

# Error Analysis of an Evolution Equation for Microstructure

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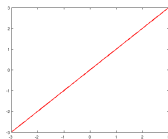
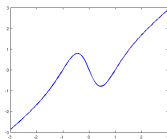


Consider the problem

$$\begin{aligned} \Delta u_t + \operatorname{div}(\sigma(\nabla u)) &= 0 && \text{in } \Omega = (0, 1)^2 \\ u &= 0 && \text{on } \partial\Omega \\ u &= u_0 && \text{when } t = 0 \end{aligned}$$

$\sigma = DW$  where  $W$  is a double well potential such that  $\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  globally Lipschitz, and  $\sigma(p) \cdot p \geq c|p|^2 - d$  for  $c > 0$ ,  $d \geq 0$ .

For example,  $W(\nabla u) = \frac{1}{2} \frac{1}{u_x^2 + 1} (u_x^2 - 1)^2 + \frac{1}{2} u_y^2$ .

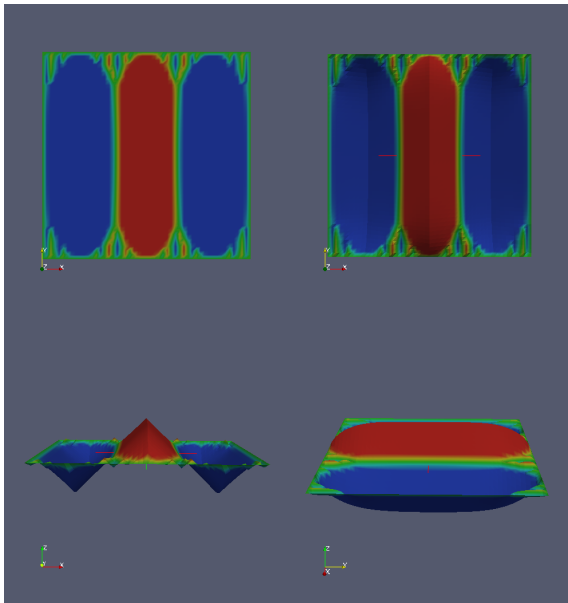


This problem is the  $H_0^1(\Omega)$  gradient flow of  $I(u) := \int_{\Omega} W(\nabla u) dx$ .  
i.e.

$$u_t = -\nabla I(u) \quad \text{in } H_0^1(\Omega).$$

The direction chosen by the dynamics is the direction of steepest descent.

In our example, the solution would like to satisfy  $u_x = \pm 1$ ,  $u_y = 0$ .



# Questions

- ▶ What can we say about the long-time behaviour of solutions and the appearance of microstructure?
- ▶ Is microstructure a numerical artifact and can we approximate the solution with FEM?

## What can we prove?

Rewrite as

$$u_t = F(u) \quad \text{in } H_0^1(\Omega)$$

where  $F(u) := -\Delta^{-1} \operatorname{div}(\sigma(\nabla u))$ .  $F : H_0^1(\Omega) \rightarrow H_0^1(\Omega)$  is Lipschitz

Standard theory and energy estimates (eg. Henry and Temam)  $\Rightarrow$   
 $\exists!$  solution

$$u(t) = u_0 + \int_0^t F(u(s)) ds,$$

$u \in C([0, \infty), H_0^1(\Omega)) \cap L^\infty([0, \infty), H_0^1(\Omega))$ ,  
 $u_t \in C((0, \infty), H_0^1(\Omega)) \cap L^\infty((0, \infty), H_0^1(\Omega))$  (both Lipschitz), and

$$\int_\Omega W(\nabla u(t)) dx + \int_0^t \|\nabla u_s(s)\|_{L^2(\Omega)}^2 ds = \text{const.} \quad t \geq 0,$$

$\Rightarrow u_t \in L^2((0, \infty), H_0^1(\Omega))$  and  $u_t \rightarrow 0$  in  $H_0^1(\Omega)$  as  $t \rightarrow \infty$ .

## What can't we prove?

- ▶ No additional regularity or compactness (only  $H_0^1(\Omega)$ ) . This limits what we can say about the long-time behaviour of solutions.  $\|u(t)\|_{H^1(\Omega)} \leq C$  for all  $t \geq 0$  only implies weak convergence.
- ▶ **Question remains:** Are all solutions minimising sequences for  $\int_{\Omega} W(\nabla u(x))dx$ , or are some solutions attracted to rest points, for which  $\int_{\Omega} W(\nabla u(x))dx > 0$ ?

# Numerics?

Can we approximate the solution with FEM?

Up to finite time it is possible to prove that  $u_h \rightarrow u$  in  $H_0^1(\Omega)$  as  $h \rightarrow 0$  but we do not get a rate of convergence (due to lack of additional regularity).

Modify problem to create additional regularity...



## Regularized Problem

Consider the problem

$$\begin{aligned}\Delta u_t - \epsilon \Delta^2 u + \operatorname{div}(\sigma(\nabla u)) &= 0 && \text{in } \Omega = (0, 1)^2 \\ \Delta u = u &= 0 && \text{on } \partial\Omega \\ u &= u_0 \in H_0^1(\Omega) && \text{at } t = 0.\end{aligned}$$

Rewrite as

$$u_t - \epsilon \Delta u = F(u) \quad \text{in } H_0^1(\Omega)$$

$$F(u) := -\Delta^{-1} \operatorname{div}(\sigma(\nabla u)).$$

In the gradient flow representation the additional term is bending energy

$$I(u) = \int_{\Omega} W(\nabla u) + \frac{\epsilon}{2}(\Delta u)^2.$$

Using same techniques as before we can prove similar results, e.g.  
 $\exists!$  solution  $u \in C([0, \infty), H_0^1(\Omega)) \cap C((0, \infty), V)$

$$u(t) = e^{\epsilon \Delta t} u_0 + \int_0^t e^{\epsilon \Delta(t-s)} F(u(s)) ds$$

and ...

$$(V := \{v \in H_0^1(\Omega) : \Delta v \in H_0^1(\Omega)\}).$$

... it is also possible to prove that

$$\begin{aligned}\|u\|_{H^1} &\leq C \quad t \in [0, \infty) \\ \|u\|_{H^2} &\leq \begin{cases} C\epsilon^{-1/2}t^{-1/2} & t \in (0, T] \\ C\epsilon^{-1/2} & t \in (T, \infty) \end{cases} \\ \|u_t\|_{H^1} &\leq \begin{cases} Ct^{-1} & t \in (0, T] \\ C & t \in (T, \infty) \end{cases}\end{aligned}$$

... and other results eg. higher regularity,  $\exists$  Lyapunov function,  $u_t \rightarrow 0$  in  $H^1$ ,  $\exists$  compact attractor of finite dimension...

## Semi-discrete Problem

$V_h \subset H_0^1(\Omega)$ . Define  $\Delta_h : V_h \rightarrow V_h$

$$(\Delta_h u_h, \phi_h)_{L^2} = -(\nabla u_h, \nabla \phi_h)_{L^2} \quad \forall u_h, \phi_h \in V_h.$$

Also define elliptic projection operator  $R = R(h)$  and  $L^2$  projection operator  $P = P(h)$  by

$$\begin{aligned} (\nabla(Ru - u), \nabla \phi_h)_{L^2} &= 0 & \forall \phi_h \in V_h, u \in H_0^1(\Omega) \\ (Pu - u, \phi_h)_{L^2} &= 0 & \forall \phi_h \in V_h, u \in H_0^1(\Omega). \end{aligned}$$

We have  $\Delta_h R = P \Delta$ . Assume

$$\begin{aligned} \|u - Ru\|_{L^2} + h\|u - Ru\|_{H^1} &\lesssim h^s \|u\|_{H^s} \\ \|u - Pu\|_{L^2} + h\|u - Pu\|_{H^1} &\lesssim h^s \|u\|_{H^s} \quad s = 1, 2. \end{aligned}$$

Apply the Galerkin method: Find  $u_h \in C([0, \infty), V_h)$  such that  $u = u_{0h} := Ru_0$  at  $t = 0$  and

$$u_{h,t} - \epsilon \Delta_h u_h = F_h(u_h) \quad \text{in } V_h \text{ for } t > 0$$

where  $F_h(u_h) := RF(u_h) = -\Delta_h^{-1} \operatorname{div}(\sigma(\nabla u_h))$ .

Same theory  $\Rightarrow \exists!$  solution  $u_h$  such that

$$u_h(t) = e^{\epsilon \Delta_h t} u_{0h} + \int_0^t e^{\epsilon \Delta_h (t-s)} F_h(u_h(s)) ds$$

Same regularity results as before (except  $H^2$  norm replaced with  $\|\Delta_h u_h\|_{L^2}$ ).

## Error Analysis

To analyse the error we follow standard theory (eg. Larsson for short time error), but pay particular attention to the dependence on  $\epsilon$ ,

to show that

$$\|u_h - u\|_{H^1} \lesssim h\epsilon^{-1/2}t^{-1/2} \quad t \in (0, T].$$

Split the error into 2 parts

$$e = u_h - u = \underbrace{u_h - Ru}_{\theta(t) \in V_h} + \underbrace{Ru - u}_{\rho(t)}.$$

$\rho(t)$  is just the elliptic projection error,

$$\|\rho(t)\|_{H^1} \lesssim h \|u(t)\|_{H^2} \lesssim h \epsilon^{-1/2} t^{-1/2} \quad \text{for } t \in (0, T].$$

$\theta(t)$  satisfies the following equation,

$$\theta_t - \epsilon \Delta_h \theta = F_h(u_h) - F_h(u) + (P - R)(u_t - F(u)).$$

$$\theta_h(t) = e^{\epsilon \Delta_h t} \theta_{0h} + \int_0^t e^{\epsilon \Delta_h (t-s)} \left[ F_h(u_h) - F_h(u) + (P - R)(u_s - F(u)) \right] ds$$



$$\theta(t) = e^{\epsilon \Delta_h t} \theta_0 + \int_0^t e^{\epsilon \Delta_h (t-s)} [F_h(u_h(s)) - F_h(u(s))] ds \quad (\text{T1})$$

$$- \int_0^t e^{\epsilon \Delta_h (t-s)} (P - R) F(u(s)) ds \quad (\text{T2})$$

$$+ e^{\epsilon \Delta_h t/2} (P - R) u(\frac{t}{2}) - e^{\epsilon \Delta_h t} (P - R) u_0 \quad (\text{T3-4})$$

$$+ \epsilon \int_0^{\frac{t}{2}} \Delta_h e^{\epsilon \Delta_h (t-s)} (P - R) u(s) ds \quad (\text{T5})$$

$$+ \int_{\frac{t}{2}}^t e^{\epsilon \Delta_h (t-s)} (P - R) u_s(s) ds \quad (\text{T6})$$

Now take  $\| \cdot \|_{H^1}$  of each term separately and use our regularity estimates to get the result.

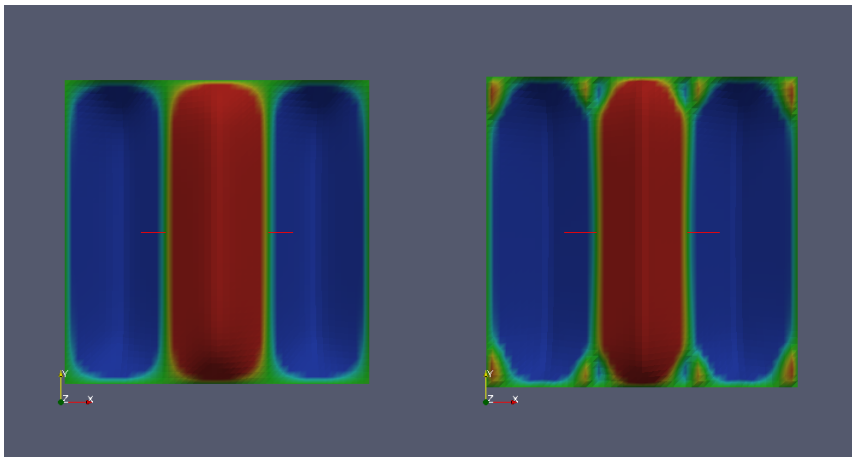
$$\|u_{\epsilon h} - u_{\epsilon}\|_{H^1} \lesssim h\epsilon^{-1/2}t^{-1/2} \quad t \in (0, T].$$

If we choose  $h^{2-2\delta} < \epsilon$  for some  $\delta > 0$  then

$$\|u_{\epsilon h} - u_{\epsilon}\|_{H^1} \lesssim h^{\delta}t^{-1/2}$$

*independent of  $\epsilon$ .*

Unfortunately we can only prove that up to finite time  $u_{\epsilon} \rightarrow u$  in  $H_0^1(\Omega)$  as  $\epsilon \rightarrow 0$ . We do not have a rate of convergence for the regularization error.



left:  $\epsilon = 0.001$ , right:  $\epsilon = 0.0001$ .  $h = 0.02$ .

## Further Work

- ▶ Long-time convergence result . . . convergence of attractors.
- ▶ Error in  $L^2$ .
- ▶ Regularization error? How does regularization change the long-time behaviour of the PDE?
- ▶ Existence of rest points for the original PDE.