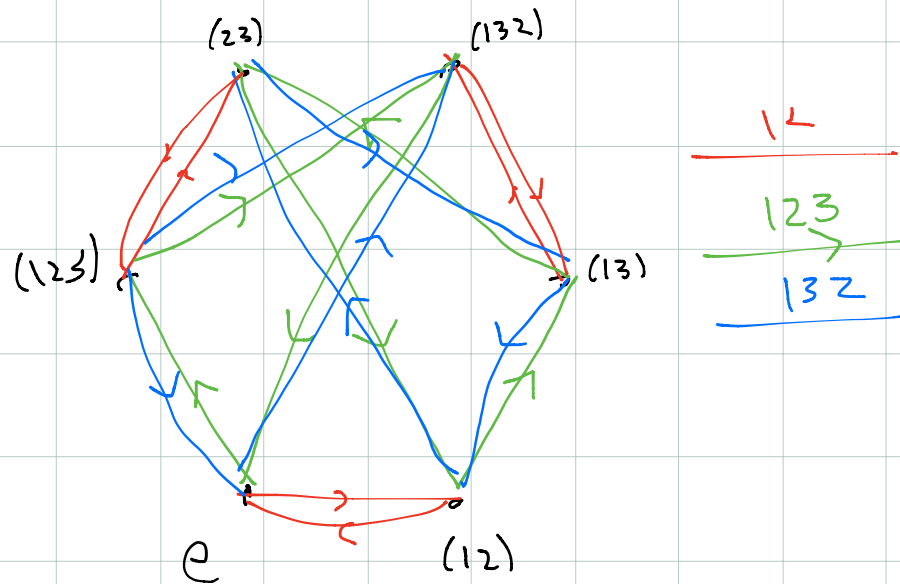
Action of G: n translates line to the right by n

$$G = \mathbb{Z}, \quad S = \{2, 3\}$$



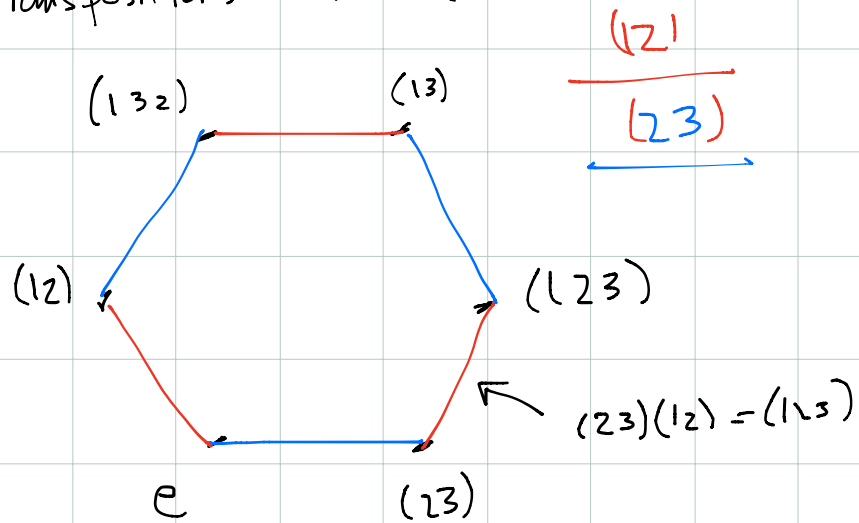
Example: $S_3 =$ symmetric group on 3 letters

of generators $S = (12), (123)$. $S \cup S^{-1} = \{(12), (123), (132)\}$

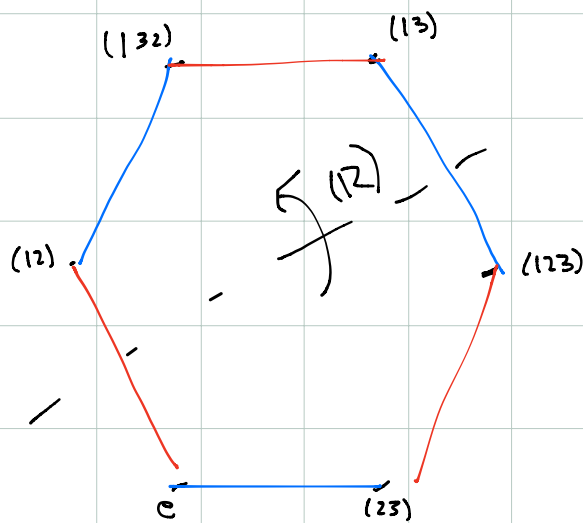


Example: $S_3 =$ symmetric group on 3 letters

Generated by transpositions (12) and (23) ($S=S^{-1}$)!



(12) acts by



(23) acts by vertical flip.

(123) acts by rotation.