

Central limit theorems for adaptive MCMC: some old and new results

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(Based partly on joint work with Gersende Fort)

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Introduction

Markov Chain Monte Carlo (MCMC) is a popular tool for Monte Carlo simulations.

- $(\mathcal{X}, \mathcal{B}, \lambda)$ a meas. space. Want to sample from $\pi(x)\lambda(dx)$.
- MCMC: a recipe to construct ergodic Markov chains $\{X_n, n \geq 0\}$ with state space $(\mathcal{X}, \mathcal{B})$ and with invariant distribution π .

Introduction

- Central limit theorems play an important role in MCMC.
 - 1 Quantify uncertainty in MCMC estimates.
 - 2 Comparing algorithms.
 - 3 Serving as a stopping rule.
- There are many CLT for Markov chains (See e.g. G. Jones' review).

Introduction

- Adaptive MCMC: you update the transition kernel (TK) of the sampler as it runs.
- Can be used to improve performances in a variety of situations. Can be useful for MCMC softwares.
- What do we know about central limit theorems for adaptive MCMC?

Introduction

Outline

- CLT for fixed-target AMCMC
- CLT for the Equi-Energy sampler

Fixed-target AMCMC

A large class of adaptive MCMC algorithms can be described as follows.

- Given π on $(\mathcal{X}, \mathcal{B}, \lambda)$, let $\{P_\theta, \theta \in \Theta\}$ a family of TK. P_θ is inv. wrt π for all $\theta \in \Theta$.
- Define some optimality criterion.

Definition

An adaptive Markov chain is a random process $\{(X_n, \theta_n), \mathcal{F}_n, n \geq 0\}$ such that

$$X_{n+1} | \mathcal{F}_n \sim P_{\theta_n}(X_n, \cdot), \quad \text{and } \theta_{n+1} \in \mathcal{F}_{n+1}.$$

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Many possibilities for the optimality criterion.

- Maximize the square-jump distance as in the example (Prasarica & Gelman (2005), Andrieu & Robert (2001)).
- Target a given acceptance rate Andrieu & Robert (2001)), (Atchade & Rosenthal (2005)).
- Moment matching (Haario et al. (2001)).
- Minimize the Kulback-Leibler between the proposal and the target (Andrieu & Moulines (2005), Holden et al. (2009), Giordani & Kohn (2008)).

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$$X_{n+1} | \mathcal{F}_n \sim P_{\theta_n}(X_n, \cdot), \quad \text{and} \quad \theta_{n+1} = \theta_n + \gamma_n H(\theta_n, X_{n+1}).$$

Objectives: We want conditions under which $n^{-1/2} \sum_{k=1}^n \bar{f}(X_k) \Rightarrow Z$,
 $\bar{f} = f - \pi(f)$.

Definition

$$D_\beta(\theta, \theta') := \sup_{x \in \mathcal{X}} \sup_{|f|_{V^\beta} \leq 1} \frac{|P_\theta f(x) - P_{\theta'} f(x)|}{V^\beta(x)}.$$

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Theorem (Andrieu-Moulines (2005))

Assume

(A1) P_θ is invariant wrt π , ϕ -irreducible, aperiodic and there exist a 1-small set C , $V : \mathcal{X} \rightarrow [1, +\infty)$, $\lambda \in (0, 1)$ and constants b such that for any $\theta \in \Theta$, $P_\theta V \leq \lambda V + b \mathbf{1}_C$.

(A2) $D_\beta(\theta, \theta') \leq C|\theta - \theta'|$, $\theta, \theta' \in \Theta$.

(A3) $\gamma_n = O(n^{-1})$ and $\sup_{\theta \in \Theta} |H(\theta, \cdot)|_{V^\alpha} < \infty$.

(A4) $|\theta_n - \theta_*| \xrightarrow{Prob} 0$.

Then for $|f|_{V^\alpha} < \infty$ ($2\beta + \alpha < 1$), $n^{-1/2} \sum_{k=1}^n \tilde{f}(X_k) \Rightarrow N(0, \sigma^2(f))$ where

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There are many MCMC algorithms that are not geometrically ergodic.

1 If

$$\int e^{s|x|} \pi(dx) = \infty, \quad \text{for all } s > 0$$

the Random Walk Metropolis algorithm cannot be geometrically ergodic. (Jarner & Tweedie (2001)).

2 If $\liminf_{|x| \rightarrow \infty} \frac{|\nabla \log \pi(x)|}{|x|} = \infty$ or $\liminf_{|x| \rightarrow \infty} |\nabla \log \pi(x)| = 0$, then the Metropolis Adjusted Langevin algorithm cannot be geometrically ergodic. (Roberts & Tweedie (1996)).

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Practical consequence:

In a MCMC simulation problem where uniform drift condition of the form

$$P_\theta V(x) \leq V(x) - \phi \circ V(x) + b\mathbf{1}_C(x)$$

is available, we recommend adaptive MCMC.

- In such cases, AMCMC algorithms are very stable.
- When good ideas are available on how to adapt, AMCMC perform better than plain MCMC.

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A quick comment on the proof:

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- Let $\{Z_n\}$ be a Markov chain with t.k. P and inv. dist. π . Let f s.t. $\pi(f) = 0$. Notation: $Pf(x) := \int P(x, dy)f(y)$.
- Suppose that

$$g = \sum_{k=0}^{\infty} P^k f,$$

exists. Then

$$g(x) - Pg(x) = f(x).$$

- We can use g to approximate partial sum of Markov chains by martingales.

Fixed-target AMCMC

In the non-geometric case, solutions to the Poisson equation are hard to work with.

- If $PV \leq V - \chi + b\mathbf{1}_C \Rightarrow f \leq \chi$ implies $|g| \leq V$.
- If $P_\theta V \leq V - V^{1-\alpha} + b\mathbf{1}_C \Rightarrow$ for $|f| \leq V^\beta$, $|g| \leq V^{\beta+\alpha}$.

$$g_\theta - g_{\theta'} = \sum_{j \geq 0} P_\theta^j \circ (P_\theta - P_{\theta'}) \circ \sum_{j \geq 0} P_{\theta'}^j f(x).$$

So that

$$|g_\theta - g_{\theta'}| \leq V^{\beta+2\alpha}.$$

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The solution is to work with $H(x, y) = g(y) - Pg(x)$.

Theorem (Maxwell-Woodroffe (2000))

Define $V_n(f) = \left\| \sum_{k=0}^{n-1} P^k f \right\|_{L^2(\pi)}$. If

$$\sum_{k \geq 0} n^{-3/2} V_n(f) < \infty,$$

Then $H_n(x, y) = \sum_{j=0}^{n-1} P^j f(y) - \sum_{j=0}^n P^j f(x)$ converges to a limit H ($H = g(y) - Pg(x)$) in $L^2(\pi \times P)$.

Kipnis-Varadhan (1986) has a similar result for reversible chains.

Fixed-target AMCMC

Proposition

Assume $P_\theta V \leq V - V^{1-\alpha} + b\mathbf{1}_C$. For $f \in L_{V^\beta}$, $\beta \in [0, 1 - 2\alpha)$, define $H_\theta(x, y) = g_\theta(y) - P_\theta g_\theta(x)$.

$$\sup_{x,y} \frac{|H_\theta(x, y) - H_{\theta'}(x, y)|}{V^{\beta+\alpha\kappa}(x) + V^{\beta+\alpha\kappa}(y)} \leq C|\theta - \theta'|.$$

for any $\kappa > 1$.

Equi-Energy sampler

- 1 Let us now consider another class of adaptive MCMC where the transition kernels do not all have the same invariant dist.
- 2 There are actually many such algorithms (Equi-Energy sampler, Wang-Landau, SAMC...).
- 3 We focus on the Equi-Energy sampler (EE).

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Let $\bar{\pi}$ a prob. meas. that is equivalent to π and $\omega(x) = \pi(dx)/\bar{\pi}(dx)$.

Let P with inv. dist. π . Define

$$\alpha(x, y) = \min \left(1, \frac{\omega(y)}{\omega(x)} \right).$$

For $\varepsilon \in (0, 1)$ and $\theta \in \Theta$ a prob. meas. define

$$P_\theta(x, A) = (1-\varepsilon)P(x, A) + \varepsilon \int \theta(dz) [\alpha(x, z)\mathbf{1}_A(z) + (1 - \alpha(x, z))\mathbf{1}_A(x)].$$

Key insight of Equi-Energy:

- (i) $P_{\bar{\pi}}(x, A)$ is invariant with respect to π .
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Implementation: take $\bar{\pi} = \pi^\gamma$, $\gamma \in (0, 1)$. Let \bar{P} with inv. dist. $\bar{\pi}$. Run the joint process $\{(\bar{X}_n, X_n, \theta_n), n \geq 0\}$ as follows.

Algorithm

Given $\sigma\{(\bar{X}_k, X_k, \theta_k), k \leq n\}$



$$\bar{X}_{n+1} \sim \bar{P}(\bar{X}_n, \cdot), \quad X_{n+1} \sim P_{\theta_n}(X_n, \cdot),$$



$$\theta_{n+1} = (n+1)^{-1} \sum_{k=1}^{n+1} \delta_{\bar{X}_k}$$

As $n \rightarrow \infty$, P_{θ_n} should converge to $P_{\bar{\pi}}$.

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Fix f with $\pi(f) = 0$. Let U that satisfies the Poisson equation
 $U - P_{\bar{\pi}}U = f$. Define $S_n = \sum_{k=1}^n f(X_k)$

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Equi-Energy sampler

Suppose that \mathcal{X} is finite. Then

$$\left(\frac{1}{\sqrt{n}} \sum_{l=1}^n H_x(\bar{X}_l) \right)_x \Rightarrow G,$$

where G is a Gaussian r.v with zero mean and covariance

$$\Gamma(x, y) = \int [U_x(z)U_y(z) - (\bar{P}U_x(z)) (\bar{P}U_y(z))] \bar{\pi}(dz),$$

Then

$$\frac{1}{\sqrt{n}} S_n = \frac{1}{\sqrt{n}} M_n + 2\varepsilon \frac{1}{n} \sum_{k=1}^n G(X_k) + o_P(1).$$

Equi-Energy sampler

Theorem

Suppose that \mathcal{X} is finite and \bar{P} and P are ergodic. Let $f : \mathcal{X} \rightarrow \mathbb{R}$ be bounded.

$$\frac{1}{\sqrt{n}} \sum_{k=1}^n f(X_k) \Rightarrow Z + 2\varepsilon \sum_{x \in \mathcal{X}} \pi(x) G(x) \quad \text{as } n \rightarrow \infty, \quad (1)$$

where Z and $\sum_{x \in \mathcal{X}} \pi(x) G(x)$ are independent random variables and $Z \sim N(0, \sigma_*^2(f))$, with $\sigma_*^2(f) := \pi(f^2) + 2 \sum_{k=1}^{\infty} \int_{\mathcal{X}} \pi(dx) f(x) P_{\bar{\pi}}^k f(x)$

Equi-Energy sampler

If \mathcal{X} is not finite, we need empirical process theory for Markov chains (uniform CLT for Markov chains). Suppose that:

- 1 \mathcal{X} is compact \bar{P} and P are uniformly geometrically ergodic.
- 2 Suppose that a uniform CLT over the class $\{H_x, x \in \mathcal{X}\}$ hold for the Markov chain $\{\bar{X}_n, n \geq 0\}$.

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Equi-Energy sampler

Theorem

Assume the above. Let $f : \mathcal{X} \rightarrow \mathbb{R}$ a bounded meas. function.

$$\frac{1}{\sqrt{n}} \sum_{k=1}^n f(X_k) \Rightarrow Z + 2\varepsilon \int \pi(dx) G(x) \quad \text{as } n \rightarrow \infty, \quad (2)$$

where Z is as above and G is a zero-mean Gaussian process on \mathcal{X} with covariance function

$$\Gamma(x, y) = \int [U_x(z)U_y(z) - (\bar{P}U_x(z)) (\bar{P}U_y(z))] \bar{\pi}(dz),$$

Equi-Energy sampler

Practical implications:

- 1 In the EE sampler (and more generally for adaptive MCMC with varying invariant distributions) you pay the price of the adaptation.
- 2 For small problems, the cost of the adaptation (the term $2\varepsilon \int \pi(dx)G(x)$) can make the algorithm inefficient compared with simpler MCMC sampler.
- 3 To minimize the cost of the adaptation, ε should be kept small.

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