

One more example of a group action

$SL(2, \mathbb{Z})$ again, but action on $\mathbb{H}^2$ instead of $\mathbb{R}^2$

$\mathbb{H}^2 = \text{upper half-plane} = \{z \mid \text{Im}(z) > 0\}$

$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(2, \mathbb{Z})$ acts by $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot z = \frac{az+b}{cz+d}$

Check: $z = x+iy, y > 0$

$$\Rightarrow \text{Im}\left(\frac{az+b}{cz+d}\right) = \text{Im}\left(\frac{a(x+iy)+b}{c(x+iy)+d}\right)$$

$$= \text{Im}\left(\frac{ax+b+i \cdot ay}{cx+d+i \cdot cy}\right) \left(\frac{cx+d-i \cdot cy}{cx+d-i \cdot cy}\right)$$

denominator is real > 0 $[(u+iv)(u-iv) = u^2+v^2]$

Imaginary part of numerator is

$$-(ax+b)cy + ay(cx+d) = (ad-bc) \cdot y = y > 0$$

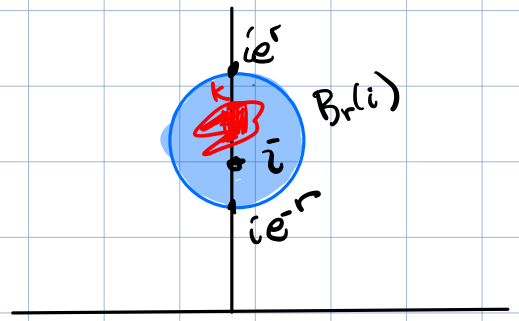
This is one of the most famous group actions in mathematics

This action is not free: $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \cdot i = \frac{0 \cdot i + 1}{-1 \cdot i + 0} = \frac{-1}{i} = i$

It is not faithful! $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \cdot z = \frac{-z}{-1} = z$

It is not cocompact

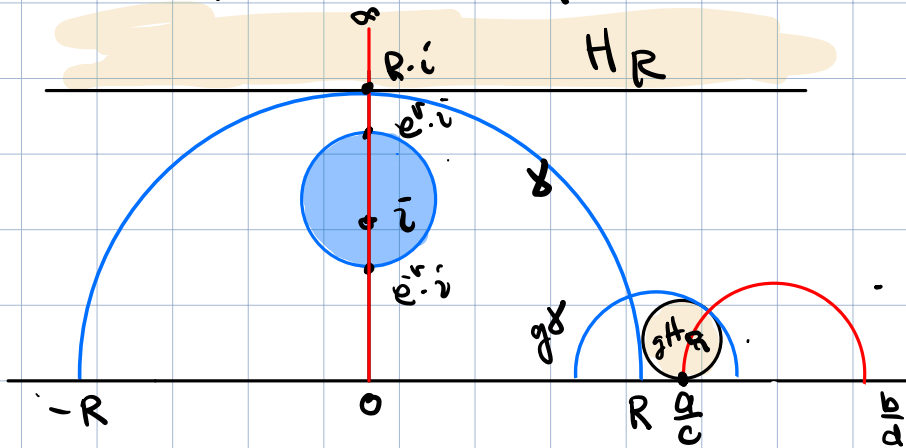
$K \text{ compact} \subseteq B_r(i)$ for some r



So suffices to show translates $g \cdot B_r(i)$ don't cover $\mathbb{H}^2$.

The top of $B_r(i)$ is at ie^r , the bottom is at ie^{-r}

Look at the horoball $\{z \mid \text{Im}(z) > R\} = H_R$
for $R \gg e^r$



Let $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(\mathbb{Z})$.

If $c=0$, $g^{-1} \cdot H_R = H_{R'}$ so $g^{-1} H_R \cap B_r(i) = \emptyset$
so $g H_R \cap B_r = \emptyset$ ✓

Now assume $c \neq 0$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \frac{1}{0} = \frac{a}{c}$$

so $g \cdot H_R$ is a horosphere at $\frac{a}{c}$

H_R lies above the geodesic γ from $-R$ to R ,
 so $g \cdot H_R$ lies below the geodesic from
 $g(-R)$ to gR .

Claim the highest point of $g \cdot \gamma$ has
 imaginary part $\frac{1}{c^2 R - \frac{d^2}{R}}$

Proof of Claim: We want to calculate the
 (Euclidean) radius of the geodesic,
 ie $\frac{1}{2} |g \cdot R - g \cdot (-R)|$

$$\begin{aligned}
 & \frac{1}{2} \left[\begin{pmatrix} a & b \\ c & d \end{pmatrix} (-R) - \begin{pmatrix} a & b \\ c & d \end{pmatrix} (R) \right] = \frac{a(-R) + b}{c(-R) + d} - \frac{aR + b}{cR + d} \cdot \frac{1}{2} \\
 & = \frac{1}{2} \left[\frac{(b - aR)(d + cR) - (b + aR)(d - cR)}{-c^2 R^2 + d^2} \right] \\
 & = \frac{1}{2} \left[\frac{\cancel{bd} + (bc - ad)R - \cancel{acR^2} - \cancel{bd} + (bc - ad)R + \cancel{acR^2}}{-c^2 R^2 + d^2} \right] \\
 & = \frac{1}{2} \left[\frac{-2(ad - bc)R}{d^2 - c^2 R^2} \right] = \frac{R}{c^2 R^2 - d^2} \\
 & = \frac{1}{c^2 R - \frac{d^2}{R}} \quad \checkmark
 \end{aligned}$$

Since $\tilde{c}^2 \geq 1$, if R is sufficiently

large then $\frac{1}{c^2 R - \frac{d^2}{R}} < \frac{1}{e^r}$

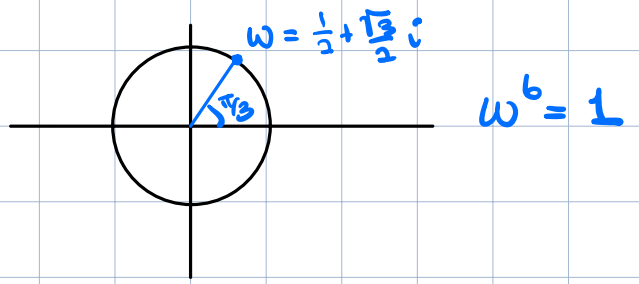
So $B_r(i)$ does not intersect $g \cdot H_R$.

So $\bar{g}' B_r(i)$ does not intersect H_R

for any g , so translates of $B_r(i)$

do not cover H^2 .

The action is proper
and stabilizers are small:



$$G_z = \{ \text{ unless } z = g \cdot i \text{ or } g \cdot w$$

$$\text{stab}(i) = \left\langle \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\rangle \cong \mathbb{Z}/4\mathbb{Z} \quad \text{stab}(w) = \left\langle \begin{pmatrix} -1 & 1 \\ -i & 0 \end{pmatrix} \right\rangle \cong \mathbb{Z}/6\mathbb{Z}$$

Aside: If $G \curvearrowright X$ and $x \in X$, then

$$\text{stab}(gx) = g(\text{stab } x)g^{-1}.$$

$$\text{pf: } \ni h \in \text{stab } x \Rightarrow ghg^{-1} \cdot (gx) = ghx = gx, \\ \text{i.e. } ghg^{-1} \in \text{stab}(gx)$$

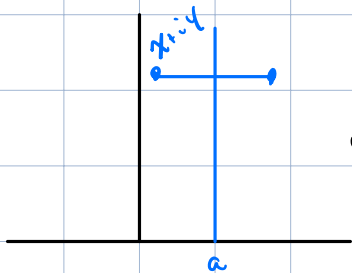
$$\subseteq h \in \text{stab } gx \Rightarrow hgx = gx \Rightarrow g^{-1}hgx = x \\ \Rightarrow g^{-1}hg \in \text{stab } x \quad \checkmark$$

What makes this action especially interesting and useful is that it preserves the hyperbolic metric, i.e. acts by isometries

To prove this, you just need to check that generators for $SL(2, \mathbb{Z})$ act by isometries.

Claim $SL(2, \mathbb{Z})$ is generated by $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ and $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$
 (proof: Euclidean algorithm: - these matrices do row and column operations, which can reduce $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ to $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ since $ad-bc=1$
 $\Rightarrow \gcd(a, c) = \gcd(b, d) = 1$

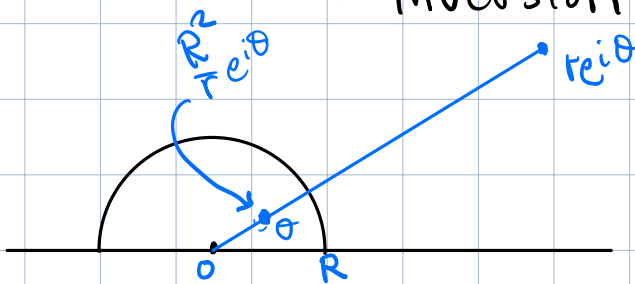
Recall: • Geodesics in $\mathbb{H}^2$ are circles and lines perpendicular to the real axis



• Reflection in a vertical line is an isometry

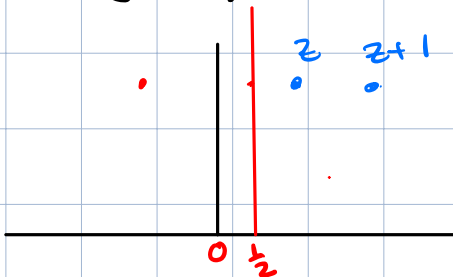
$$\begin{aligned} x+iy &\leftrightarrow -x+2a+iy \\ z &\leftrightarrow -\bar{z}+2a \end{aligned}$$

• inversion in a circle is an isometry

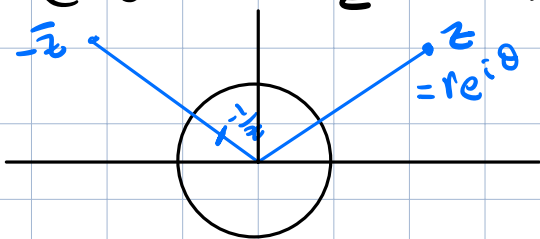


$$re^{i\theta} \leftrightarrow \frac{R^2}{r} e^{i\theta}$$

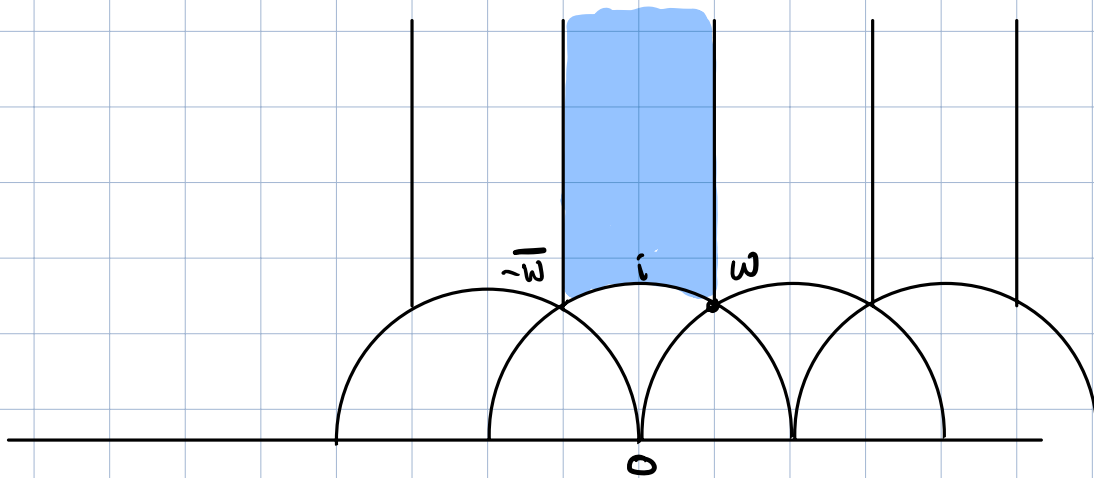
$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} z = z+1$: horizontal translation by 1.
 = product of reflections in imaginary axis and vertical line $\text{Re}(z) = \frac{1}{2}$



$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} z = -\frac{1}{z}$: reflection in imaginary axis followed by inversion in circle centered at 0 radius 1,



Translates of the blue area cover $\mathbb{H}^2$
(slightly tricky exercise).



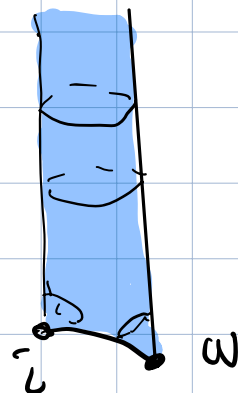
The left side is identified with the right by $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$

The circle arc from i to w is identified with the circle arc from i to $-w$ by $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

There are no other identifications

so the orbit space is

$$SL(2, \mathbb{Z}) \backslash \mathbb{H}^2 =$$



From now on we will be mostly interested in studying finitely generated groups acting on metric spaces by isometries

If G is finitely generated by S , we can define a metric on G using S .
then G acts on itself by multiplication, which is an isometry.

Details: For $g \in G$, define $l_s(g)$ = length of shortest word in S representing g .
and $d_s(g, h) = l_s(g^{-1}h)$. We assume $1 \notin S$, so $l_s(1) = 0$.

Check: d is a metric

- $d_s(g, g) = l_s(g^{-1}g) = l_s(1) = 0$ ✓
- $d_s(g, h) = l_s(g^{-1}h) = l_s(h^{-1}g) = d_s(h, g)$ ✓

- $d_s(g, h) + d_s(h, k) = l_s(g^{-1}h) + l_s(h^{-1}k)$
 $\geq l_s(g^{-1}h h^{-1}k) = l_s(g^{-1}k)$
 $= d_s(g, k)$ ✓

Action $g \cdot h = gh$

The action preserves the metric:

$$d(gh, gk) = l_s(h^{-1}g^{-1}gk) = l_s(h^{-1}k) = d(h, k) \checkmark$$

eg $G = \langle t \rangle$ $\begin{matrix} t^{-1} & 1 & t & t^2 & t^3 & t^4 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{matrix}$

$$t^k \cdot t^n = t^{k+n}$$

Note a different generating set S gives a different metric:

eg:

G is also generated by $S' = \{t^2, t^3\}$ ($t^3 \cdot (t^2)^{-1} = t$)
 so $d_S(1, t^2) = d_{S'}(1, t^3) = 1$, $d_S(t) = 2$.

Cayley Graphs

Let G be finitely generated by S ($1 \notin S$)

The Cayley graph $\mathcal{C}(G, S)$ is the graph

- with
- vertices = elements of G
 - an edge from g to gs for every $s \in S$.

Notes:

- $g \xrightarrow{s} gs$ and $gs^{-1} \xleftarrow{s} g$ are edges
- $1 \notin S \Rightarrow$ there are no loops

So all vertices have an incoming edge and outgoing edge for each $s \in S$.

eg $G = \langle t \rangle$, $S = \{t\}$

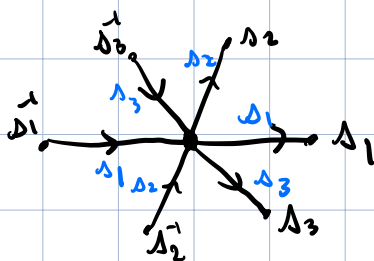
$\mathcal{C}(G, S) = \dots \xrightarrow{t} t^{-2} \xrightarrow{t} t^{-1} \xrightarrow{t} 1 \xrightarrow{t} t \xrightarrow{t} t^2 \xrightarrow{t} t^3 \dots$

G acts on $\mathcal{C}(G, S)$ (on the left) by:

If $h \in G$ $h \cdot g = hg$, and if e is the edge $g \xrightarrow{s} gs$
 then $h \cdot e$ is the edge $hg \xrightarrow{s} hgs$

This action is free: If g is a vertex and $h \in G_g$ then $hg = g$, which implies $h = 1$.
 If e is an edge $\overset{g}{\bullet} \xrightarrow{s} \bullet \xrightarrow{s} g^s$ and $h \in \text{stab}(e)$ then $hg = g$ and $hgs = gs$, so again $h = 1$.

The action is cocompact:
 Let $\text{st}(1) = 1$ plus all edges adjacent to 1



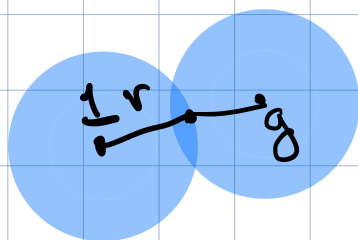
The translates of $\text{st}(1)$ cover $\mathcal{C}(G, S)$.

The quotient by the action is the rose with one petal for each generator



The action is proper: If $K \subset \mathcal{C}(G, S)$ is compact, $K \subset B_r(1)$ for some r

If $g \cdot B_r(1) \cap B_r(1)$ is not empty, then $g \cdot B_r(1)$ is centered at g , with $d(1, g) \leq 2$



There are only finitely many such g ,
 so $g \cdot B_r(1) \cap B_r(1) \neq \emptyset$ for only finitely many g .

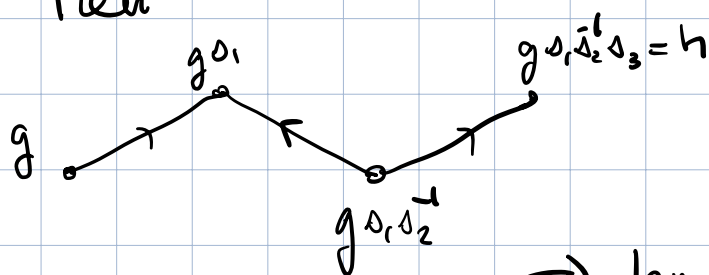
To make $\ell(G, S)$ a metric space,

- Define the distance between two vertices as the length of the shortest edge-path
- Make the interior of each edge isometric to $(0,1) \in \mathbb{R}$.

• If $x \in e_x$ and $y \in e_y$,

define $d(x, y) = \text{length of shortest path from } x \text{ to a vertex of } e_x \text{ to a vertex of } e_y \text{ to } y$

If g, h are vertices (= elements of G)
then



$$\Rightarrow s_1 s_2^{-1} s_3 = \bar{g}^{-1} h$$

$\Rightarrow$ length of shortest edge-path

$$\text{from } g \text{ to } h = \ell_S(\bar{g}^{-1} h) = d_S(g, h)$$

$G \subset \ell(G, S)$ preserves distance between vertices, and $\therefore$ length of paths, so distances between any points.

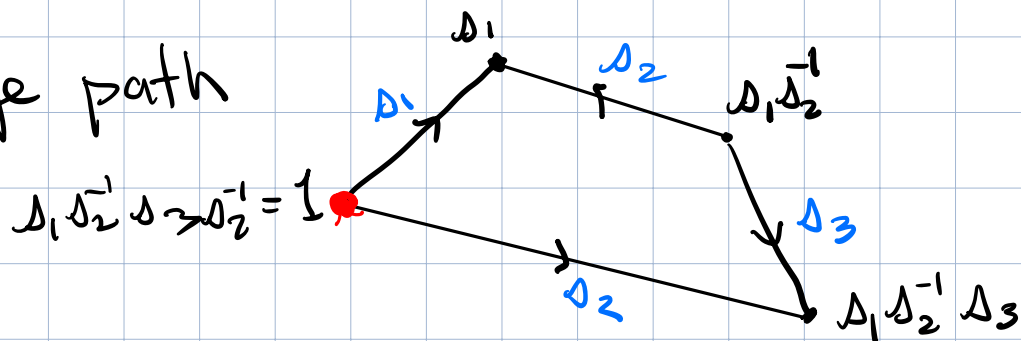
Suppose a product of generators and their inverses is the identity in G

$$\Delta_1^{\epsilon_1} \Delta_2^{\epsilon_2} \dots \Delta_k^{\epsilon_k} = 1$$

Note $g \xleftarrow{\Delta_1} g\Delta_1^{-1}$ is an edge.

Eg suppose $\Delta_1 \Delta_2^{-1} \Delta_3 \Delta_2^{-1} = 1$

Then the edge path



ends at 1,

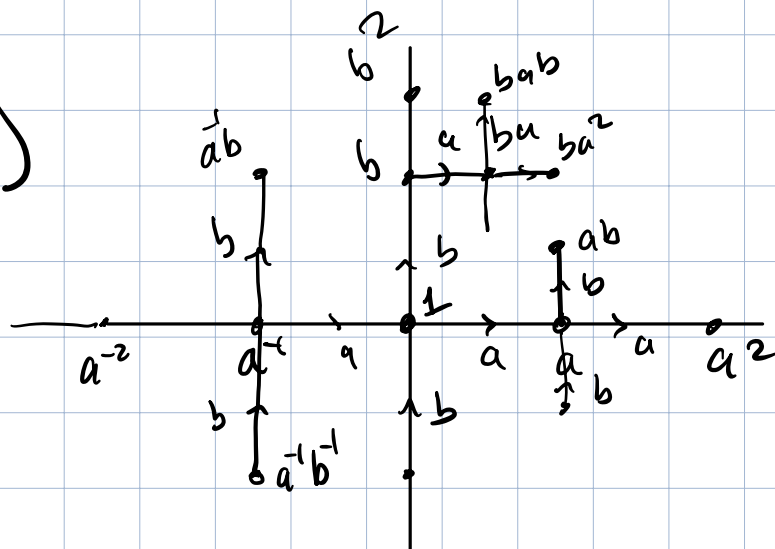
so is a loop.

Loops in $\ell(G, S)$ correspond exactly to elements in $\ker(F(S) \rightarrow G)$

ie to relations in G wrt S .

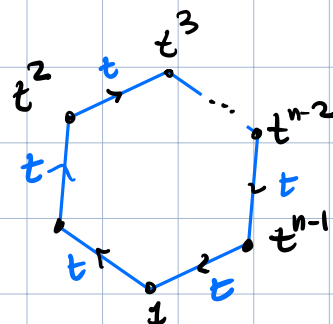
Some more examples:

eg $\mathcal{C}(\mathbb{F}_2, \{a, b\})$

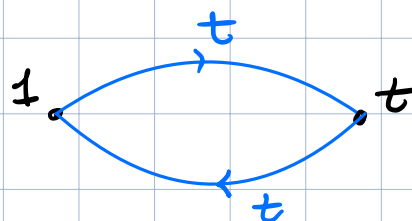


eg $G = \text{cyclic group of order } n = \langle t \mid t^n \rangle, S = \{t\}$

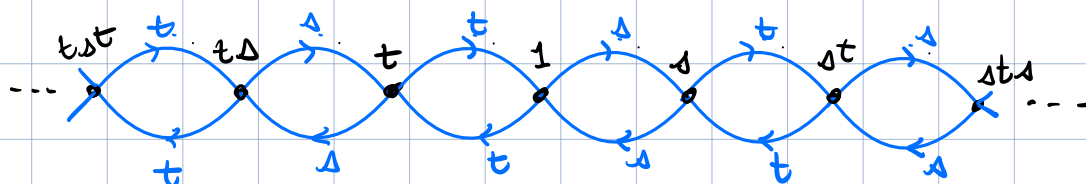
$\mathcal{C}(\langle t \mid t^n \rangle, \{t\}) =$



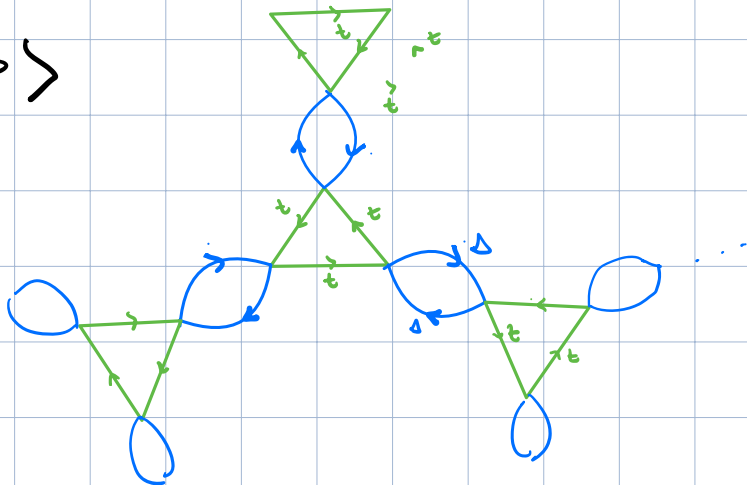
eg $\mathcal{C}(\langle t \mid t^2 \rangle, \{t\})$



eg Infinite dihedral group $\langle t, s \mid t^2, s^2 \rangle$
 $S = \{s, t\}$

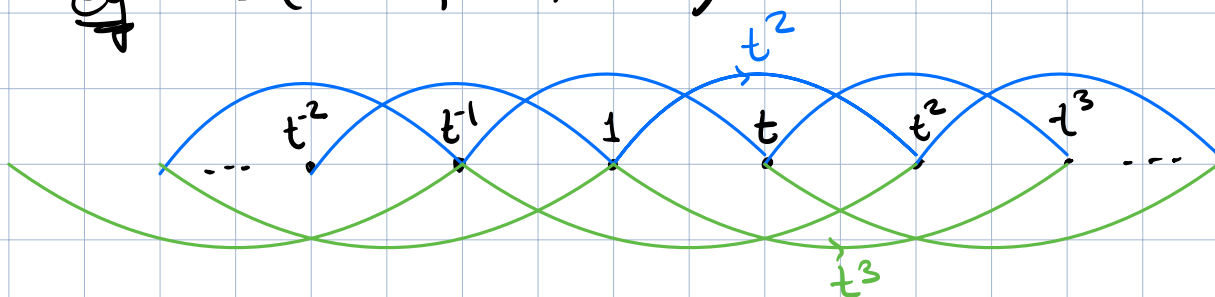


eg $\langle s, t \mid s^2, t^3 \rangle$



Different generating sets can produce non-isomorphic graphs

eg $\mathcal{C}(\langle t \rangle, \{t^2, t^3\})$



and non-isomorphic groups can have isomorphic unlabeled Cayley graphs.

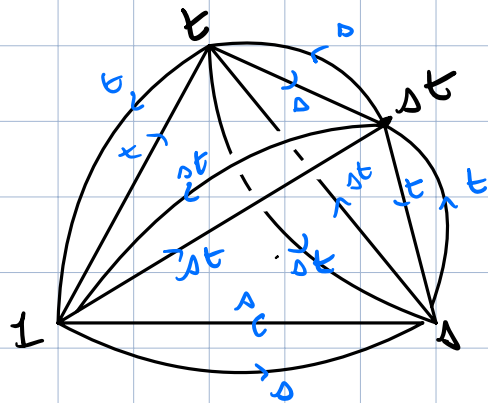
eg

$$G = \mathbb{Z}/2 \times \mathbb{Z}/2, \quad \mathbb{Z}/4 \quad \text{both have 4 elements}$$

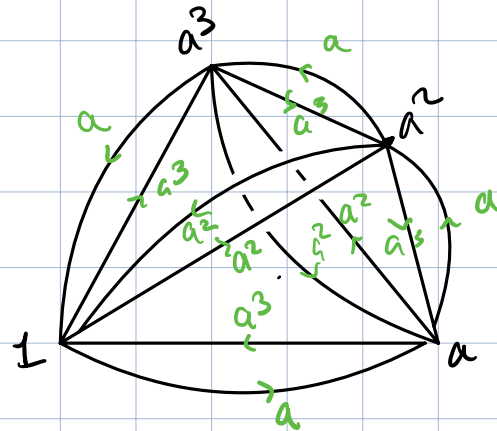
If you choose $S = \underline{\text{all}}$ non-trivial elements of G

Then $\mathcal{C}(G, G)$ is the complete graph on 4 vertices, double edge.

$$\mathbb{Z}/2 \times \mathbb{Z}/2 = \{1, a, b, ab\}$$



$$\mathbb{Z}/4 = \{1, a, a^2, a^3\}$$



But, if you include labels, the Cayley graph uniquely determines G .

Prop if there is a bijection $S \rightarrow S'$
and a (directed) graph isomorphism

$$\mathcal{C}(G, S) \rightarrow \mathcal{C}(G', S')$$

Then the map $S \rightarrow S'$ extends

to an isomorphism $G \rightarrow G'$

Proof $G = \langle S \mid R \rangle$. Then

Elements of $R \iff$ loops in $\mathcal{C}(G, S)$

$\iff$ loops in $\mathcal{C}(G', S')$

$\iff$ words in $F(S')$

that are trivial in G' ,

$\therefore$ The map $G = F(S) / \langle\langle R \rangle\rangle \longrightarrow G'$

extends to a homomorphism (which is surjective since $S \rightarrow S'$.)

Similarly, get a surjective homomorphism

$$G' \longrightarrow G$$

Composition is identity (both ways) so both maps are also injective. ✓

We have

- $\mathcal{C}(G, S)$ is a metric space and $G \curvearrowright \mathcal{C}(G, S)$ by isometries : $d(gx, gy) = d(x, y)$

- $(G, d_S) \hookrightarrow \mathcal{C}(G, S)$ preserves distance
 $d_S(v, w) = d_S(v, w) = d_G(v, w)$

Now we want to use the geometry of $\mathcal{C}(G, S)$ to study G - eg use $\mathcal{C}(G, S)$ as a ping-pong table to find free subgroups of G

Problem: Suppose G acts on two different metric spaces $G \curvearrowright X_1$, $G \curvearrowright X_2$. How is the geometry of X_1 related to the geometry of X_2 ?

Example 1 Let S, S' be two different finite generating sets for G

$$\left. \begin{array}{l} G \curvearrowright \mathcal{L}(G, S) \\ G \curvearrowright \mathcal{L}(G, S') \end{array} \right\} \text{ free, proper, cocompact}$$

Example 2 Let $G = \mathbb{Z}^2$, $S = \{e_1, e_2\}$

$$\left. \begin{array}{l} G \curvearrowright \mathcal{L}(G, S) = \text{unit grid} \\ G \curvearrowright \mathbb{R}^2 \text{ by translations} \end{array} \right\} \text{ free, proper, cocompact}$$

So X_1, X_2 are not necessarily isometric,
But there's a coarser notion called
quasi-isometry.

The Svarc-Milnor Lemma

(also called the Fundamental Theorem of Geometric Group Theory) says that if the actions are nice enough, then X_1 is quasi-isometric to X_2 . Then quasi-isometry invariants are invariants of G .

To motivate the definition of quasi-isometry,

Consider the embedding $b(\mathbb{Z}^2, \{e_i, e_j\}) \hookrightarrow \mathbb{R}^2$

This is not an isometry but.

① It is almost surjective

$$\forall y \in \mathbb{R}^2. \exists x \in \mathbb{Z}^2 \text{ s.t. } d(y, f(x)) < \frac{1}{2}$$

② It almost preserves distance

$$\frac{1}{\sqrt{2}} d_b(x, y) \leq d_{\mathbb{R}^2}(f(x), f(y)) \leq d_b(x, y)$$

Definition X, Y metric spaces. A map $f: X \rightarrow Y$

- is quasi-surjective if $\exists K > 0$ s.t.
 $\forall y \in Y, \exists x \in X \text{ s.t. } d(y, f(x)) \leq K.$

(note K -quasi-surjective $\Rightarrow K'$ q-surj for any $K' > K$)

- is a quasi-isometric embedding if
 $\exists \lambda \geq 1, C \geq 0$ s.t. $\forall x, x' \in X,$

$$\frac{1}{\lambda} d(x, x') - C \leq d(f(x), f(x')) \leq \lambda d(x, x') + C$$

- is a quasi-isometry if it is a
quasi-surjective quasi-isometric embedding.
(or a (λ, C, K) -quasisometry)

Note: (λ, C) -qi $\Rightarrow (\lambda', C')$ -qi for any $\lambda' \geq \lambda, C' \geq C$

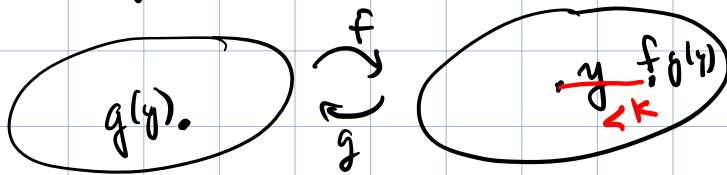
Lemma: Suppose $f: X \rightarrow Y$, $g: Y \rightarrow X$
and $\lambda \geq 1, C \geq 0, K \geq 0$ st.

- $d(f(x), f(x')) \leq \lambda d(x, x') + C \quad \forall x, x' \in X$
- $d(g(y), g(y')) \leq \lambda d(y, y') + C \quad \forall y, y' \in Y$
- $d(x, g f(x)) \leq K \quad \forall x \in X$
- $d(y, f g(y)) \leq K \quad \forall y \in Y$

Then f and g are quasi-isometries.

Proof: Proof for f (proof for g is the same)

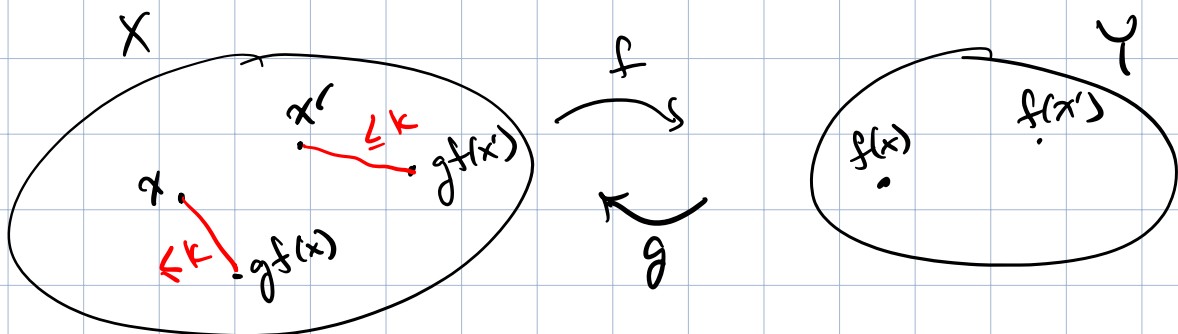
- f is quasi-surjective: $y \in Y$



and f is a qi-embedding: need $\lambda' \geq \lambda, C' \geq C$ st

$$\frac{1}{\lambda'} d(x, x') - C' \leq d(f(x), f(x'))$$

$$\text{ie } d(x, x') \leq \lambda' d(f(x), f(x')) + C'$$



$$\begin{aligned}
 d(x, x') &\leq d(x, gf(x)) + d(gf(x), gf(x')) + d(gf(x'), x') \\
 &\leq d(gf(x), gf(x')) + 2K \\
 &\leq \lambda d(f(x), f(x')) + C + 2K
 \end{aligned}$$

$\lambda' = \lambda$ $C' = \max(C\lambda, C+2K)$

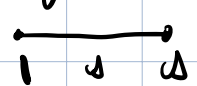
Cor S, S' two finite generating sets for G .

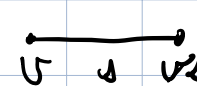
The $\ell(G, S)$ is qv to $\ell(G, S')$

Pf Define $\ell(G, S) \xrightarrow{f} \ell(G, S')$ 

by :

- identity on vertices

- Send  to a shortest path γ_s in $\ell(G, S')$ connecting s to s' .

- Send  to $u \circ \gamma_s$

Write each elt $s \in S$ as a word in $S' S'^{-1}$

Define $\lambda = \max_{s \in S} l_{S'}(s)$

Then f stretches each edge by at most λ .

So $d_{\ell'}(f(x), f(x_2)) \leq \lambda d_{\ell}(x, x_2) + 0$

for any $x, x_2 \in \ell(G, S)$

Similarly, define $h: \mathcal{C}(G, S') \rightarrow \mathcal{C}(G, S)$
 by sending each edge $\overset{v}{\bullet} \xrightarrow{s'} \overset{v}{\bullet} \xrightarrow{s'} \overset{s'}{\bullet}$ to the
 v -translate of a shortest path
 in $\mathcal{C}(G, S)$ from 1 to s'

and let $\lambda' = \max_{s' \in S'} l_S(s')$

$$d_{\mathcal{C}}(h(x_1), h(x_2)) \leq \lambda' d_{\mathcal{C}}(x_1, x_2)$$

$$\text{Then } d_{\mathcal{C}}(x, hf(x)) = \begin{cases} 0 & \text{if } x \text{ is a leaf} \\ \leq \lambda \lambda' & \text{otherwise} \end{cases}$$

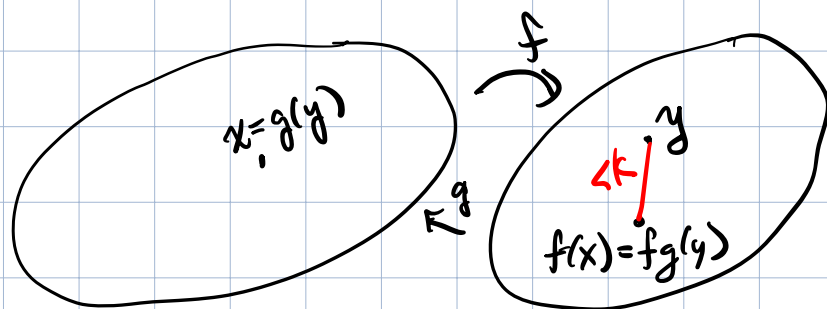
Prop Quasi-Metricity is an equivalence relation

pf reflexive $\checkmark$, $X \xrightarrow{id} X$

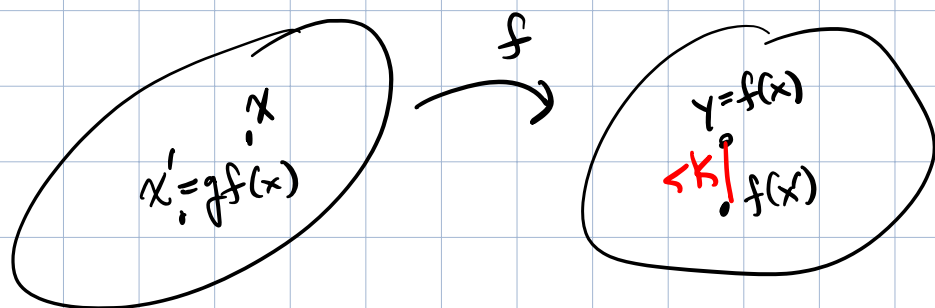
transitive $\checkmark$ $X \xrightarrow{f} Y \xrightarrow{g} Z$
(exercise)

symmetric: Let $f: X \rightarrow Y$ be a (λ, C, K) -qi.

Define $g: Y \rightarrow X$: For $y \in Y$, choose
 $x \in X$ w/ $d(f(x), y) < K$
Define $g(y) = x$.



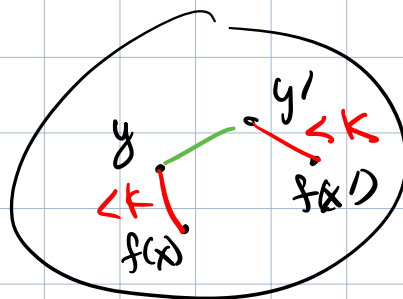
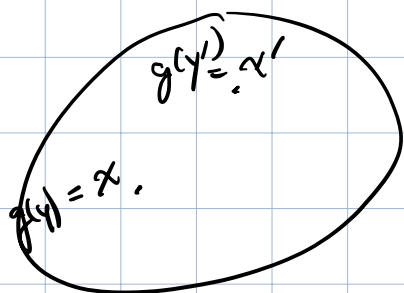
Then $d(fg(y), y) = d(f(x), y) < K \checkmark$



$$d(f(x), fg(x)) \geq \frac{1}{\lambda} d(x, x') - C$$

$$\Rightarrow d(gf(x), x) = d(x, x') \leq \lambda(d(f(x), fg(x)) + C) \\ \leq \lambda K + C\lambda := K' \checkmark$$

Now: $d(g(y), g(y')) < \lambda' d(y, y') + C :$



$$d(f(x), f(x')) \geq \frac{1}{\lambda} d(x, x') - C$$

$$\Rightarrow \lambda [d(f(x), f(x')) + C] \geq d(x, x')$$

$$\begin{aligned} \text{So } d(g(y), g(y')) &= d(x, x') \leq \lambda [d(f(x), f(x')) + C] \\ &\leq \lambda (2k + d(y, y') + C) \\ &= \underbrace{\lambda}_{\lambda'} d(y, y') + \underbrace{2k\lambda + C\lambda}_{C'} \checkmark \end{aligned}$$

We want nice actions on nice metric spaces

Let X be a metric space

A path from x to y in X is a geodesic if its length is equal to $d(x, y)$.

(Geodesics are not necessarily unique!)

A metric space is geodesic if any two points are connected by a geodesic

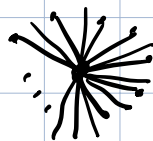
A metric space is proper if closed balls of finite radius r are compact.

I Proper metric space $\neq$ proper action!

non-examples:

- $\mathbb{R}^2 - \{0,0\}$ is not geodesic

- a graph with an infinite-valent vertex. is not proper



Ready to prove the Fundamental Theorem

Thm (Svarc-Milnor Lemma) (X, d_X) = proper geodesic metric space, $G \curvearrowright X$ a proper cocompact action. Then G is finitely generated and (G, d_S) is quasi-isometric to (X, d_X) for any finite generating set S .

Proof of Theorem: Choose any $x_0 \in X$ and define $f: G \rightarrow X$ by $f(g) = g \cdot x_0$

Claim 1 G is finitely generated.

Claim 2 For some (hence any) finite generating set S , $f: (G, d_S) \rightarrow (X, d_X)$ is a quasi-isometry

Setup Choose $K \subset X$ compact s.t. $X = \bigcup_g g \cdot K$, with $x_0 \in K$.

Then $K \subset U$ for some open ball $U = B_r(x_0)$, with (compact) closure $\bar{U}$.

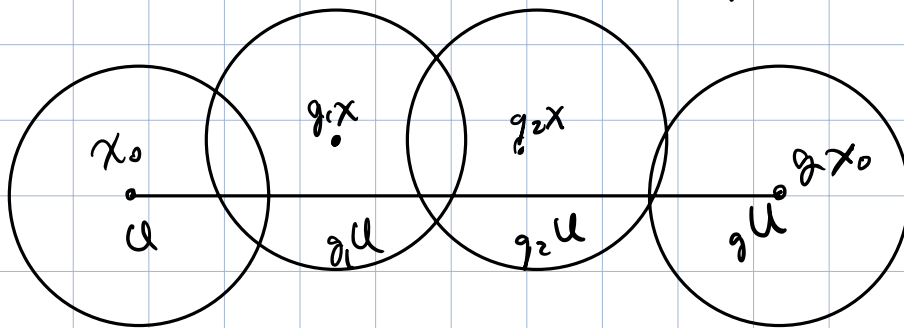
Now $X = \bigcup_{g \in G} gU$ and

$$S = \{g \in G \mid gU \cap U \neq \emptyset\} \subseteq \{g \in G \mid gD \cap D \neq \emptyset\},$$

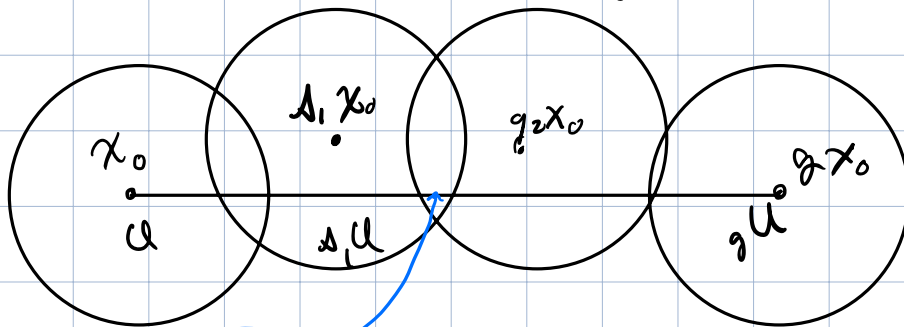
which is finite since the action is proper

To prove Claim 1 we will show S generates G .

proof For $g \in G$ let σ be a path from x_0 to gx_0 .
Cover σ by translates of U , then take
a finite subcover $U, g_1U, g_2U, \dots, gU$



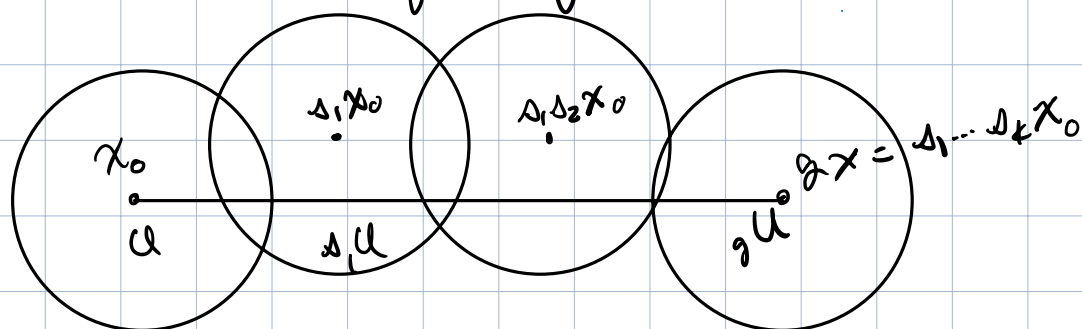
$$U \cap g_1U \neq \emptyset \Rightarrow g_1 \in S, \text{ say } g_1 = \Delta_1$$



$$\Delta_1 U \cap g_2U \neq \emptyset \Leftrightarrow U \cap \Delta_1^{-1}g_2U \neq \emptyset$$

$$\Rightarrow \Delta_1^{-1}g_2 = \Delta_2 \in S \Rightarrow g_2 = \Delta_1 \Delta_2$$

etc continue, get $g = s_1 s_2 \dots s_k$, $s_i \in S$ ✓



Claim 2: $f: (G, d_S) \longrightarrow (X, d_X)$ is a q.i.
 $g \longmapsto gx_0$

We need to show

- f is quasi-surjective and
- $\exists \lambda \geq 1, c \geq 0$ s.t

$$(*) \begin{cases} \forall g_1, g_2 \in G, \\ \frac{1}{\lambda} d_S(g_1, g_2) - c \leq d_X(g_1 x_0, g_2 x_0) \leq \lambda d_S(g_1, g_2) + c \end{cases}$$

Now $d_S(g_1, g_2) = d_S(g_1^{-1} g_2) = d_S(1, g_1^{-1} g_2)$. Also, G acts by isometries, so $d_X(g_1 x_0, g_2 x_0) = d_X(1, g_1^{-1} g_2 x_0)$

Setting $g = g_1^{-1} g_2$, (*) becomes the simpler-looking

$$(**) \begin{cases} \forall g \in G, \\ \frac{1}{\lambda} d_S(1, g) - c \leq d_X(x_0, gx_0) \leq \lambda d_S(1, g) + c \end{cases} \quad \text{②} \quad \text{①}$$

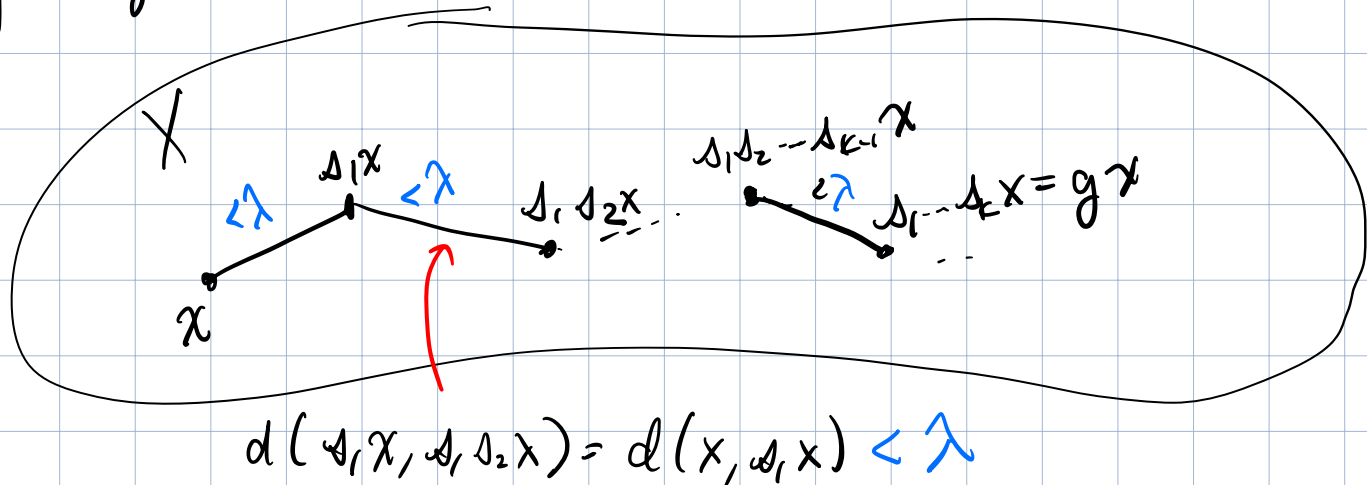
- f is quasi-surjective:
The balls $g B_r(x) = B_r(gx)$ cover X ,
So every $x \in X$ is within r of some gx . ✓

- ① Let S be any finite generating set.

Suppose $g = s_1 \dots s_k$ $s_i \in S \cup S^{-1}$
is a shortest word, i.e. $d_S(1, g) = k$.

Let $\lambda = \max_{s \in S} d(x, sx)$. Then we can

make a path in X from x_0 to gx_0
of length $\leq \lambda \cdot k$:



$$\text{So } d_x(x, gx) \leq \lambda d_S(1, g) + 0$$

② It remains: $d_X(x, gx) \geq \frac{1}{\lambda} d_S(l, g) - C$

$$\text{ie } d_S(l, g) \leq \lambda d_X(x, gx) + C\lambda$$

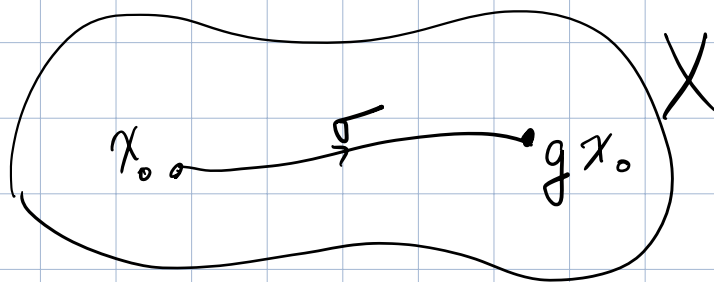
We have r s.t. $\{g \cdot B_r(x_0)\}$ cover X

$$\text{Let } S' = \{g \mid g B_{3r}(x_0) \cap B_{3r}(x_0) \neq \emptyset\}$$

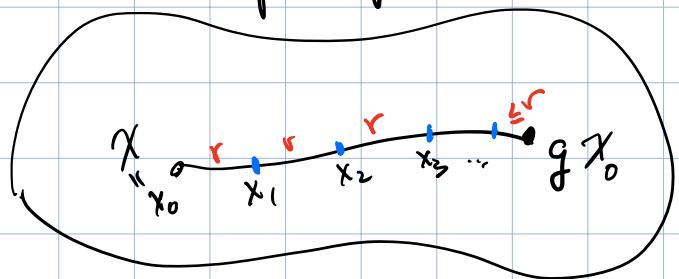
Since the translates of $B_r(x_0)$ cover X ,
so do the translates of $B_{3r}(x_0)$,

So the same arguments show S' is also
a finite generating set, and ① holds

Now let σ be a geodesic from x to gx .

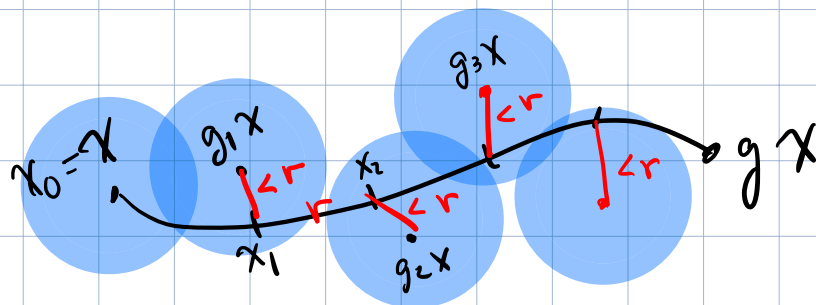


Divide σ into n pieces, each of length $= r$ except
the last has size $r' \leq r$.



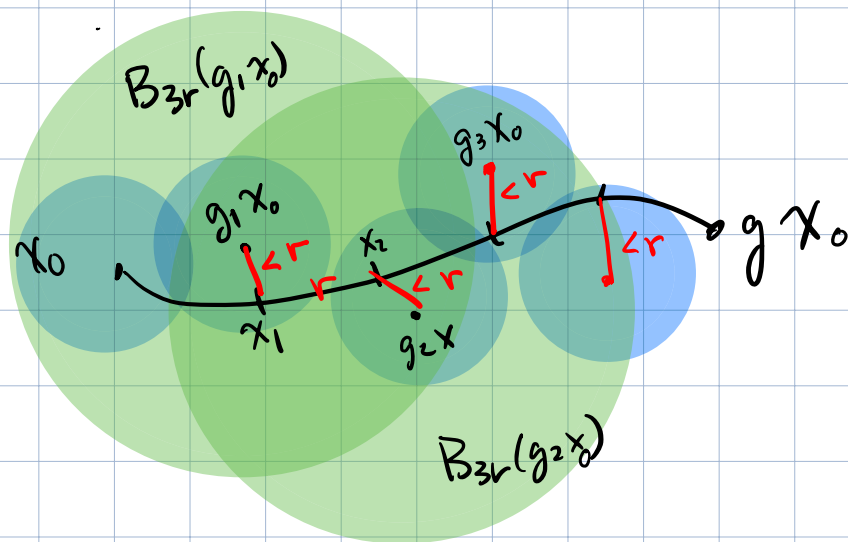
Now $d(x_i, g x_0) = \text{length}(\sigma) = (k-1) \cdot r + r'$

The translates of $B_r(x_0)$ cover X , so
for each i , $\exists g_i$ with $d(x_i, g_i x_0) < r$



Then $d(g_i x_0, g_{i+1} x_0) < 3r$, so

$$B_{3r}(g_i x_0) \cap B_{3r}(g_{i+1} x_0) \neq \emptyset$$



so $B_{3r}(x) \cap g_i^{-1} g_{i+1} B_{3r}(x) \neq \emptyset$, and

$$g_i^{-1} g_{i+1} \in S' \text{ for all } i.$$

$$\text{Write } g = (1, g_1)(g_1^{-1}, g_2)(g_2^{-1}, g_3) \dots (g_{k-1}^{-1}, g_k) \\ = d_1 \quad d_2 \quad d_3 \quad \dots \quad d_k$$

$$\text{So } d_{S'}(1, g) \leq k$$

$$\text{But } r(k-1) \leq d_x(x, gx) \Rightarrow k \leq \frac{1}{r} d_x(x, gx) + 1$$

$$\text{so } d_{S'}(1, g) \leq k \leq \frac{1}{r} d_x(x, gx) + 1$$

$\uparrow$

$\hookrightarrow \checkmark$

Definition A proper, cocompact action on a proper geodesic metric space will be called a geometric action

Examples:

1. $\mathbb{Z}^n \curvearrowright \mathbb{R}^n$ by linearly-independent translations
is geometric

$$\Rightarrow \mathbb{Z}^n \underset{q_i}{\sim} \mathbb{R}^n.$$

$$\begin{aligned}
 2. \quad F_2 &= \pi_1(\bigcirc) \cong \text{univ. cover of } \bigcirc \\
 &= 4\text{-valent tree } T_4 \\
 &\quad \text{---} \text{---} \text{---} \text{---} \\
 &\quad \text{---} \text{---} \text{---} \text{---} \\
 &\Rightarrow F_2 \sim_{q_i} T_4
 \end{aligned}$$

$$\begin{aligned}
 3. \quad F_2 &= \pi_1(\textcircled{1}) \cong \text{univ. cover of } \textcircled{1} = \text{---} \text{---} \text{---} \text{---} \\
 &= \text{trivalent tree } T_3 \\
 &\Rightarrow F_2 \sim_{q_i} T_3
 \end{aligned}$$

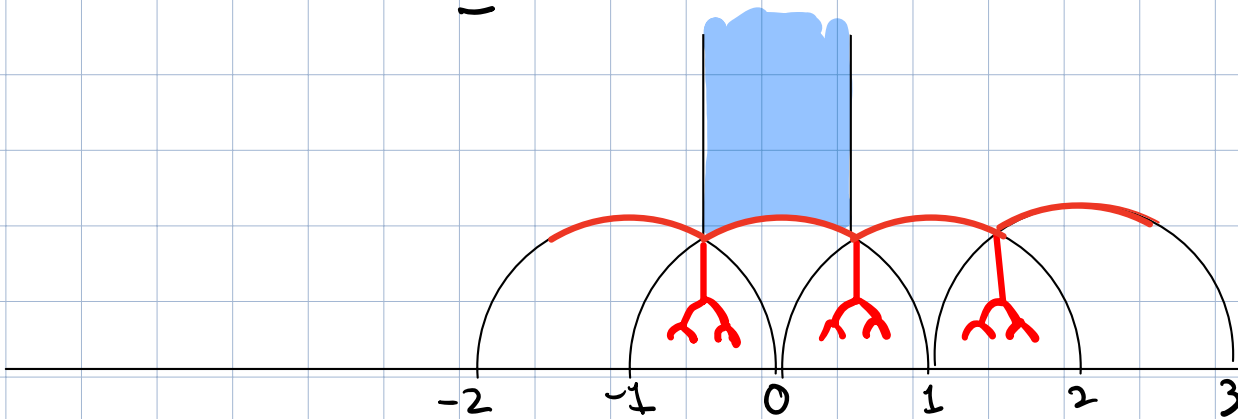
$$\rightarrow T_4 \sim_{q_i} F_2 \sim_{q_i} T_3 \Rightarrow T_1 \sim_{q_i} T_3$$

$$4. \quad F_3 = \pi_1(\textcircled{2}) \cong T_3 = \text{univ. cover of } \textcircled{2}$$

$$\rightarrow F_3 \sim T_3 \sim F_2$$

5 Action of $SL(2, \mathbb{Z})$ on $\mathbb{H}^2$ is proper but not cocompact, so you can't conclude $SL(2, \mathbb{Z}) \backslash \mathbb{H}^2 \cong \mathbb{H}^2$

But there's a trivalent tree T inside $\mathbb{H}^2$ that is invariant under the action.



$T = \text{union of images of } \bar{w} \overset{i}{\curvearrowright} w = \alpha$

$\text{stab}(w)$ is generated by $\begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix}$

$$\begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} z = \frac{1}{-z+1} \quad \begin{array}{l} 1 \mapsto \infty \\ -1 \mapsto \frac{1}{2} \end{array}$$

So sends the geodesic arc α to an arc in the vertical geodesic from $\frac{1}{2}$ to ∞

The action of $SL_2(\mathbb{Z})$ on T is cocompact,

$$\text{so } SL(2, \mathbb{Z}) \backslash \mathbb{H}^2 \cong T_3 \sim \mathbb{F}_2$$

In fact, $SL(2, \mathbb{Z})$ has a finite-index subgroup which is a free group

Prop If G is finitely generated and $H < G$ has finite index, then H is quasi-isometric to G .

Proof The action of G on $\mathcal{C}(G, S)$

restricts to an action of H , which is still proper.

Let $g_1, \dots, g_k$ be coset representatives for H , $B_1(1)$ the ball of radius 1 in $\mathcal{C}(G, S)$ and $B = \bigcup_{g_i} g_i B_1(1)$

Then H -translates of B cover $\mathcal{C}(G, S)$, so

the action of H on $\mathcal{C}(G, S)$ is cocompact.

So $H \underset{q.i.}{\sim} \mathcal{C}(G, S) \underset{q.i.}{\sim} G \checkmark$

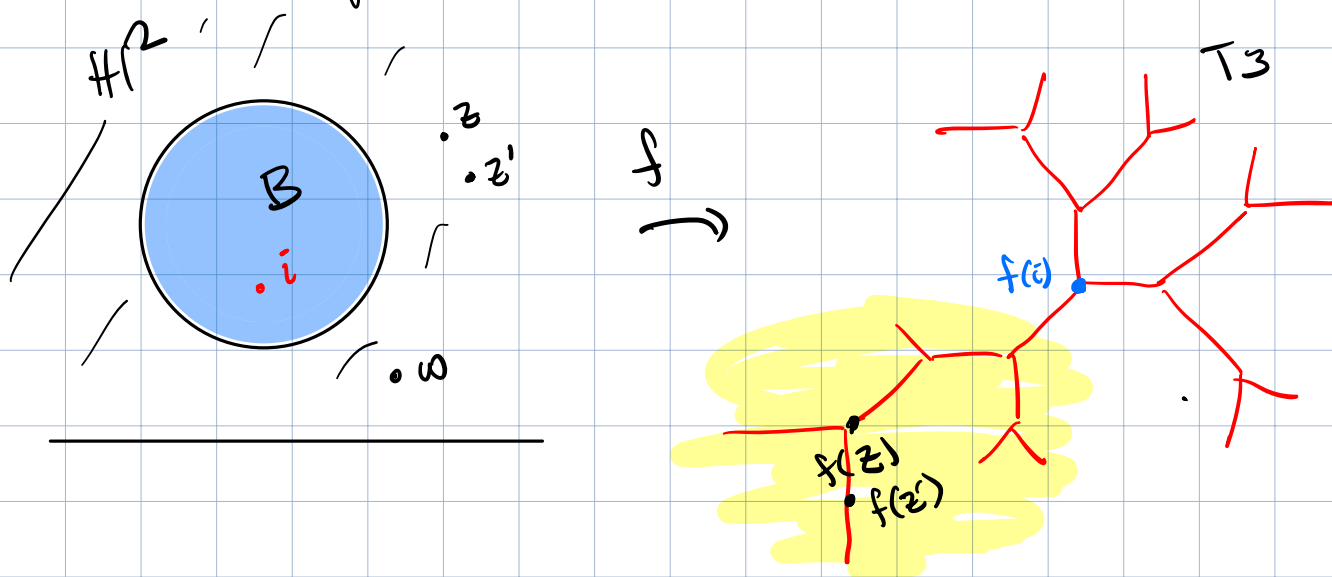
Next question: Is $SL(2, \mathbb{Z})$ quasi-isometric to $\mathbb{H}^2$?

Well $SL(2, \mathbb{Z})$ is quasi-isometric to T_3 , and

I claim T_3 is not qi to $\mathbb{H}^2$

Why?

Suppose $f: T_3 \rightarrow \mathbb{H}^2$ is a quasi-isometry.



$T_3 - f(i)$ has two or three components — call them “branches”

Idea

If z is far away from i , say outside the ball B
then $f(z)$ is far away from $f(i)$

If z' is close to z , then $f(z')$ is close to $f(z)$ —
in particular it's in the same branch

I can get from any z outside B to any w outside B in small steps staying outside B ... so $f(z)$ and $f(w)$ are in the same branch.

Every point in $f(B)$ is close to $f(i)$,
so if y is far out in a different branch,
there is no x with $f(x)$ close to y
i.e. f is not quasi-surjective. ✓

The difference between $\mathbb{H}^2$ and T_3 is that
 T_3 has many ends, $\mathbb{H}^2$ has only one end

Next we will make all of this precise.

Ends

We will define ends of a metric space,
and show that if X and Y are quasi-
isometric, then they have the same number
of ends.

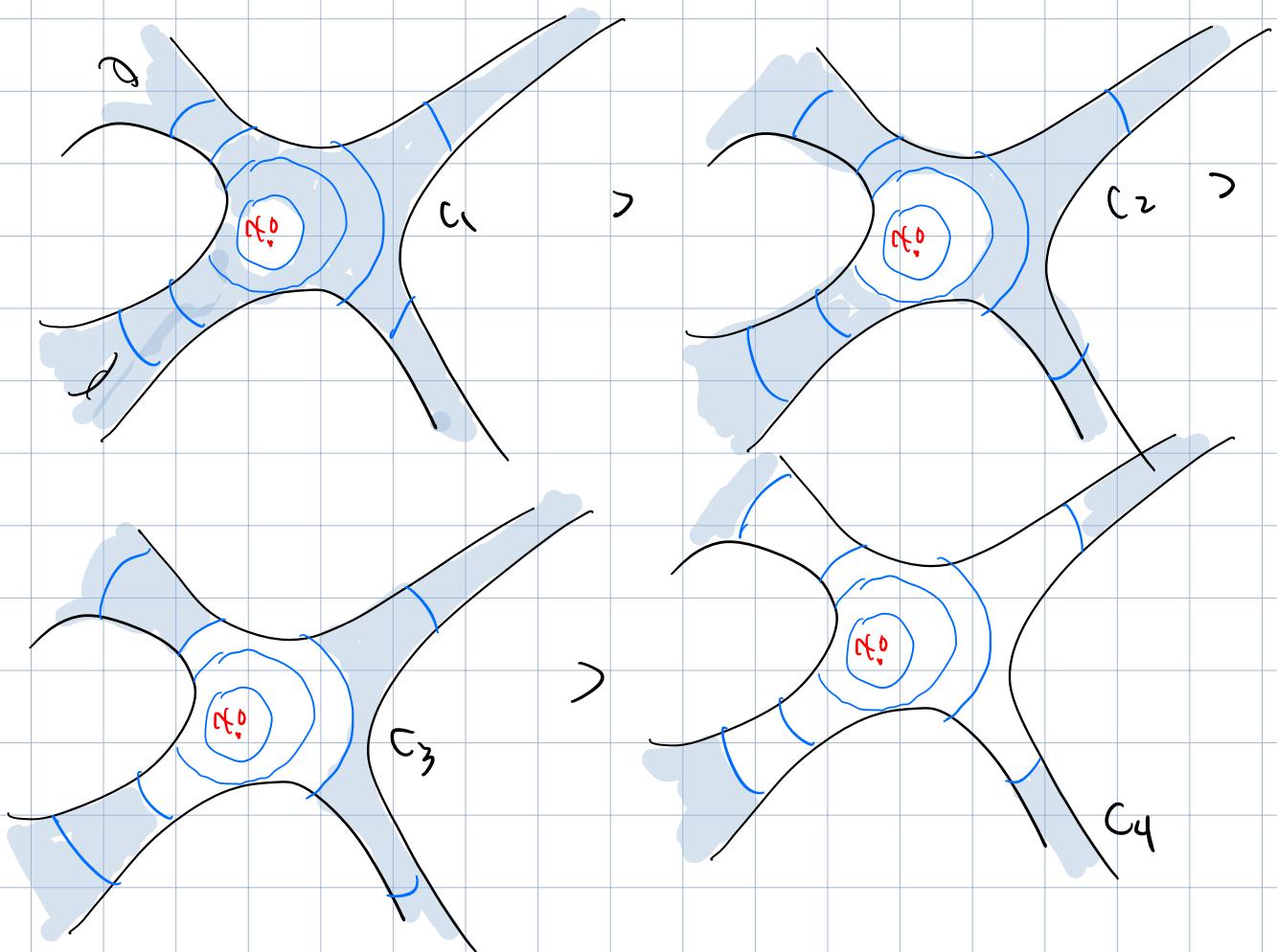
Definition let X be a proper geodesic metric space, $x_0 \in X$ and $B_n = B_n(x_0)$ the closed ball of radius n

An end of X is an infinite sequence

$$e = C_1 \supseteq C_2 \supseteq C_3 \supseteq \dots$$

where each C_n is a connected component of $X \setminus B_n$.

Note that C_n determines C_i for all $i \leq n$.



Prop: If x'_0 is another point in X ,

a sequence $e' = C'_1 \supseteq C'_2 \supseteq C'_3 \supseteq \dots$
of components of $X \setminus B_n(x'_0)$ determines
a unique end of X

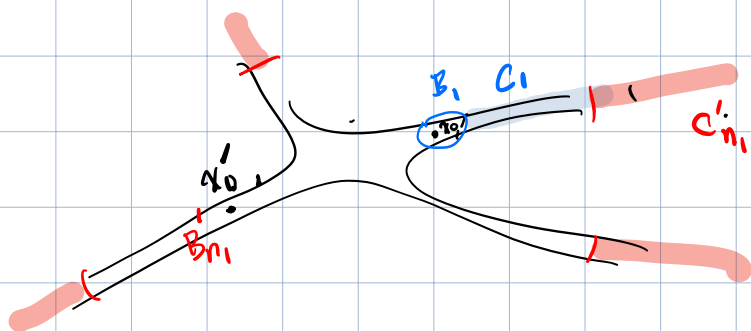
Pf

Set $B_i = B_i(x_0)$, $B'_i = B_i(x'_0)$

For any i , $\exists n_i$ s.t. $B_i \subset B'_{n_i}$.

so $X \setminus B_i \supseteq X \setminus B'_{n_i} \supseteq C'_{n_i}$

C'_{n_i} is connected, so x'_0 is in a unique
component C_i of $X \setminus B_i$.



Thus the C'_{n_i} determine the chain $C_1 \supseteq C_2 \supseteq \dots$

Corollary The number of ends of X does
not depend on the choice of x_0

Prop If X is quasi-isometric to Y ,
then X and Y have the same number of ends.

The proof is basically the same as the one I informally
explained for $X = \mathbb{H}^2$ and $Y = T_3$.

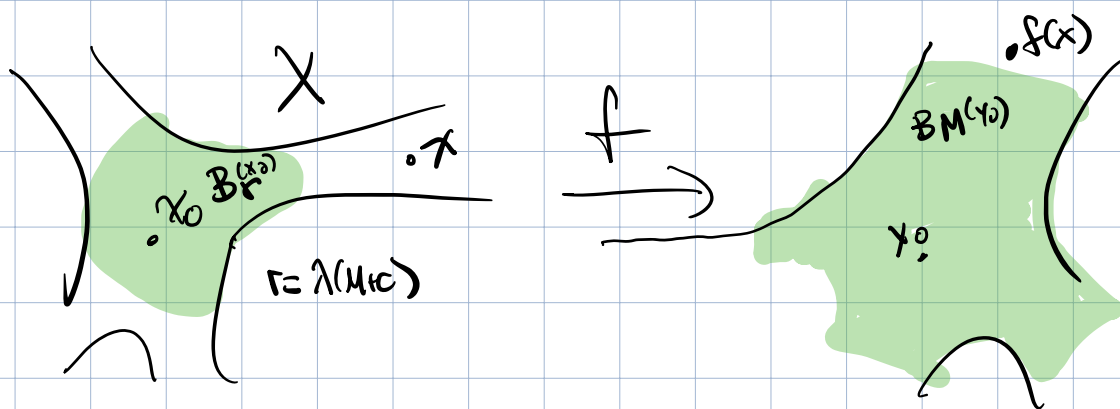
Proof Let $f: X \rightarrow Y$ be a quasi-isometry, w
 $\frac{1}{\lambda} d(x, x') - C \leq d(f(x), f(x')) \leq \lambda d(x, x') + C$

Fix $N > 0$ and $M > N + C$

Pick $x_0 \in X$, let $y_0 = f(x_0)$

Then ① $d(x, x_0) > \lambda(M + C)$

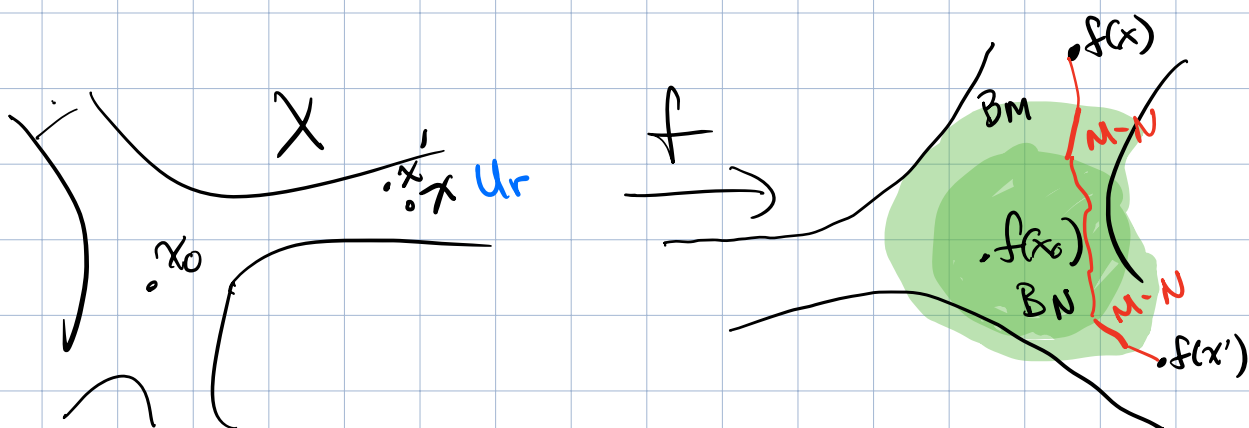
$$\Rightarrow d(f(x), y_0) \geq \frac{1}{\lambda} d(x, x_0) - C > \frac{1}{\lambda} (\lambda(M + C)) - C = M$$



and ② $d(x, x') < \frac{M - N - C}{\lambda} := \varepsilon$

$$\Rightarrow d(f(x), f(x')) < \lambda d(x, x') + C < \lambda \frac{(M - N - C)}{\lambda} + C = M - N$$

Now suppose x, x' are outside $B_r(x_0)$ and $d(x, x') < \varepsilon$. If $f(x), f(x')$ are in different components of $Y \setminus B_N(y_0)$, then $d(f(x), f(x')) > 2(M - N)$ *



So: If x, x' are in the same component C_r of $X \setminus B_r$,
 connect them by a path, divide the path into pieces
 of size $< \varepsilon$, conclude $f(x), f(x')$ are
 in the same component of $Y \setminus B_N$.

Now $f(B_r) \subset B_{r+c}(y_0)$, so we can conclude
 $\text{ends}(X) \rightarrow \text{ends}(Y)$ is surjective:

If not, can find a point y in some end of Y
 that is arbitrarily far from $f(X)$, contradicting
 the fact that f is quasi-surjective.

Similarly, $\text{ends}(Y) \rightarrow \text{ends}(X)$ is surjective,
 so either $\text{ends}(X) = \text{ends}(Y) < \infty$
 or they are both infinite.

So $\mathbb{R}$ is not gi to $\mathbb{R}^2$ (or any $\mathbb{R}^n, n \geq 2$)
 $\mathbb{Z}$ is not gi to $\mathbb{Z}^2$ (or $\mathbb{Z}^n, n \geq 2$)

$\mathbb{R}$ is not gi to T_3 (or any $T_n, n \geq 3$)
 $\mathbb{Z}$ is not gi to F_2 (or $F_n, n \geq 2$)

Q: Is $\mathbb{R}^2$ q.v. to $\mathbb{R}^3$?

A: No, but you have to use more sophisticated q.v. invariants.

Finite groups have 0 ends.

$\mathbb{Z}$ has 2 ends

$\mathbb{Z}^n$ has 1 end.

F_2 has ∞ many ends

Q: Is there a group with 3 ends?

A: No!

Theorem A finitely-generated group G has 0, 1, 2 or infinitely many ends.

proof: Suppose $\mathcal{C} = \mathcal{C}(G, S)$ has e ends, $2 < e < \infty$

$g \in G \Rightarrow g: \mathcal{C} \rightarrow \mathcal{C}$ is an isometry,

so permutes the finite number e of ends of $\mathcal{C}$

Let $N = \ker (G \longrightarrow \text{Sym}_e)$
 $g \longmapsto \sigma_g$

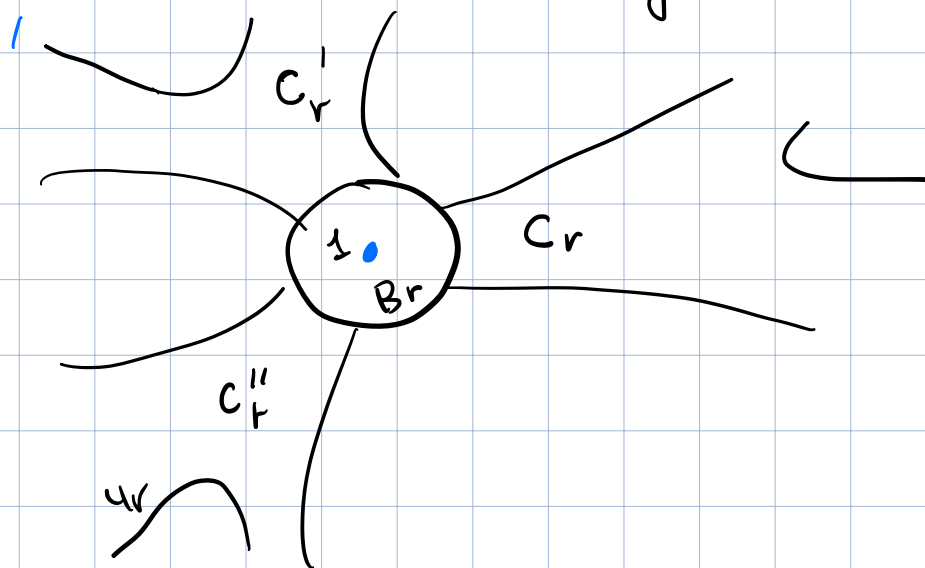
Since $e < \infty$, N has finite index in G , so is q_i to G so has the same number of ends

So, replacing G by N , we may assume G fixes the ends of $\mathcal{C}$.

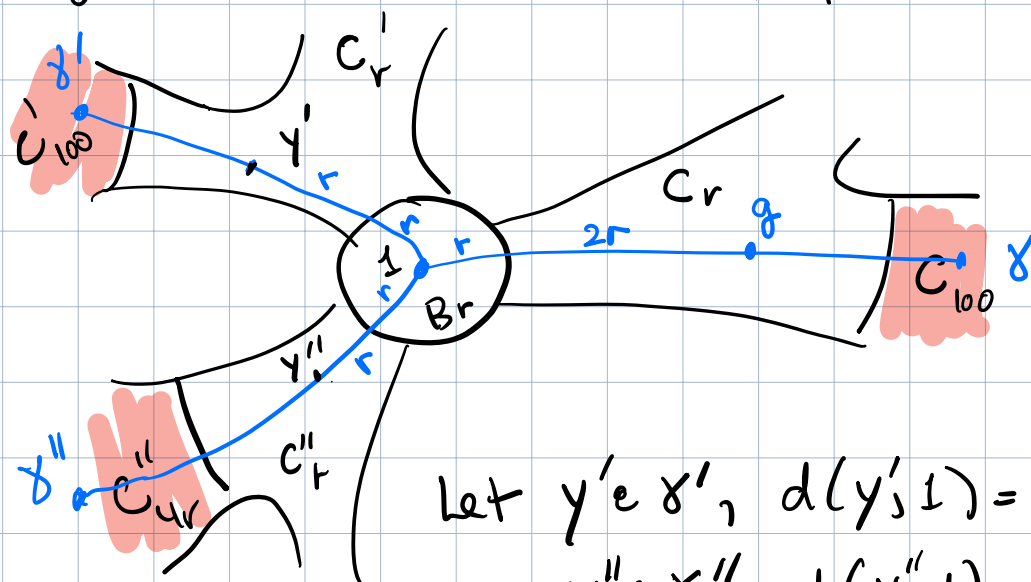
Now:

Let $\mathcal{C} = C_1 > C_2 > \dots$ be 3 different ends;
 $\mathcal{C}' = C'_1 > C'_2 > \dots$
 $\mathcal{C}'' = C''_1 > C''_2 > \dots$ (C_i, C'_i, C''_i = components of $\mathcal{C} \setminus B_i(1)$)

Then for some r , C_r, C'_r and C''_r are different components of $X \setminus B_r(1)$



Let γ be a geodesic from 1 to a vertex in C_{100}
 γ' 1 to a vertex in C'_{100}
 γ'' 1 to a vertex in C''_{100}



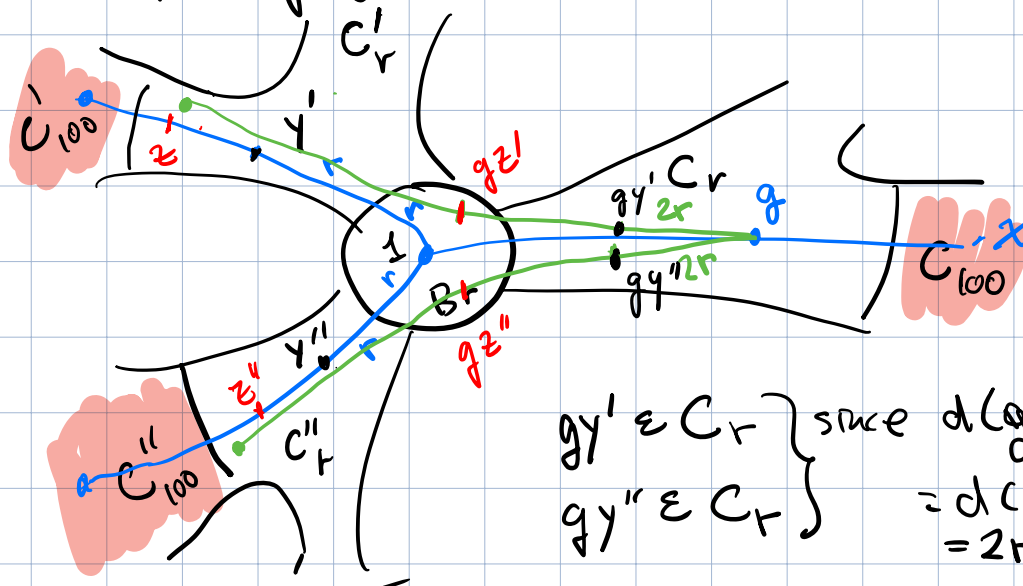
Let $y' \in \gamma'$, $d(y', 1) = 2r$
 $y'' \in \gamma''$, $d(y'', 1) = 2r$

Then $z' \in \gamma'$, $d(z', 1) > 2r$
 $z'' \in \gamma''$, $d(z'', 1) > 2r$ } $\Rightarrow d(z', z'') > 2r$

Now let $g \in \gamma$, $d(1, g) = 3r$

Act on this picture by g : Since g fixes ends

- the endpoint of $g\gamma'$ is still in C'_r
- the endpoint of $g\gamma''$ is still in C_r



$gy' \in C_r$
 $gy'' \in C_r$ } since $d(gy', g) = d(y', 1) = 2r$
 $= d(y', 1) = 2r$

So $\exists z'$ on γ' , z'' on γ''
with gz', gz'' both in $B_r(1)$
so $d(gz', gz'') < 2r$

but $d(gz', gz'') = d(z, z') > 2r$ since
 $d(z', B_r), d(z'', B_r) > r$. $\times$

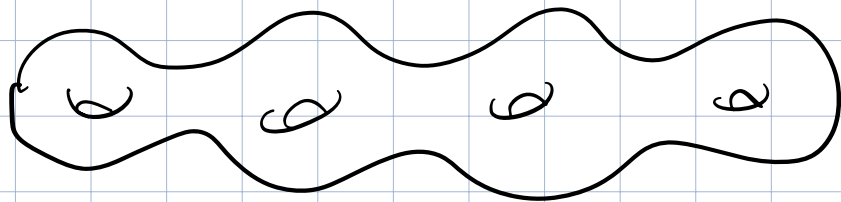
Next question: $\mathbb{H}^2$ has one end.

We showed $SL(2, \mathbb{Z})$ has ∞ many ends, so
is not q.i. to $\mathbb{H}^2$

Is there a group quasi-isometric
to $\mathbb{H}^2$?

(A: yes)

Definition A surface group is the fundamental
group of a closed orientable surface
of genus $g \geq 2$.



$\mathbb{H} = \{z \mid \text{Im}(z) > 0\}$ with the metric $\frac{ds}{y} = \sqrt{dx^2 + dy^2}/y$ is one model for the hyperbolic plane.

Another model is the Poincaré disk model $\mathbb{D}$.

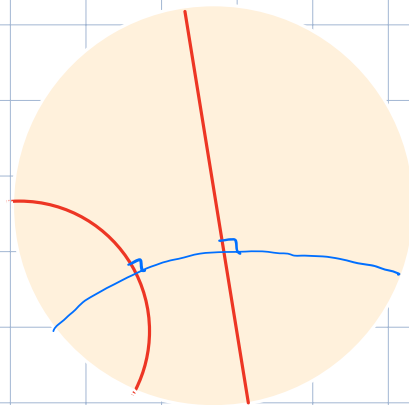
This is the interior of the unit disk in $\mathbb{R}^2$ with the metric $\frac{2ds}{1-r^2}$.

The map

$$\begin{aligned} f: (\mathbb{H}, \frac{ds}{y}) &\longrightarrow (\mathbb{D}, \frac{ds}{1-r^2}) \\ z &\longmapsto \frac{z-i}{z+i} \end{aligned}$$

is an isometry.

Geodesics in $\mathbb{D}$ are
circle-arcs $\perp$ to S^1
and straight lines
through the origin

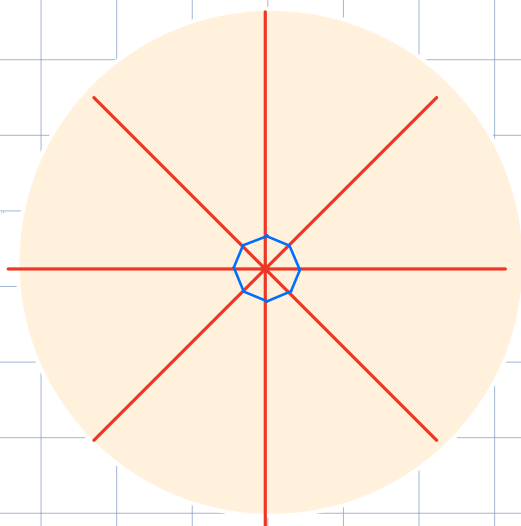
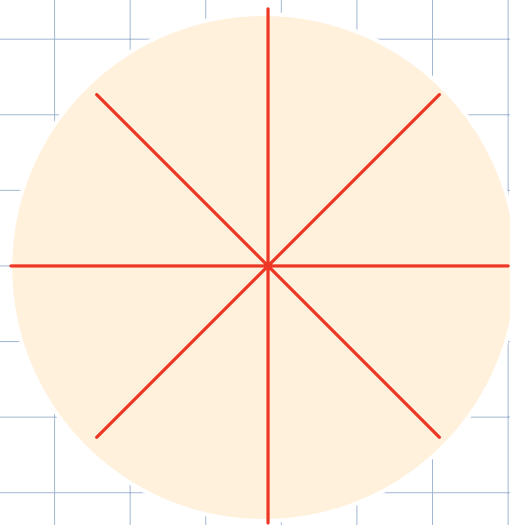


As before, isometries are generated by inversions in circles,
and there is an orientation-preserving isometry taking any geodesic
to any other geodesic, and any point to any other point.
(= translation along the unique geodesic
orthogonal to both)

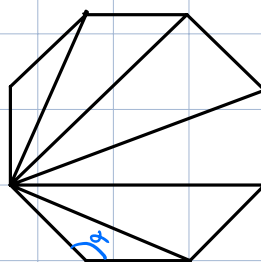
It is easy to see that for $n \geq 2$
 $\mathbb{D}$ contains a regular $4n$ -gon
 with all angles $\frac{\pi}{n}$.

Picture for $n=4$:

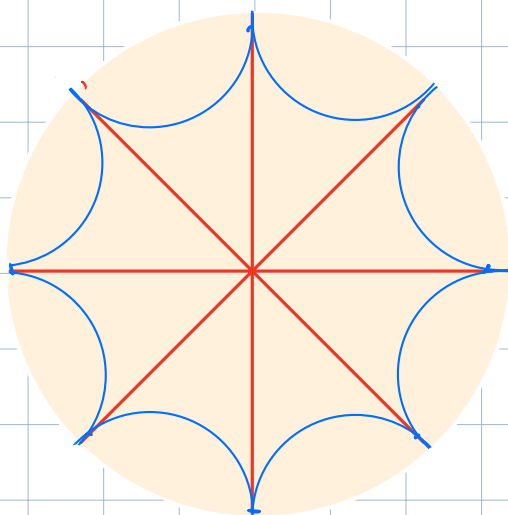
take points on these rays
 at distance r from O



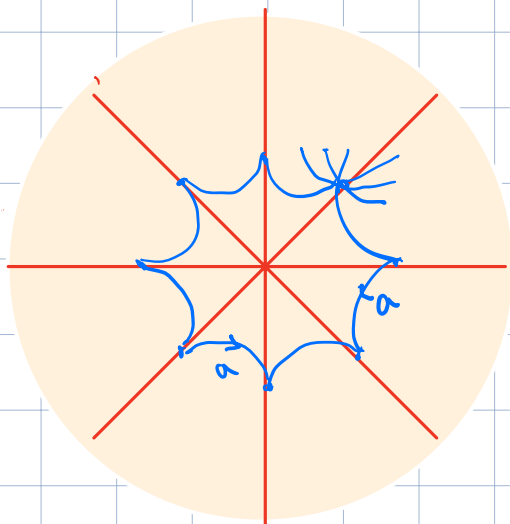
If r is small, $\frac{ds}{1-r^2}$ is
 almost ds , the octagon
 is almost Euclidean, so
 has angles almost $\frac{3\pi}{4}$



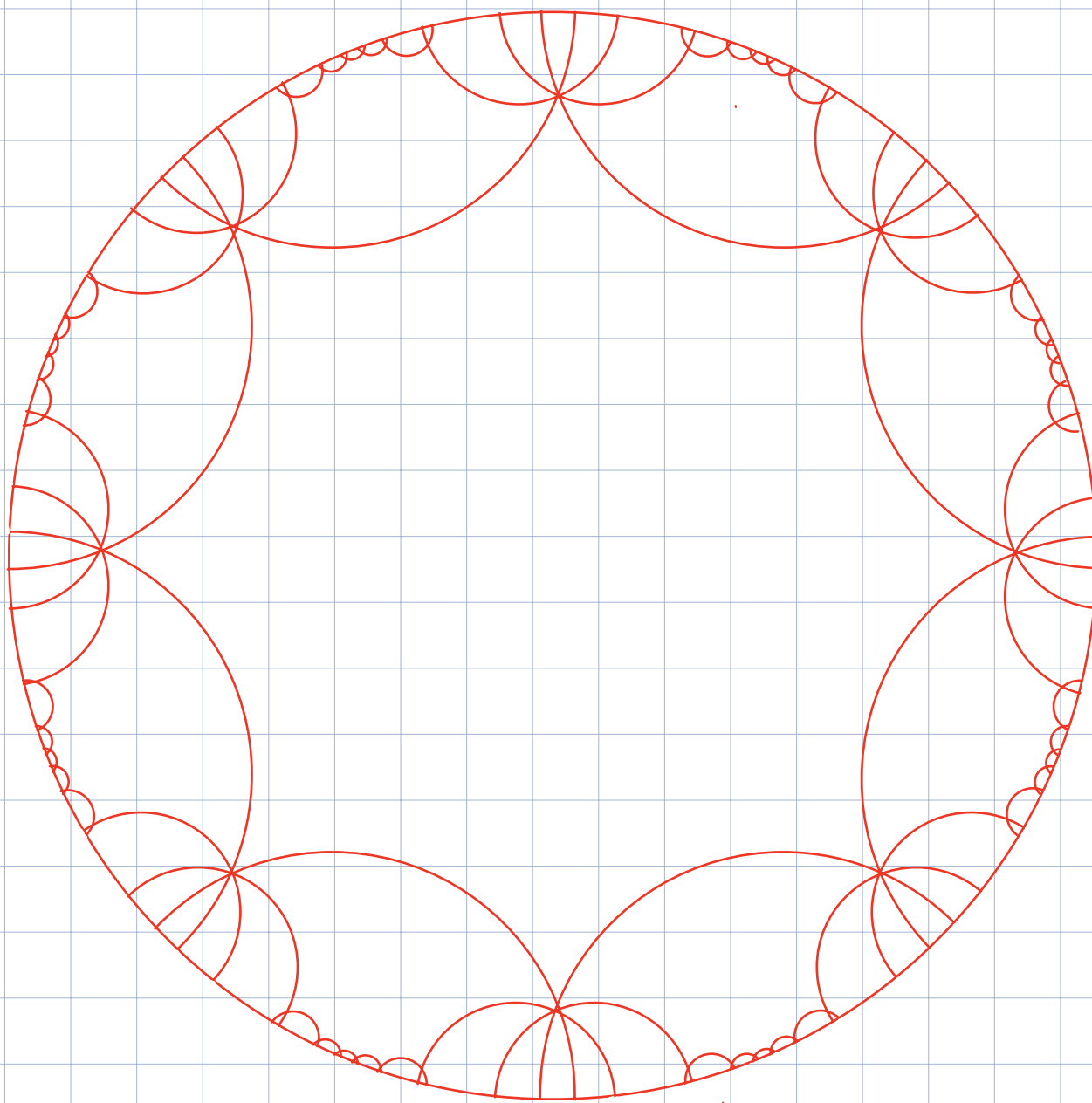
$$\begin{aligned} & \text{in } \mathbb{R}^2, \\ & 6 \cdot \pi = 8 \cdot \alpha, \text{ so} \\ & \alpha = \frac{3\pi}{4} \end{aligned}$$



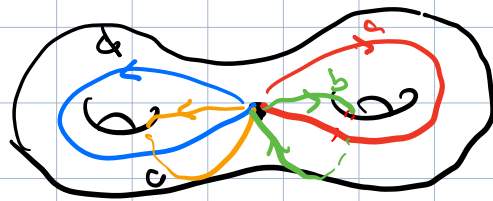
If r is close to 1, the angles
 are almost 0



So somewhere in between they
 are $\frac{\pi}{4}$. So 8 octagons fit
 around each vertex :

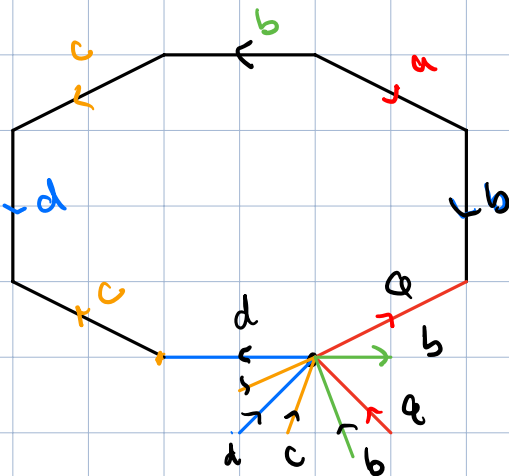


Let Σ_2 be the closed orientable surface of genus 2:



The loops a, b, c, d generate $\pi_1(\Sigma_2, b)$

The universal cover of Σ_2 is a non-compact simply-connected surface, so homeomorphic to the plane; the pre-image of the colored loops cut the surface into octagons, 8 around each vertex

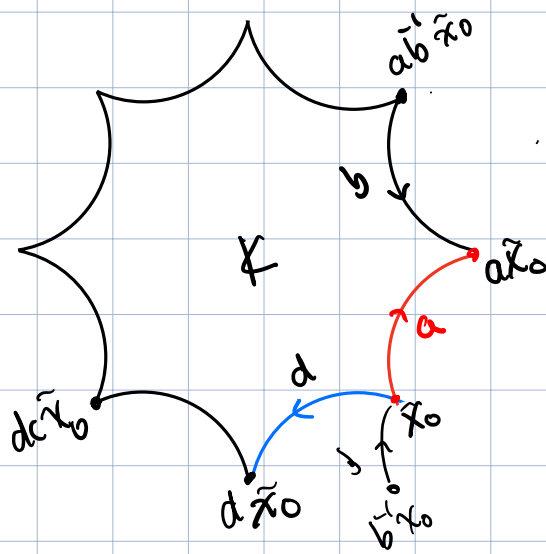


$\pi_1(\Sigma_2)$ acts freely on $\tilde{\Sigma}_2$ by deck transformations

We saw we can tile the hyperbolic plane $\mathbb{H}$ by regular octagons with dihedral angle $\frac{\pi}{4}$,

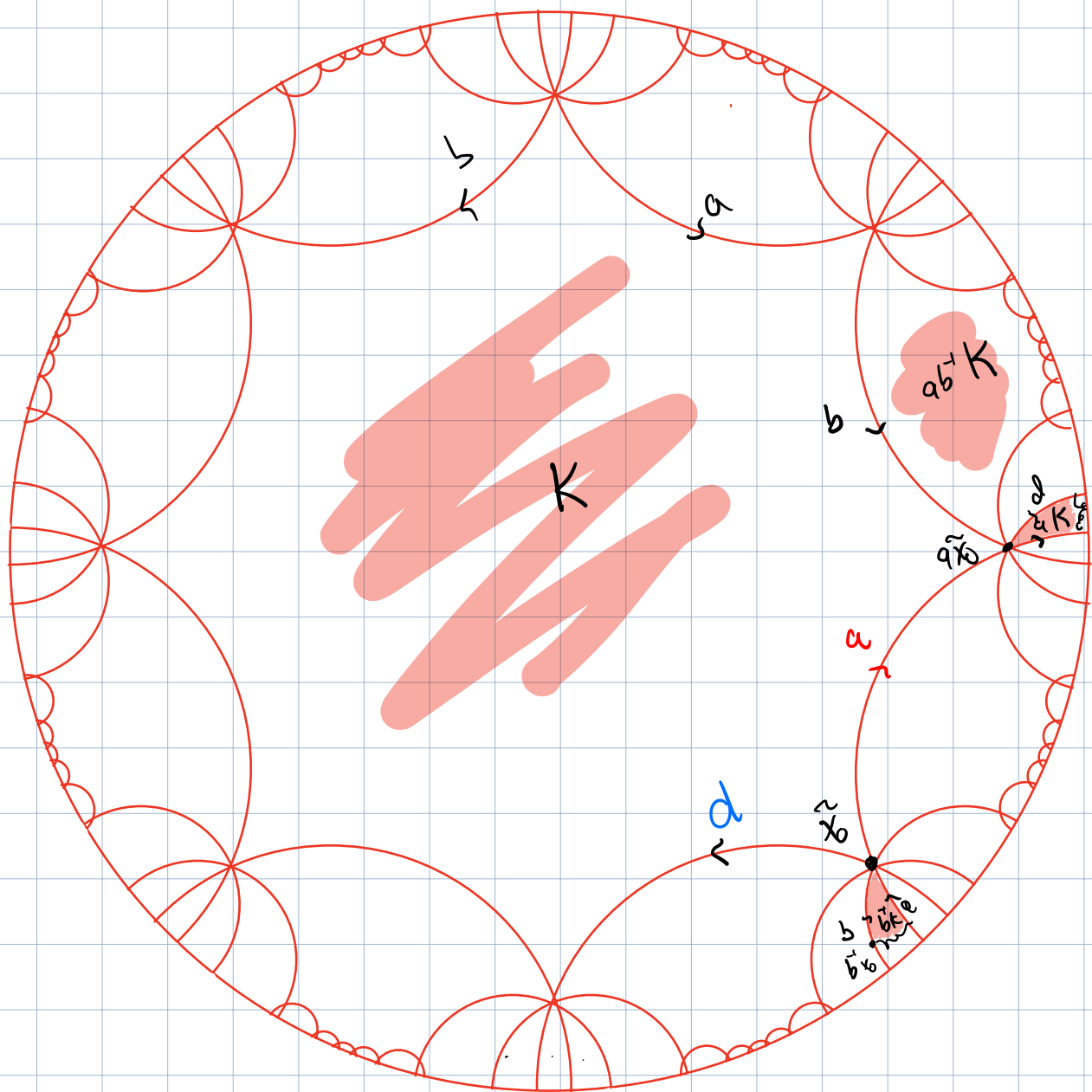
So we can identify $\tilde{\Sigma}_2$ with $\mathbb{D}$, and

Each generator of $\pi_1 \tilde{\Sigma}_2$ acts by
an isometry



so all of $\pi_1 \tilde{\Sigma}_2$
acts by isometries

So $\pi_1 \tilde{\Sigma}_2$ acts freely and cocompactly
on $\mathbb{D}$ by isometries.



There's nothing special about genus 2 -
 You can find a regular $4g$ -gon in

$\mathbb{D}$ with all angles $\frac{2\pi}{4g}$, and identify $\tilde{\Sigma}_g$

with $\mathbb{D}$ tiled by these.

So $\pi_1(\Sigma_2) \cong \pi_1(\mathbb{D}) \cong \pi_1(\Sigma_3) \cong \pi_1(\Sigma_4) \cong \dots$

Max Dehn noticed this around 1910. He used the geometry of $\mathbb{D}$ to prove interesting facts about fundamental groups of surfaces ... eg they contain free subgroups, and never contain free abelian subgroups of rank 2.