

Network inference in a stochastic multi-population WARWICK neural mass model via ABC Algorithm Seminar 2023

Massimiliano Tamborrino, Dept. of Statistics, warwick.ac.uk/tamborrino



Can we infer the connectivity structures of brain regions<sup>ICK</sup> before and during epileptic seizure? Do they differ? Algorithm Semina

Massimiliano Tamborrino, Dept. of Statistics, warwick.ac.uk/tamborrino

# EEG recordings



EEG recordings of a 11 year old female patient.







Modelling: How to model this?



- Modelling: How to model this?
- Simulation/Numerics:
  - How to simulate EEG recordings from the chosen model?



- Modelling: How to model this?
- Simulation/Numerics:
  - How to simulate EEG recordings from the chosen model?
- Statistics:
  - How to infer such network structure?



#### Let's look at one neural population

Model: 6-dim Jansen-and-Rit NMM (Hamiltonian-type SDE)

 $\begin{aligned} dX_{1}(t) &= X_{4}(t)dt \\ dX_{2}(t) &= X_{5}(t)dt \\ dX_{3}(t) &= X_{6}(t)dt \\ dX_{4}(t) &= \left[Aa(\operatorname{sig}(X_{2}(t) - X_{3}(t))) - 2aX_{4}(t) - a^{2}X_{1}(t)\right]dt + \bar{\varepsilon}dW_{4}(t) \end{aligned} \tag{1} \\ dX_{5}(t) &= \left[Aa(\mu + C_{2}\operatorname{sig}(C_{1}X_{1}(t))) - 2aX_{5}(t) - a^{2}X_{2}(t)\right]dt + \sigma dW_{5}(t) \\ dX_{6}(t) &= \left[BbC_{4}\operatorname{sig}(C_{3}X_{1}(t)) - 2bX_{6}(t) - b^{2}X_{3}(t)\right]dt + \tilde{\varepsilon}dW_{6}(t), \end{aligned}$ with fixed  $\bar{\varepsilon}, \tilde{\varepsilon} \ll \sigma$  and unknown parameters  $\mu, C, \sigma$ .



# What can a single sJR-NMM do?



Different activities obtained by modifying the excitation-inhibition-ratio A/B



It succesfully fits single EEG recording<sup>1</sup>



<sup>1</sup>Buckwar, Tamborrino, Tubikanec. Spectral density-based and measure-preserving ABC for partially observed diffusion processes. An illustration on Hamiltonian SDEs. Stat. Comput. 30 (3), 627-648, 2020.



# Modelling of N copuled neural populations

- *N* populations of neural mass models  $\Rightarrow$  6N-SDE
- Each population k follows a sJR-NMM with

$$dX_{5}(t) = \left[Aa(\mu + C_{2}sig(C_{1}X_{1}(t))) - 2aX_{5}(t) - a^{2}X_{2}(t)\right]dt + \sigma dW_{5}(t)$$
  
$$\Rightarrow dX_{5}^{k}(t) = \left[A_{k}a_{k}\left(\mu_{k} + C_{2,k}sig\left(C_{1,k}X_{1}^{k}(t)\right) + \sum_{j=1,j\neq k}^{N}\rho_{jk}K_{jk}X_{1}^{j}(t)\right) - 2a_{k}X_{5}^{k}(t) - a_{k}^{2}X_{2}^{k}(t)\right]dt + \sigma_{k}dW_{5}^{k}(t)$$

#### with

\*  $\rho_{jk} \in \{0,1\}$  modelling the directed coupling from the *j*th to *k*th pop \*  $K_{jk} > 0$  modelling the coupling strenght.

- N-dimensional observed output
- $Y(t) := (Y^{1}(t), \dots, Y^{N}(t))^{\top} = (X_{2}^{1}(t) X_{3}^{1}(t), \dots, X_{2}^{N}(t) X_{3}^{N}(t))^{\top}, \quad t \in [0, T].$ 
  - ▶ Now the excitation-inhibitiona ratio A/B,  $\rho_{ij}$  and  $K_{ij}$  play a crucial role



# Example: Cascade network - 4 populations, 1 active



Population 1: Setting D: Frequent spiking. Left columns:  $\rho_{kj} = 0$ . Center and Right columns:  $\rho_{12} = \rho_{23} = \rho_{34} = 1$ ,  $K_{ii+1} = 300$  (C) vs 500 (R).



#### Formulation as stochastic Hamiltonian-type system

Each kth population can be written as

$$d\begin{pmatrix} Q^{k}(t)\\ P^{k}(t) \end{pmatrix} = \begin{pmatrix} \nabla_{P}H_{k}(Q^{k}(t), P^{k}(t))\\ -\nabla_{Q}H_{k}(Q^{k}(t), P^{k}(t)) - 2\Gamma_{k}P^{k}(t) + G_{k}(Q(t)) \end{pmatrix} dt + \begin{pmatrix} \mathbb{O}_{3}\\ \Sigma_{k} \end{pmatrix} dW^{k}(t),$$

with  $H_k: \mathbb{R}^6 \rightarrow \mathbb{R}^+_0$  given by

$$H_k(Q^k, P^k) := \frac{1}{2} \left( \left\| P^k \right\|^2 + \left\| \Gamma_k Q^k \right\|^2 \right),$$

with:

- gradients  $\nabla_P H_k(Q^k(t), P^k(t)) = P^k(t)$  and  $\nabla_Q H_k(Q^k(t), P^k(t)) = \Gamma_k^2 Q^k(t)$ - 3×3-dimensional diagonal matrix  $\Gamma_k = \text{diag}[a_k, a_k, b_k]$ . and  $G_k : \mathbb{R}^{3N} \to \mathbb{R}^3$  given by

$$G_{k}(Q(t)) = \begin{pmatrix} A_{k}a_{k}\operatorname{sig}(X_{2}^{k}(t) - X_{3}^{k}(t)) \\ A_{k}a_{k}\left(\mu_{k} + C_{2,k}\operatorname{sig}(C_{1,k}X_{1}^{k}(t)) + \sum_{j=1, j \neq k}^{N}\rho_{jk}K_{jk}X_{1}^{j}(t)\right) \\ B_{k}b_{k}C_{4,k}\operatorname{sig}(C_{3,k}X_{1}^{k}(t)) \end{pmatrix},$$



Formulation as stochastic Hamiltonian-type system

Putting everything together

$$d\begin{pmatrix}Q(t)\\P(t)\end{pmatrix} = \begin{pmatrix}P(t)\\-\Gamma^2Q(t)-2\Gamma P(t)+G(Q(t))\end{pmatrix}dt + \begin{pmatrix}\mathbb{O}_{3N}\\\Sigma\end{pmatrix}dW(t),$$

with

$$Q = (Q^{1},...,Q^{N})^{\top} = (X_{1}^{1},X_{2}^{1},X_{3}^{1},...,X_{1}^{N},X_{2}^{N},X_{3}^{N})^{\top}$$

$$P = (P^{1},...,P^{N})^{\top} = (X_{4}^{1},X_{5}^{1},X_{6}^{1},...,X_{4}^{N},X_{5}^{N},X_{6}^{N})^{\top}$$

$$\Gamma = \text{diag}[a_{1},a_{1},b_{1},...,a_{N},a_{N},b_{N}],$$

$$\Sigma = \text{diag}[\varepsilon_{1},\sigma_{1},\varepsilon_{1},...,\varepsilon_{N},\sigma_{N},\varepsilon_{N}]$$



### Simulation of stochastic Hamiltonian-type system

We can rewrite

$$d\begin{pmatrix}Q(t)\\P(t)\end{pmatrix} = \begin{pmatrix}P(t)\\-\Gamma^2Q(t)-2\Gamma P(t)+G(Q(t))\end{pmatrix}dt + \begin{pmatrix}\mathbb{O}_{3N}\\\Sigma\end{pmatrix}dW(t),$$

as

$$dX(t) = (AX(t) + N(X(t)) dt + \Sigma_0 dW(t),$$

with  $X(t) = (Q(t), P(t))^T$  and

$$A = \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix}, \quad N(X(t)) = N(Q(t)) = \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix}, \quad \Sigma_0 = \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix}.$$

We will use *splitting schemes* ( $\supseteq$  leap-frog) to simulate from it



$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

Step 1: Split the equation into explicitly solvable subequations.

#### **Step 2**: Derive the explicit solutions of the subequations.

**Step 3**: Compose the derived explicit solutions.



$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

Step 1: Split the equation into explicitly solvable subequations.

$$dX^{[1]}(t) = AX^{[1]}(t)dt + \Sigma_0 dW(t) dX^{[2]}(t) = N(X(t))dt$$

**Step 2**: Derive the explicit solutions of the subequations.

**Step 3**: Compose the derived explicit solutions.



$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

**Step 1**: Split the equation into explicitly solvable subequations.

$$dX^{[1]}(t) = AX^{[1]}(t)dt + \Sigma_0 dW(t) dX^{[2]}(t) = N(X(t))dt$$

**Step 2**: Derive the explicit solutions of the subequations.

$$\begin{split} X^{[1]}(t_{i+1}) &= \varphi_{\Delta}^{[1]}\left(X^{[1]}(t_{i})\right) = e^{A\Delta}X^{[1]}(t_{i}) + \xi_{i}(\Delta),\\ \text{with }\xi(\Delta) \sim \mathcal{N}(0_{6N}, \mathcal{C}(\Delta)), \text{Cov}(\Delta) = \int_{0}^{\Delta} e^{A(\Delta-s)}\Sigma_{0}\Sigma_{0}^{\top}\left(e^{A(\Delta-s)}\right)^{\top} ds \text{ and}\\ e^{F\Delta} &= \begin{pmatrix} e^{-\Gamma\Delta}(\mathbb{I}_{3N} + \Gamma\Delta) & e^{-\Gamma\Delta}\Delta\\ -\Gamma^{2}e^{-\Gamma\Delta}\Delta & e^{-\Gamma\Delta}(\mathbb{I}_{3N} - \Gamma\Delta) \end{pmatrix} =: \begin{pmatrix} \vartheta(\Delta) & \kappa(\Delta)\\ \vartheta'(\Delta) & \kappa'(\Delta) \end{pmatrix} \end{split}$$



$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

**Step 1**: Split the equation into explicitly solvable subequations.

$$dX^{[1]}(t) = AX^{[1]}(t)dt + \Sigma_0 dW(t) dX^{[2]}(t) = N(X(t))dt$$

**Step 2**: Derive the explicit solutions of the subequations.

$$X^{[1]}(t_{i+1}) = \varphi_{\Delta}^{[1]}\left(X^{[1]}(t_{i})\right) = e^{A\Delta}X^{[1]}(t_{i}) + \xi_{i}(\Delta),$$
$$\left(\frac{1}{2}\Gamma^{-3}\Sigma^{2}\left(\mathbb{I}_{2M} + \kappa(\Delta)\vartheta'(\Delta) - \vartheta^{2}(\Delta)\right) - \frac{1}{2}\Sigma^{2}\kappa^{2}(\Delta)\right)$$

$$\operatorname{Cov}(\Delta) = \begin{pmatrix} \frac{1}{4} \Gamma^{-1} \Sigma^{-1} & \frac{1}{2} \Sigma^{-1} \kappa^{-1} \\ \frac{1}{2} \Sigma^{-2} \kappa^{-2} \\ \frac{1}{2} \Sigma^{-2} \kappa^{-2} \\ \frac{1}{4} \Gamma^{-1} \Sigma^{-2} \\ \frac{1}{4} \Gamma^{-1} \Sigma^{-2} \\ \frac{1}{4} \Gamma^{-1} \\$$

Warwick
 Statistics
 Step 3: Compose the derived explicit solutions.

$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

Step 1: Split the equation into explicitly solvable subequations.

$$dX^{[1]}(t) = AX^{[1]}(t)dt + \Sigma_0 dW(t) dX^{[2]}(t) = N(X(t))dt$$

**Step 2**: Derive the explicit solutions of the subequations.

$$\begin{aligned} X^{[1]}(t_{i+1}) &= \varphi^{[1]}_{\Delta}\left(X^{[1]}(t_i)\right) = e^{A\Delta}X^{[1]}(t_i) + \xi_i(\Delta), \\ X^{[2]}(t_{i+1}) &= \varphi^{[2]}_{\Delta}\left(X^{[2]}(t_i)\right) = X^{[2]}(t_i) + \Delta\begin{pmatrix}0_{3N}\\G(Q^{[2]}(t_i))\end{pmatrix}. \end{aligned}$$

**Step 3**: Compose the derived explicit solutions.



$$dX(t) = [AX(t) + N(X(t))]dt + \Sigma_0 dW(t)$$
  
=  $\left( \begin{pmatrix} \mathbb{O}_{3N} & \mathbb{I}_{3N} \\ -\Gamma^2 & -2\Gamma \end{pmatrix} X(t) + \begin{pmatrix} \mathbb{O}_{3N} \\ G(Q(t)) \end{pmatrix} \right) dt + \begin{pmatrix} \mathbb{O}_{3N} \\ \Sigma \end{pmatrix} dW(t).$ 

Step 1: Split the equation into explicitly solvable subequations.

$$dX^{[1]}(t) = AX^{[1]}(t)dt + \Sigma_0 dW(t) dX^{[2]}(t) = N(X(t))dt$$

**Step 2**: Derive the explicit solutions of the subequations.

$$\begin{aligned} X^{[1]}(t_{i+1}) &= \varphi_{\Delta}^{[1]}\left(X^{[1]}(t_{i})\right) = e^{A\Delta}X^{[1]}(t_{i}) + \xi_{i}(\Delta), \\ X^{[2]}(t_{i+1}) &= \varphi_{\Delta}^{[2]}\left(X^{[2]}(t_{i})\right) = X^{[2]}(t_{i}) + \Delta\begin{pmatrix}0_{3N}\\G(Q^{[2]}(t_{i}))\end{pmatrix}. \end{aligned}$$

**Step 3**: Compose the derived explicit solutions.

$$\widetilde{X}^{\mathrm{S}}(t_{i+1}) = \left(\varphi_{\Delta/2}^{[2]} \circ \varphi_{\Delta}^{[1]} \circ \varphi_{\Delta/2}^{[2]}\right) \left(\widetilde{X}^{\mathrm{S}}(t_{i})\right).$$
(2)



Algorithm 1 Strang splitting scheme for the N-population stochastic JR-NMM Input: Initial value  $X_0$ , step size  $\Delta$ , number of time steps m in [0,T] and model parameters Output: Approximated path of  $(X(t))_{t \in [0,T]}$  at discrete times  $t_i = i\Delta$ ,  $i = 0, \ldots, m$ ,  $t_m = T$ .

1: Set  $\widetilde{X}^{S}(t_{0}) = X_{0}$ 2: for i = 0 : (m - 1) do 3: Set  $X^{[2]} = \widetilde{X}^{S}(t_{i}) + \frac{\Delta}{2} \begin{pmatrix} 0_{3N} \\ G(\widetilde{Q}^{S}(t_{i})) \end{pmatrix}$ 4: Set  $X^{[1]} = e^{F\Delta}X^{[2]} + \xi_{i}(\Delta)$ 5: Set  $\widetilde{X}^{S}(t_{i+1}) = X^{[1]} + \frac{\Delta}{2} \begin{pmatrix} 0_{3N} \\ G(Q^{[1]}) \end{pmatrix}$ 6: end for 7: Return  $\widetilde{X}^{S}(t_{i}), i = 0, ..., m$ .



# Properties of the derived splitting scheme

The derived splitting scheme

- 1. is **mean-square convergent order** 1 if N(X(t)) is globally Lipschitz (similar results for one-sided globally Lipschitz with polynomial growth<sup>2</sup>.
- 2. is 1-step hypoelliptic.
- 3. satisfies a discrete Lyapunov condition ⇒ it is geometrically ergodic.

<sup>2</sup>Buckwar et al. Appl. Num. Math. 2022



# Properties of the derived splitting scheme

The derived splitting scheme

- 1. is **mean-square convergent order** 1 if N(X(t)) is globally Lipschitz (similar results for one-sided globally Lipschitz with polynomial growth<sup>2</sup>.
- 2. is 1-step hypoelliptic.
- 3. satisfies a discrete Lyapunov condition ⇒ it is geometrically ergodic.

#### (More to be discussed):

- It could be used for simulating Langevin dynamics in HMC.
- Better than leap-frog/MALT.

<sup>2</sup>Buckwar et al. Appl. Num. Math. 2022



# What about inference?



# SMC-ABC

#### Algorithm 3 Sequential Monte Carlo ABC (SMC-ABC)

```
1: Set t := 1.
 2: for i = 1, ..., N do
          repeat
 3:
               Sample \theta^* \sim \pi(\theta).
 4:
              Generate z^i \sim p(z|\theta^*) from the model.
 5:
              Compute summary statistic s^i = S(z^i).
 6:
          until ||s^i - s_y|| < \delta_1
 7:
         Set \theta_1^{(i)} := \theta^*
 8:
         set \tilde{w}_{1}^{(i)} := 1.
 9:
10: end for
11: Obtain \delta_2 and update the scaling factors for the summary statistics.
12: for t = 2, ..., T do
          for i = 1, ..., N do
13:
14:
               repeat
                    Randomly pick (with replacement) \theta^* from the weighted set \{\theta_{t-1}^{(i)}, w_{t-1}^{(i)}\}_{i=1}^N.
15:
                   Sample \theta^{**} \sim q_t(\cdot | \theta^*).
16:
                   if \pi(\theta^{**}) = 0 go to step 16, otherwise continue.
17:
                   Generate z^i \sim p(z|\theta^{**}) from the model.
18:
                   Compute summary statistic s^i = S(z^i).
19:
               until ||s^i - s_u|| < \delta_t
20:
              Set \theta_{\star}^{(i)} := \theta^{**}
21:
              set \tilde{w}_t^{(i)} = \pi(\theta_t^{(i)}) / \sum_{i=1}^N w_{t-1}^{(j)} q_t(\theta_t^{(i)} | \theta_{t-1}^{(j)}).
22:
          end for
23:
          Normalise the weights: w_t^{(i)} := \tilde{w}_t^{(i)} / \sum_{i=1}^N \tilde{w}_t^{(j)}.
24:
25:
          Decrease the current \delta and update the scaling factors for the summary statistics.
26: end for
27: Output:
28: A set of weighted parameter vectors (\theta_T^{(1)}, \tilde{w}_T^{(1)}), \dots, (\theta_T^{(N)}, \tilde{w}_T^{(N)}) \sim \pi_{\delta_T}(\theta|s_u).
```

# Adjusted SMC-ABC

1: for i = 1 : M do 2: repeat 3: Randomly pick (with replacement)  $\theta_c$  from the weighted set  $\{\Theta_{c,t-1}, w_{t-1}\}$ 4: Perturb  $\theta_c$  to obtain  $\theta_c^*$  from  $q_t^c(\cdot|\theta_c)$ . Sample  $\theta_d^k$ ,  $k = 1, ..., d_n$ , from Bernoulli $(\hat{p}_t^k)$ , where  $\hat{p}_t^k = \frac{1}{M} \sum_{i=1}^M \theta_{d,t-1}^{k,(i)}$ . 5: Perturb  $\theta_d = (\theta_d^1, \dots, \theta_d^{d_n})$  to obtain  $\theta_d^*$  from  $q_t^d(\cdot | \theta_d)$ . 6: Conditioned on  $\theta^* = (\theta_c^*, \theta_d^*)$ , simulate a dataset  $\tilde{y}_{\theta^*}$  from the model. 7: 8: Compute the summaries  $s(\tilde{y}_{\theta^*})$ . 9: Calculate the distance  $D = d(s(y), s(\tilde{y}_{\theta^*}))$ . 10: until  $D < \delta_t$ Set  $\theta_{d,t}^{(i)} = \theta_{d}^*$  and  $\theta_{c,t}^{(i)} = \theta_{c}^*$ 11:  $\mathsf{Set}~\tilde{w}_t^{(i)} = \pi^c \left( \theta_{c,t}^{(i)} \right) / \sum_{l=1}^M w_{t-1}^{(l)} \mathscr{K}_t^c \left( \theta_{c,t}^{(i)} \middle| \theta_{c,t-1}^{(l)} \right)$ 12: 13: end for 14: Normalise the weights  $w_t^{(i)} = \tilde{w}_t^{(i)} / \sum_{j=1}^M \tilde{w}_t^{(i)}$ , for  $j = 1, \dots, M$ 



#### Choice of perturbation kernels

 $q_{\theta}^{c}$ : Optimised Gaussian kernels as in Filippi et al. 2013 (alternatively: copula-based samplers, Picchini and Tamborrino, 2022).

Discrete kernel: a value  $\theta_k^d$ ,  $k = 1, ..., d_n$ , sampled from a Bernoulli distribution at iteration t is either kept with (fixed) probability  $q_{\text{stay}}$  or perturbed to  $1 - \theta_k^d$ , i.e.

$$q_{t}^{d}\left(\theta_{d,t}^{(i)}\middle|\theta_{d,t-1}^{(l)}\right) = \prod_{k=1}^{d_{n}} q_{t}^{d,k}\left(\theta_{d,t}^{k,(i)}\middle|\theta_{d,t-1}^{k,(l)}\right) = \prod_{k=1}^{d_{n}} \left(p_{t}^{k,(l)}\right)^{\theta_{d,t}^{k,(i)}} \left(1 - p_{t}^{k,(l)}\right)^{1 - \theta_{d,t}^{k,(i)}},$$

where

$$p_t^{k,(l)} = \left\{ 1 - q_{\text{stay}}, \quad \text{if } \theta_{d,t-1}^{k,(l)} = 0 \; . \right.$$



# Choice of Summary Statistics

Accept  $\theta^*$  if  $d(s(y), s(\tilde{y}_{\theta^*})) < \delta_t$ .





# Choice of Summary Statistics

Accept  $\theta^*$  if  $d(s(y), s(\tilde{y}_{\theta^*})) < \delta_t$ .



 $\implies$  Derive summaries based on the characterising model properties: map the data into something fully characterised by  $\theta$ .





# Choice of Summary Statistics

$$s(y) := \{f_k, S_k, Z_{jk}, R_{jk}\}_{j,k=1,...,N, j \neq k}.$$

- \*  $f_k$ : invariant density of  $Y^k$ .
- \* Spectral density  $S_k$  of  $Y^k$ :

$$S_k(v) = \mathscr{F}\{R_k\}(v) = \int_{-\infty}^{\infty} R_k(\tau) e^{-i2\pi v\tau} d\tau, \quad k \in \{1, \dots, N\},$$

where v denotes the frequency and  $R_k(\tau) = \mathbb{E}[Y^k(t)Y^k(t+\tau)], \quad k \in \{1, \dots, N\}.$ 

\* Cross-spectral density  $S_{jk}$  of  $Y^j$  and  $Y^k$ :

$$S_{jk}(\mathbf{v}) = \mathscr{F}\{R_{jk}\}(\mathbf{v}) = \int_{-\infty}^{\infty} R_{jk}(\tau) e^{-i2\pi\mathbf{v}\tau} d\tau,$$

where  $R_{jk}(\tau) = \mathbb{E}[Y^j(t)Y^k(t+\tau)], \quad j,k \in \{1,\ldots,N\}, \ j \neq k.$ 

\* Magnitude Square Coherence (MSC):

$$Z_{jk}(v) := rac{|S_{jk}(v)|^2}{S_j(v)S_k(v)}, \quad j,k \in \{1,\ldots,N\}, \ j \neq k,$$

where  $\left|\cdot\right|$  denotes the magnitude.



#### Choice of distance measure

We use the Integrate Absolute Error  $(IAE)^3$ 

$$\mathrm{IAE}(g_1,g_2) := \int\limits_{\mathbb{R}} |g_1(x) - g_2(x)| \, dx \in \mathbb{R}^+,$$

to compute

$$D(s(y), s(\tilde{y}_{\theta})) := v_1 \frac{1}{N} \sum_{k=1}^{N} IAE(\hat{S}_k, \tilde{S}_k) + v_2 \frac{1}{N(N-1)/2} \sum_{j=1,k>j}^{N} IAE(\hat{Z}_{jk}, \tilde{Z}_{jk}) + v_3 \frac{1}{N(N-1)} \sum_{j,k=1,j\neq k}^{N} IAE(\hat{R}_{jk}, \tilde{R}_{jk}) + v_4 \frac{1}{N} \sum_{k=1}^{N} IAE(\hat{f}_k, \tilde{f}_k),$$

The weights  $v_l \ge 0$ , l = 1, 2, 3, 4, are chosen such that the different summary functions have a comparable impact on the distance measure.

<sup>3</sup>Buckwar, Tamborrino, Tubikanec, Stat. Comput. 2020



#### Parameters of interest

(N+2+N(N-1))-dimensional parameter vector

$$\theta = (\underbrace{A_1, \ldots, A_N, L, c}_{\theta_c}, \underbrace{\operatorname{vec}(\mathscr{P})}_{\theta_d}),$$

with

- ► A<sub>k</sub>: Average excitatory synaptic gains.
- ▶  $\mathscr{P}$ : directed connectivity parameters  $\theta_d = \mathscr{P} = (\rho_{jk})_{j,k=1,...,N}$ , with  $\rho_{ji} = \{0,1\}$ .
- (L,c) entering into the coupling parameters  $K_{jk}$  as

$$K_{jk} := c^{|j-k|-1}L,$$

- L > 0: coupling strength parameter
- $0 \ll c < 1$  determines how fast the the network coupling strength decreases with distance.







(b)



(c)



# Partially connected network





# Partially connected network





#### Back to real data

$$\begin{pmatrix} - & K_{12} & K_{13} & K_{14} \\ K_{21} & - & K_{23} & K_{24} \\ K_{31} & K_{32} & - & K_{34} \\ K_{41} & K_{42} & K_{43} & - \end{pmatrix} = \begin{pmatrix} - & L & c^2 L & c^3 L \\ L & - & cL & c^2 L \\ c^2 L & cL & - & L \\ c^3 L & c^2 L & L & - \end{pmatrix},$$

\* b and C chosen from pilot study, other quantities fixed according to standard values.

Parameter of interest: (10+12)-dimensional

 $\theta = (A_1, A_2, A_3, A_4, L, c, \sigma_l, \sigma_r, \mu_l, \mu_r, \operatorname{vec}(\mathscr{P})).$ 





Before seizure: solid green (N = 4)During seizure: solid blue (N = 4)











Before seizure: solid green (N = 4), dotted orange (N = 2, LH), dotted brown (N = 2, RH). During seizure: solid blue (N = 4), dashed grey (N = 2, LH), dashed black (N = 2, RH).







### Fitted summaries



Odd panels: before seizure.

Even panels: during seizure.

Solid black lines: Summaries derived from the EEG datasets. Grey areas: Range of the summaries obtained from synthetic datasets simulated using the kept posterior samples from the full model.



#### Fitted summaries





## Some references

Today Ditlevsen, Tamborrino, Tubikanec. Network inference in a stochastic multi-population neural mass model via approximate Bayesian computation. Preprint at arXiv:2306.15787, 2023.

Buckwar, Tamborrino, Tubikanec. Spectral density-based and measure-preserving ABC for partially observed diffusion processes. An illustration on Hamiltonian SDEs. Stat. Comput., 30, 627–648, 2020.

Picchini, Tamborrino.
 Guided sequential ABC for intractable Bayesian models.
 Preprint at arXiv:2206.12235, 2022.

Buckwar, Samson, Tamborrino, Tubikanec. A splitting method for SDEs with locally Lipschitz drift. An illustration on the FitzHugh-Nagumo model. App. Num. Math. 179, 191–220, 2022.

Some interesting ongoing/forthcoming activities

- OneWorldABC (every last Thursday of the month) www.warwick.ac.uk/oneworldabc
- BioInference2024, 5th-7th June 2024, Warwick. https://bioinference.github.io/2024/









# Specific choices

► M=500.

- $T = 20, \Delta_{\text{sim}} = 10^{-4}, \Delta_{\text{obs}} = 210^{-3} \Rightarrow n = 10^4.$
- ▶  $\delta_1$  obtained via a reference table acceptance-rejection ABC pilot run. Under  $\pi(\theta)$ , we produce  $10^4$  distances and then choose  $\delta_1 = \text{median}(D_1, \dots, D_{10^4}).$
- $\delta_t = \text{percentile}(D_1^{(t-1)}, \dots, D_M^{(t-1)})$ , with percentile = 50% if accept. rate > 1%,75% otherwise.
- ▶ Stopping criterion: acceptance rate below 0.1%.



Parameter	Meaning	Standard value
A	Average excitatory synaptic gain	3.25  mV
B	Average inhibitory synaptic gain	22  mV
a	Membrane time constant of excitatory postsynaptic potential	$100 \ {\rm s}^{-1}$
b	Membrane time constant of inhibitory postsynaptic potential	$50 \ {\rm s}^{-1}$
C	Average number of synapses between the subpopulations	135
$C_1, C_2$	Avg. no. of synaptic contacts in the excitatory feedback loop	C, 0.8 C
$C_3, C_4$	Avg. no. of synaptic contacts in the inhibitory feedback loop	$0.25\ C,\ 0.25\ C$
$\nu_{\rm max}$	Maximum firing rate (Maximum of the sigmoid function)	$5 \ s^{-1}$
$v_0$	Value for which 50% of the maximum firing rate is attained	6  mV
$\gamma$	Determines the slope of the sigmoid function at $v_0$	$0.56 \ {\rm mV}^{-1}$

Table 1: Standard parameter values for the Jansen and Rit Neural Mass Model [1, 18, 12].



Algorithm 2 Adjusted SMC-ABC for network inference (nSMC-ABC) Input: Summaries s(y) of the observed data y, prior distributions  $\pi^c$  and  $\pi^d$ , perturbation kernels  $K_r^c$  and  $K_{r^*}^d$ , number of kept samples per iteration M, initial threshold  $\delta_1$ Output: Samples from the nSMC-ABC posterior

1: Set r = 12: for j = 1 : M do 3: repeat Sample  $\theta_d$  from  $\pi^d$  and  $\theta_c$  from  $\pi^c$ , and set  $\theta = (\theta_c, \theta_d)$ 4: 5: Conditioned on  $\theta$ , simulate a synthetic dataset  $\tilde{y}_{\theta}$  from the observed output Y 6: Compute the summaries  $s(\tilde{y}_{\theta})$ Calculate the distance  $D = d(s(y), s(\tilde{y}_{\theta}))$ 7: until  $D < \delta_1$ 8: Set  $\theta_{d,1}^{(j)} = \theta_d$  and  $\theta_{c,1}^{(j)} = \theta_c$ 9: 10: end for 11: Initialize the weights by setting each entry of  $w_1 = (w_1^{(1)}, \ldots, w_1^{(M)})$  to 1/M12: repeat Set r = r + 113: Determine  $\delta_r < \delta_{r-1}$ 14: for j = 1 : M do 15: 16: repeat Sample  $\theta_c$  from the weighted set  $\{\Theta_{c,r-1}, w_{r-1}\}$ Perturb  $\theta_c$  to obtain  $\theta_c^*$  from  $\mathcal{K}_r^c(\cdot|\theta_c)$ 18: Sample  $\theta_d^k$ ,  $k = 1, ..., d_n$ , from Bernoulli $(\hat{p}_r^k)$ , where  $\hat{p}_r^k = \frac{1}{M} \sum_{r=0}^M \theta_{d,r-1}^{k,(l)}$ 19: Perturb  $\theta_d = (\theta_d^1, \dots, \theta_d^{d_n})$  to obtain  $\theta_d^*$  from  $\mathcal{K}_r^d(\cdot | \theta_d)$ 20:Conditioned on  $\theta^* = (\theta_c^*, \theta_d^*)$ , simulate a dataset  $\tilde{y}_{\theta^*}$  from the observed output Y 21:Compute the summaries  $s(\tilde{y}_{\theta^*})$ 22:Calculate the distance  $D = d(s(y), s(\tilde{y}_{\theta^*}))$ 23:until  $D < \delta_r$ 24: Set  $\theta_{d,r}^{(j)} = \theta_d^*$  and  $\theta_{c,r}^{(j)} = \theta_c^*$ 25:Set  $\tilde{w}_r^{(j)} = \pi^c \left( \theta_{c,r}^{(j)} \right) / \sum_{r=1}^M w_{r-1}^{(l)} \mathcal{K}_r^c \left( \theta_{c,r}^{(j)} \middle| \theta_{c,r-1}^{(l)} \right)$ 26: end for 27:Normalise the weights  $w_r^{(j)} = \tilde{w}_r^{(j)} / \sum_{i=1}^M \tilde{w}_r^{(l)}$ , for  $j = 1, \dots, M$ 28:29: until stopping criterion is reached