

Improved Importance Sampling of Phylogenies

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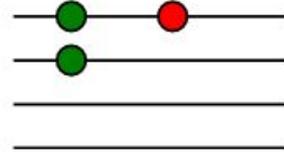
Outline

1. Our motivating problem
2. Importance sampling
 - a. sequential proposal distributions
 - i. existing proposals
3. Path density bias
 - a. de-biasing by counting paths

Setup

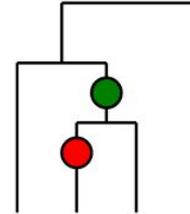
The data:

Single Nucleotide Polymorphisms (SNPs) in n aligned genetic sequences sampled in the present.



The model:

Individuals are leaves on an unobserved random tree with the most recent common ancestor at the root (a coalescent). New segregating sites occur along branches at rate θ .



The challenge:

Computing likelihoods does not scale as n increases (there are too many possible trees to consider)

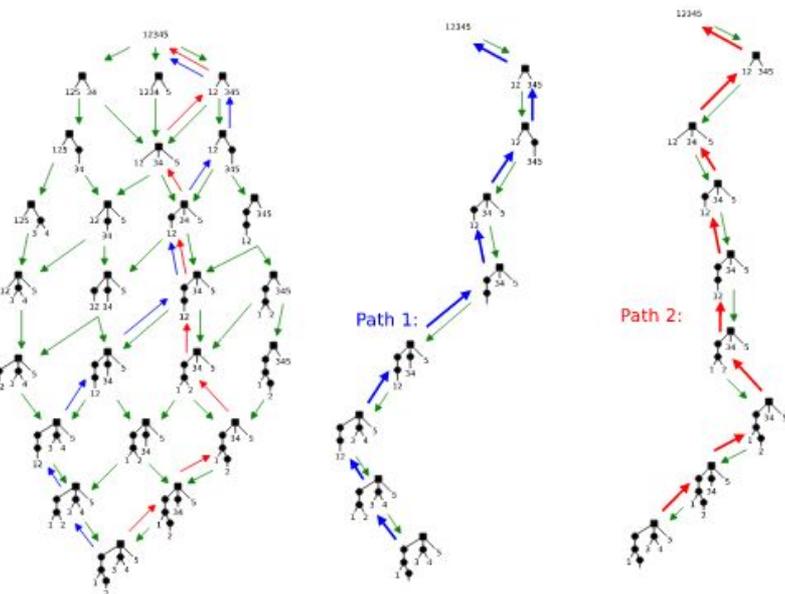
$$\mathbb{P} \left(\begin{array}{c} \text{---} \bullet \text{---} \bullet \text{---} \\ \text{---} \bullet \text{---} \\ \text{---} \\ \text{---} \end{array} \right) = \sum_{\substack{\Psi \text{ genealogical} \\ \text{history of } \begin{array}{c} \text{---} \bullet \text{---} \bullet \text{---} \\ \text{---} \bullet \text{---} \\ \text{---} \\ \text{---} \end{array}}} \mathbb{P}(\Psi)$$

Importance sampling of ancestral histories

$$\mathbb{P}\left(\begin{array}{c} \circ \\ \circ \\ \circ \\ \circ \end{array}\right) = \sum_{x \in \mathcal{H}\left(\begin{array}{c} \circ \\ \circ \\ \circ \\ \circ \end{array}\right)} \frac{\mathbb{P}(x)}{\mathbb{Q}(x)} \mathbb{Q}(x) = \mathbb{E}_{X \sim \mathbb{Q}} \left[\frac{\mathbb{P}(X)}{\mathbb{Q}(X)} \right] \approx \frac{1}{N} \sum_{i=1}^N \frac{\mathbb{P}(X_i)}{\mathbb{Q}(X_i)}$$

Ideally, the proposal distribution \mathbb{Q} , should

1. Approximate the target distribution \mathbb{P} well
2. Sampling $X \sim \mathbb{Q}$ should be fast
3. Computing weights $f_{\mathbb{Q}}(X)$ should be fast



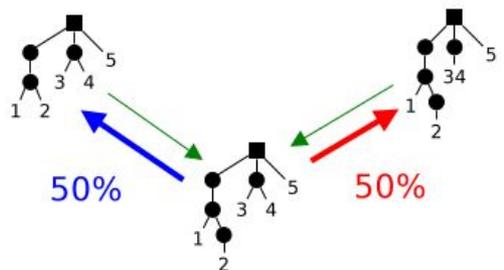
e.g.
$$\mathbb{P}\left(\begin{array}{c} \circ \\ \circ \\ \circ \\ \circ \end{array}\right) \approx \frac{1}{2} \left(\frac{\mathbb{P}(\text{Path 1})}{\mathbb{Q}(\text{Path 1})} + \frac{\mathbb{P}(\text{Path 2})}{\mathbb{Q}(\text{Path 2})} \right)$$

Conditions 2 & 3 allow us to pick large N (number of particles).

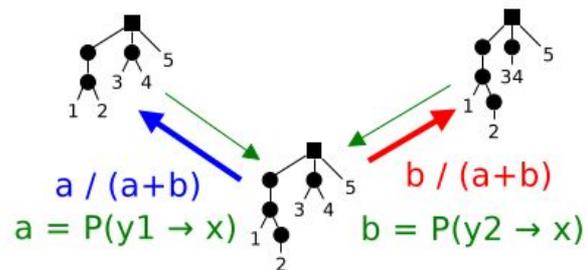
Condition 1 gives us better convergence in N .

For this problem: Known (feasible) proposals are **sequential**. Sampling from \mathbb{Q} is done by constructing paths step-by-step, **from the bottom up**.

Existing proposals (a single step)

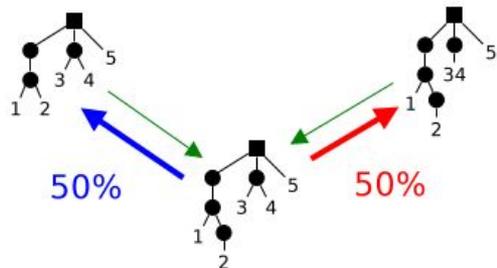


Stephens and Donnelly proposal

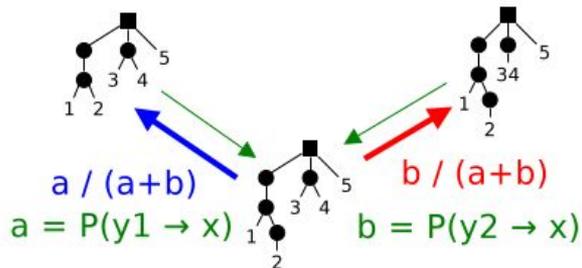


Griffiths and Taveré (G&T)

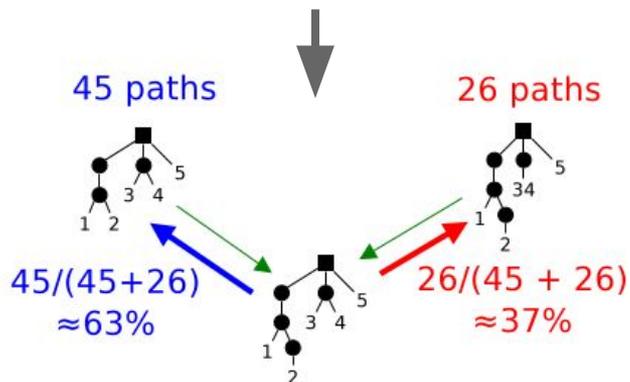
Combinatorial importance sampling



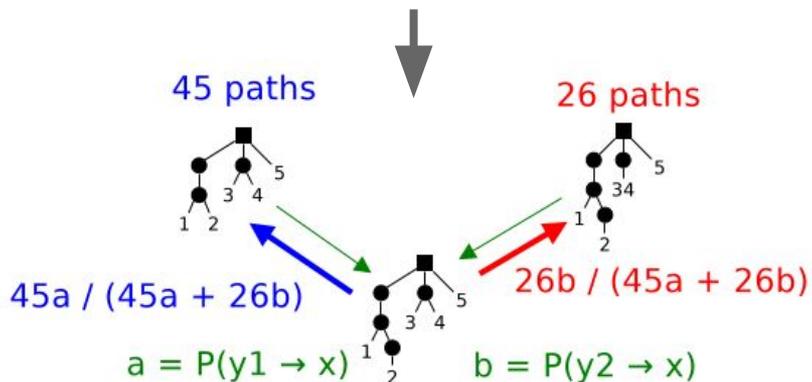
Stephens and Donnelly proposal



Griffiths and Taveré (G&T)

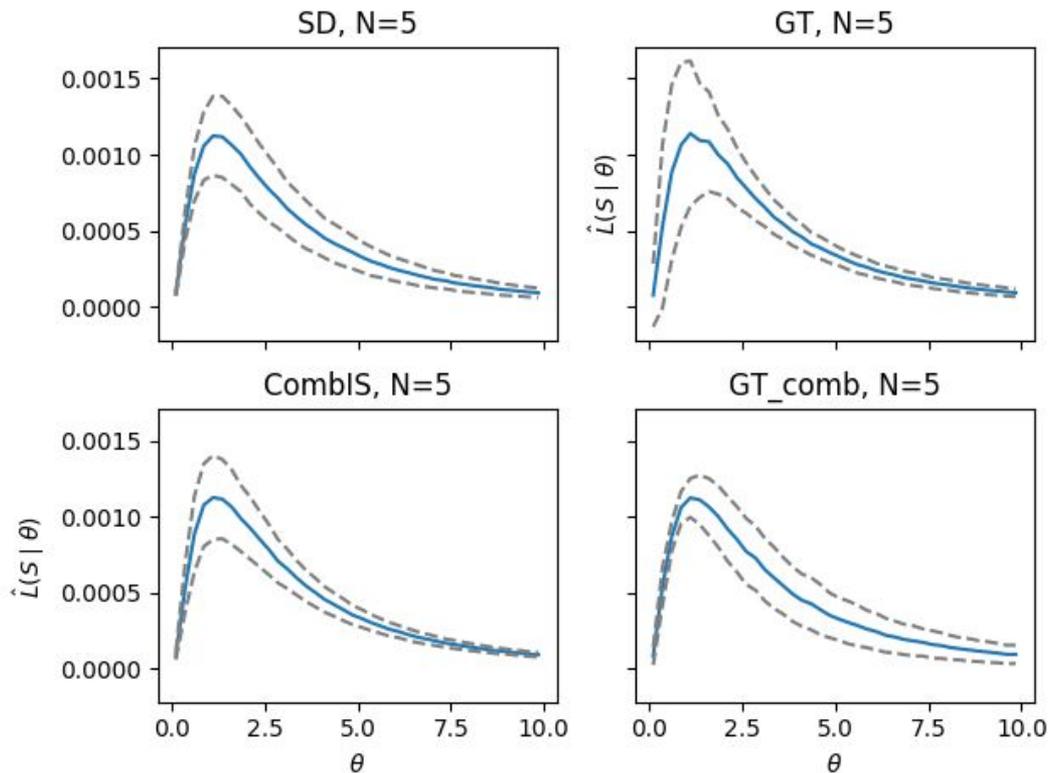


simple combinatorial sampling

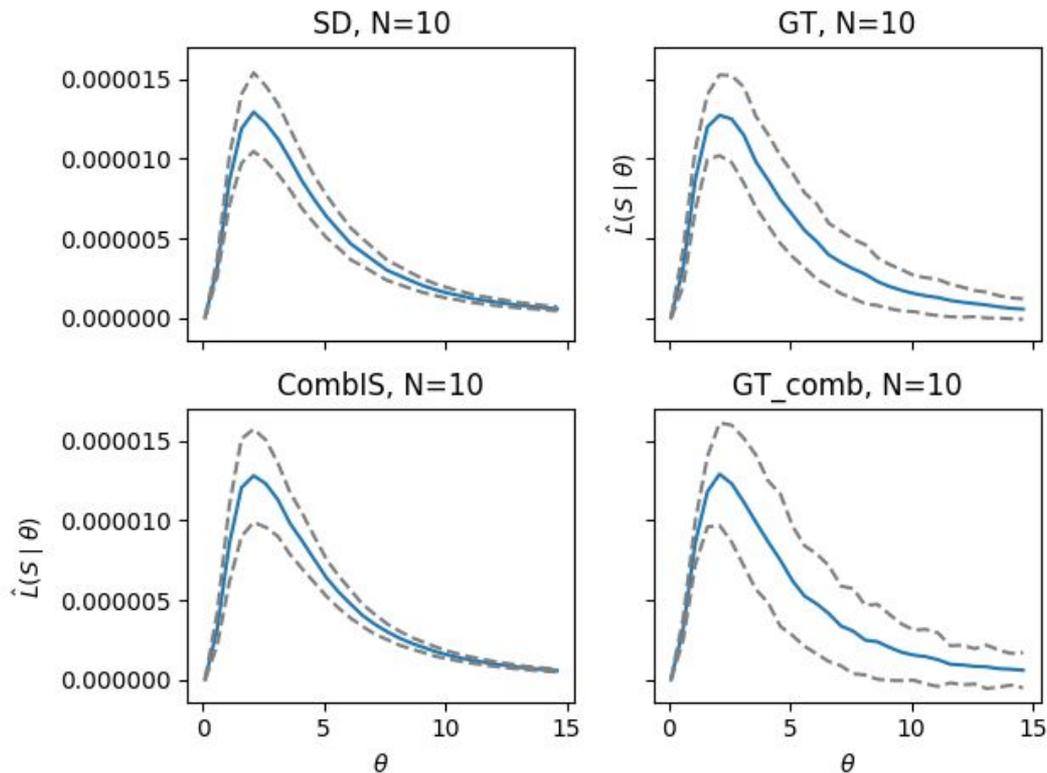


G&T + combinatorial correction

Likelihoods (toy example 1: 4 seq, 2 sites)



Likelihoods (toy example 2: 5 seq; 4 sites)



Thank you. Any Questions?

Collaborators (and supervisors)



Jotun Hein
(Oxford, Statistics)



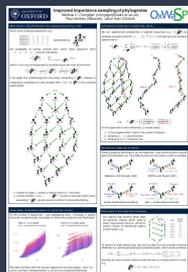
Paul Jenkins
(Warwick, Statistics & CS)

Code: <https://github.com/Cronjaeger/combIS>

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I also have a poster →