Impractical CFTP

Beyond Geometric Ergodicity

References

Perfect simulation: A (short) survey.

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Plan of talk

Setting the scene

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Setting the scene (I)

- Propp and Wilson (1996) (and precursors);
- modify favourable MCMC algorithms to be exact;
- use coupling;
- resulting algorithms have random run-times;

Dyer and Greenhill (1999)'s Disconcerting Observation, Huber's Rejoinder.





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Setting the scene (II)

Successful *CFTP* needs "secret plans and clever tricks":

- search for monotonicity;
- crossover (WSK 1998);
- small sets (Murdoch and Green 1998);
- bounding chains (Häggström and Nelander 1999; Huber 2003);
- finitary CFTP (space as well as time) (WSK 1997, Häggström and Steif 2000);
- multi-shift (Wilson 2000b);
- read-once (Wilson 2000a);
- *FMMR* (Fill, Machida, Murdoch, and Rosenthal 2000).



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Impractical CFTP (I)

When is CFTP possible in principle?

• Foss and Tweedie (1998): classic *CFTP* is equivalent to uniform ergodicity

(small-set CFTP, sub-sampling).

 Nevertheless a notion of "dominated CFTP" can be made to work in some cases of geometric ergodicity (WSK 1998, WSK and Møller 1999). Application to perpetuities $(X_{n+1} = U_{n+1}^{\alpha}(1 + X_n))$: $\exp(M/D/1 \text{ workload})$ dominates.



Algorithm performance is even better for 64-bit computing ...



Impractical CFTP (II)

WSK (2004): any geometrically ergodic Markov chain X can (in principle) be adapted to *domCFTP*.

Sketch:

- Geometric ergodicity yields Foster-Lyapunov condition $\mathbb{E}\left[V(X_{n+1})|X_n\right] \leq \gamma V(X_n) + b\mathbb{I}[C](X_n).$
- Markov's inequality: domination by exp(D/M/1 workload).
- Need \u03c6 < e^{-1} to make workload positive-recurrent!</p>
- Sub-sample to improve Foster-Lyapunov γ .
- Domination maintained even under regeneration / non-regeneration at small set C: (argument of transportation type, eg Roberts and Rosenthal 2001).

Impractical, but similar to perpetuity example.



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Beyond Geometric Ergodicity (I) (Joint work with Stephen Connor)

Consider polynomial ergodicity, eg $\mathbb{E}[V(X_{n+1})|X_n] \leq V(X_n) - V(X_n)^{\alpha} + b\mathbb{I}[C](X_n).$

- Previous approach cannot work *in general*.
- Many Markov chains are slow because of "slow-down" in extremities of state-space;
- so use adaptive sub-sampling: $\sigma_{n+1} = \sigma_n + \lceil \lambda V(X_{\sigma_n})^{\delta} \rceil;$
- *X* is tame if (suitably) geometrically ergodic under *σ*-sub-sampling.

Beyond Geometric Ergodicity (II)

Idea: σ -time-changed X has *domCFTP* so "undo" time-change.

Construct stationary dominating process D which delivers $\exp(D/M/1 \text{ workload})$ dominator under σ -time-change.

Build X dominated by D by coupling only at times when D changes;

Careful conditional probability to show how to draw from X_0 ;



Proceed as with geometric ergodicity.

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Beyond Geometric Ergodicity (III)

Examples of non-geometrically-ergodic tame chains:

- "Epoch chain": spend random length of time at random level before jumping to 0 and regenerating;
- Delayed death processes;
- Delayed simple random walks;
- Random walks on half-lines (Tuominen and Tweedie 1994, Jarner and Roberts 2002).

Actual examples often permit direct domination (hence *domCFTP*) without adaptive σ -sub-sampling.



To polynomial ergodicity and beyond!

Are all polynomially ergodic chains tame?

Sub-geometric ergodicity and CFTP?

Positive recurrence and CFTP?

Sub-sampling versus maximal coupling?

Questions?



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