

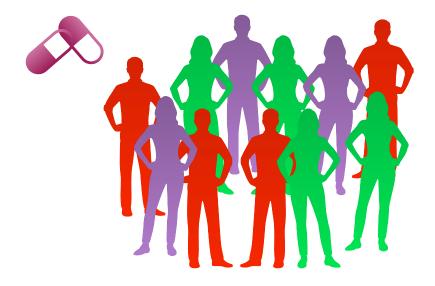


Amortized Simulation-Based Inference For Non-Linear Mixed-Effects Models

Jonas Arruda & Yannik Schälte - 29th June 2023

One World ABC Seminar

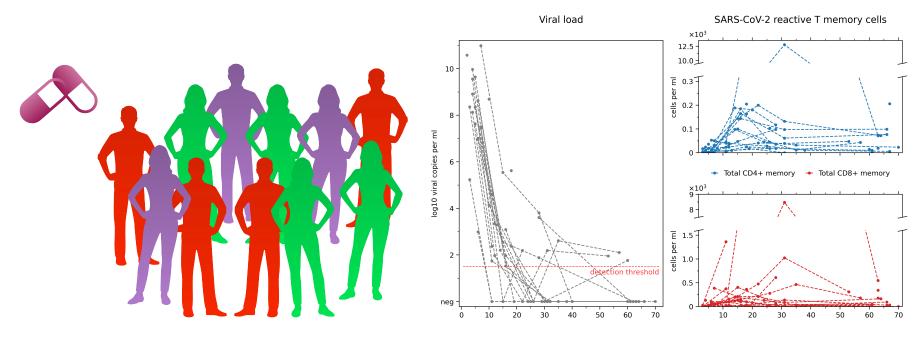
Biology is heterogeneous







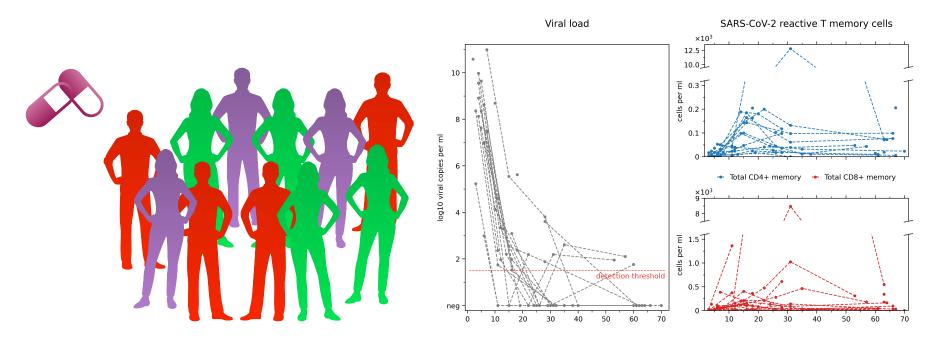
Biology is heterogeneous



We need methods to deal with this heterogeneity!



Biology is heterogeneous



How to describe hete Wegneed methods to ideas with this heterogeneity!





 $M(\phi_i)$ generative model for individual i $\phi_i = \theta_1 + b_i$

- Fixed Effects θ₁
 (e.g. mean effect of some drug)
- Random Effects $b_i \sim p_{\theta_2}(b)$ (variability of an effect)

Population Model $\phi \sim p(\phi \mid \theta)$ But observations are noisy





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Population Model $\phi \sim p(\phi \mid \theta)$ But observations are noisy

 \rightarrow all individuals must be estimated simultaneously



• What is the likelihood of observing $y_i = \bigcap_{i=1}^{n} using our model M(\phi)? \rightarrow p(y_i \mid \phi)$



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- How are random effects distributed? $\rightarrow p(\phi \mid \theta)$



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- How are random effects distributed? $\rightarrow p(\phi \mid \theta)$
- What is the likelihood of observing $\mathscr{D} = \bigoplus (\mathscr{D} \mid \theta)$

Random effects are unobserved quantities

$$p(\mathcal{D} \mid \theta) = \prod_{i} \int p(y_i \mid \phi) p(\phi \mid \theta) \, d\phi$$



Current Estimation Methods $p(\mathcal{D} \mid \theta) = \prod_{i} \int p(y_i \mid \phi) p(\phi \mid \theta) d\phi$

1. "Estimate" the missing variables ϕ_i

2. Find best parameters of the overall model



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We can do this

- Deterministically \rightarrow biased
- Stochastically \rightarrow computationally intensive



Deterministic Approach

$$p(\mathcal{D} \mid \theta) = \prod_{i} \int p(y_i \mid \phi) p(\phi \mid \theta) \, d\phi$$

Linearisation-based or Laplace methods

1. For every individual i

A. Estimate mode $\hat{\phi}_i$ of $p(y_i \mid \phi) p(\phi \mid \theta_t)$ based on the best current θ_t

B. Use approximation to the integral based on the mode $\hat{\phi}_i$

- 2. Compute likelihood for population
- 3. Repeat until convergence



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Biased, **unreliable** and sensitive

(Pinheiro 1994, Comets & Mentré 2001)



Stochastic Approach

$$p(\mathcal{D} \mid \theta) = \prod_{i} \int p(y_i \mid \phi) p(\phi \mid \theta) \, d\phi$$

Stochastic expectation maximisation algorithm (SAEM)

1. Expectation step

 $Q(\theta \mid \theta_t) = \mathbb{E}_{\phi \sim p(\phi \mid y_i, \theta_t)}[\log p(y_i \mid \phi) + \log p(\phi \mid \theta)]$

 $\phi \sim p(\phi \mid y_i, \theta_t)$ samples must be generated with a MCMC procedure



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$$\theta_{t+1} = \underset{\theta}{\operatorname{argmax}} Q(\theta \mid \theta_t)$$



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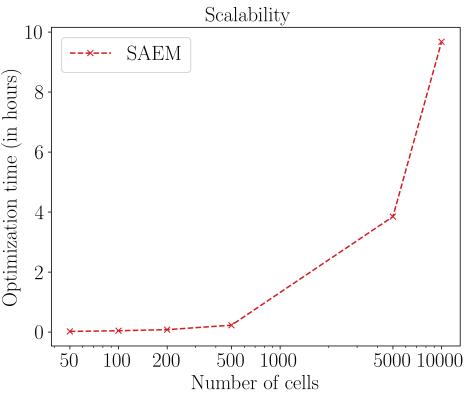
$$\theta_{t+1} = \underset{\theta}{\operatorname{argmax}} Q(\theta \mid \theta_t)$$

Refinement in every step: $\hat{Q}(\theta \mid \theta_t) = (1 - \lambda_t)\hat{Q}(\theta \mid \theta_{t-1}) + \lambda_t Q(\theta \mid \theta_t)$



Stochastic Expectation Maximisation Algorithm

- State of the art method
- EM provides unbiased estimates (Savic et. al. 2010)
- Computationally demanding
- Sensitive to initial values (local minima)

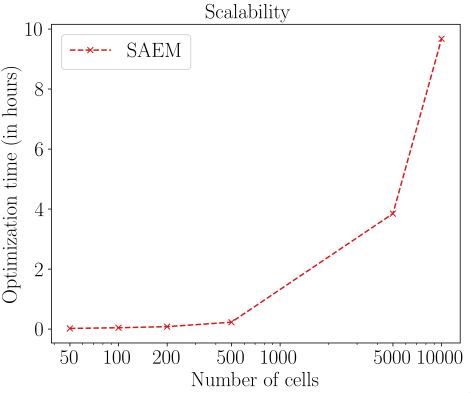




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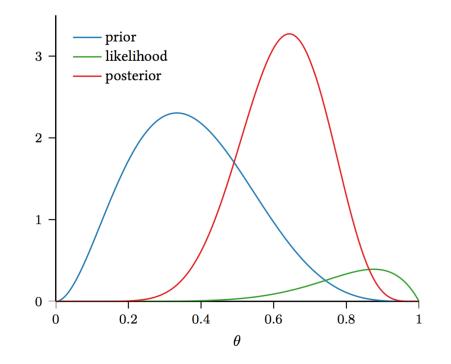
Can we be more scalable?





Bayesian Inference

- Posterior distribution $p(\phi \mid y) \propto p(y \mid \phi)p(\phi)$
- Computed with methods like Markov chain Monte Carlo methods (MCMC)
- Computationally demanding





• Back to $p(\mathcal{D} \mid \theta) = \prod_{i} \int p(y_i \mid \phi) p(\phi \mid \theta) d\phi$



• Back to $p(\mathcal{D} \mid \theta) = \prod_{i} \int \frac{p(y_i)p(\phi \mid y_i)}{p(\phi)} p(\phi \mid \theta) d\phi$

• Rewrite marginal likelihood $p(y_i \mid \phi)$ in terms of the individual-specific posterior distribution



Bayesian Approach for Single Individual

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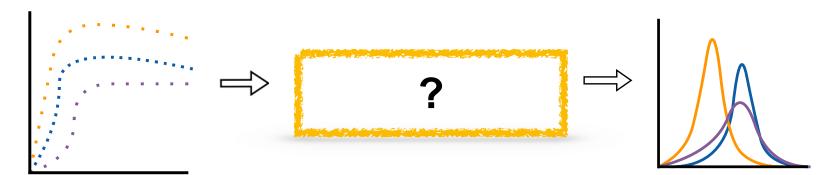
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$$\approx \arg\max_{\theta} \prod_{i} \sum_{\phi_{i,i} \sim p(\phi \mid y_i)} \left[\frac{p(\phi_{i,j} \mid \theta)}{p(\phi_{i,j})} \right]$$

• Use Monte-Carlo approximation by sampling from individual-specific posterior



How do we get the individual-specific posterior in a scalable way? Inference Phase

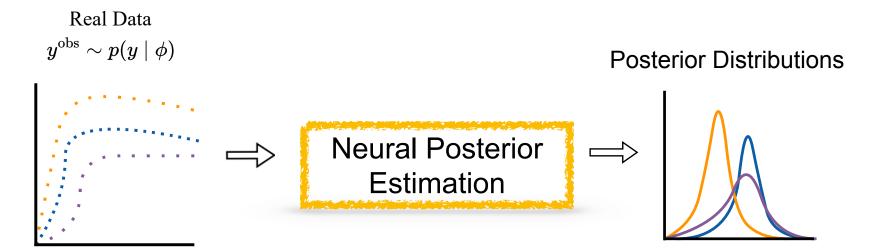
Real Data $y^{
m obs} \sim p(y \mid \phi)$





Posterior Distributions

How do we get the individual-specific posterior in a scalable way? Inference Phase





Neural Density Estimation

- Generative models
- Known for faithfully constructing e.g. portrait images



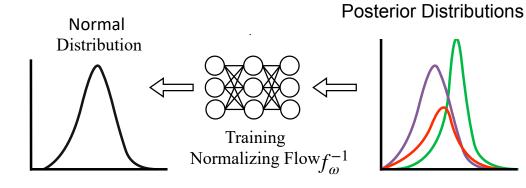


Training Data

Generated Data



Training Phase



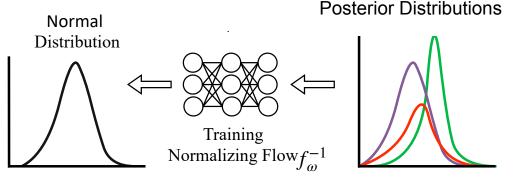


Amortized Inference Phase BayesFlow by Radev et. al. 2020

Conditional normalizing flows

- sample from Exemples the set ion $z \sim p(z)$
- get sample from desired distribution by invertible mappings $f_i(z)$

$$x = f_0(z) \circ f_1(z) \circ \cdots \circ f_n(z)$$



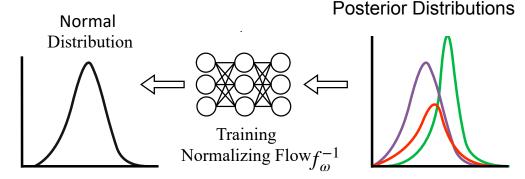


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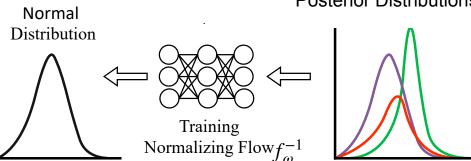


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- f_{ω} parameterized by invertible neural networks



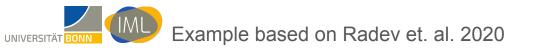


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Posterior Distributions

Example of Invertible Neural Networks

- affine coupling layers, split input $u = (u_1, u_2)$, s_i , t_i can be any neural network
 - $v_1 = u_1 \odot \exp(s_1(u_2)) + t_1(u_2)$
 - $v_2 = u_2 \odot \exp(s_2(v_1)) + t_2(v_1)$



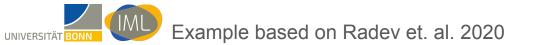
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• inversion

$$u_{2} = (v_{2} - t_{2}(v_{1})) \odot \exp(-s_{2}(v_{1}))$$
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• Jacobian of the affine transformation is a strictly upper or a lower triangular matrix \rightarrow easy to compute

Example based on Radev et. al. 2020

Learning a Normalizing Flow

Minimize **KL-divergence** between true posterior and approximation for all possible data y

 $\underset{\omega}{\arg\min} \mathbb{E}_{p(y)} \left[\text{KL} \left(p(\phi \mid y) \| p_{\omega}(\phi \mid y) \right) \right]$



Learning a Normalizing Flow

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=
$$\arg\max_{\omega} \iint p(y, \phi) \log p_{\omega}(\phi \mid y) \, dy \, d\phi$$



Minimize **KL-divergence** between true posterior and approximation for all possible data y

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Minimize **KL-divergence** between true posterior and approximation for all possible data y

$$\arg \max_{\omega} \iint p(y,\phi) \log p_{\omega}(\phi \mid y) \, dy \, d\phi$$
$$= \arg \max_{\omega} \iint p(y,\phi) (\log p(f_{\omega}(\phi, y)) + \log |\det J_{f_{\omega}}|) \, dy \, d\phi$$



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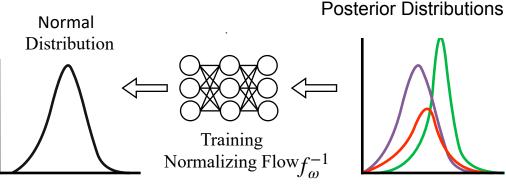
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We need sample pairs $(\phi^{(m)}, y^{(m)})!$

Neural Posterior Density Estimation

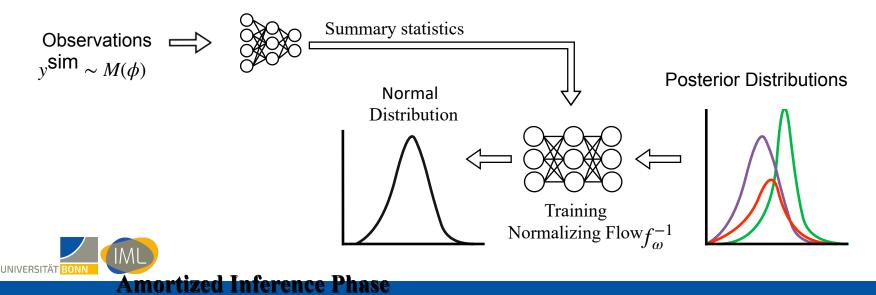
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- Generate samples ϕ from prior and produce simulations y^{sim}





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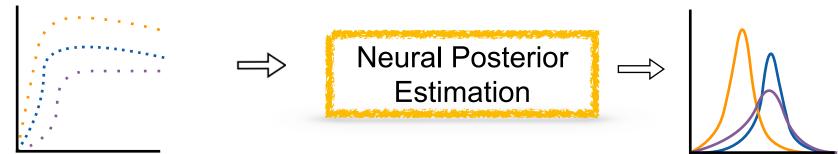


How do we get the individual-specific posterior in a scalable way?

Amor

 $egin{array}{l} {
m Real Data} \ y^{
m obs} \sim p(y \mid \phi) \end{array}$

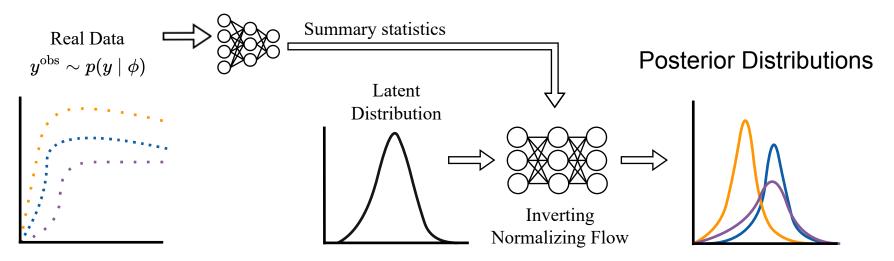
Posterior Distributions





How do we get the individual-specific posterior in a scalable way?

Amortized Inference Phase





sample from normal distribution and condition on real data

Choices to be made

- Depth of invertible neural networks
- Type of summary networks
- Duration of training (early stopping)
- Loss function (e.g. Wasserstein instead of KL-divergence)



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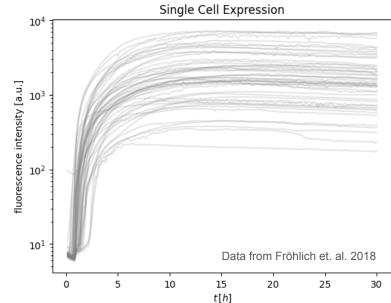
Other types of neural density estimators

- Conditional variational autoencoders (Kingma & Welling, 2022)
- Conditional generative adversarial neural networks (Wang & Ročková 2022)



Example Application

- living cells show molecular and phenotypic differences at the single-cell level
- mass cytometry can provide snapshots in thousands to millions of cells
- time-lapse microscopy measurements of **single-cells after transfection** with synthetic mRNA to assess mRNA lifetime



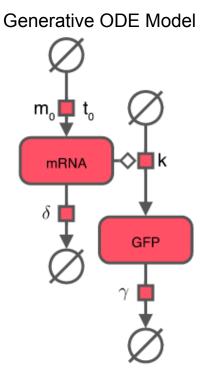


Amortized Approach to Non-Linear Mixed-Effects

1. Simulate individual cells with generative model from prior

2. Train neural density estimator with simulations

3. Infer population parameter from real data



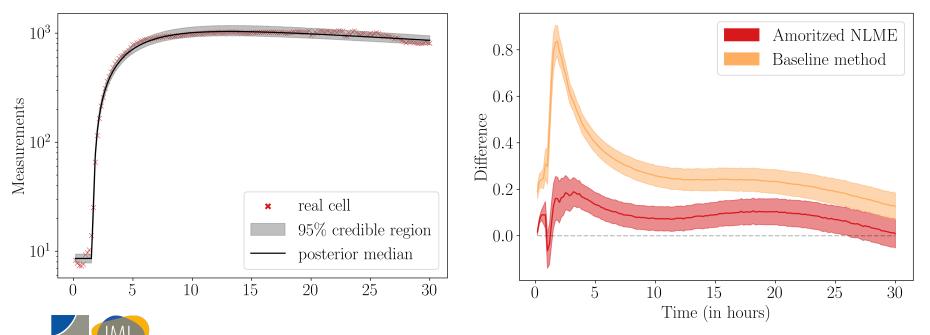


Inference Results

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Neural Density Estimator

Population Estimation



Current Limitations

Neural Density Estimator

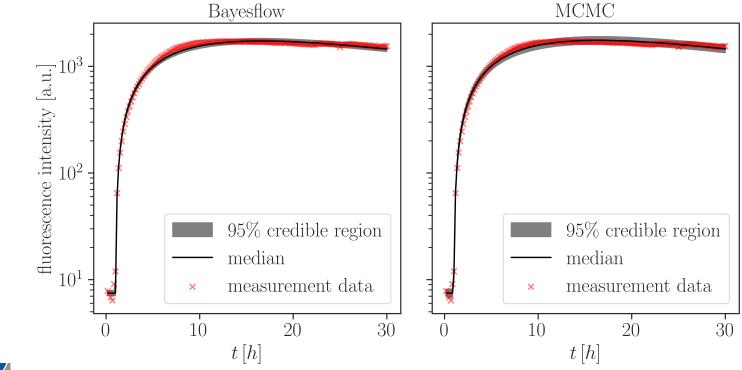
- Expressivity of the normalizing flow (Hagemann et. al. 2023)
- Misspecification of the model (Schmitt et. al. 2022)
- Non-conservative posteriors (Hermans et. al. 2022)

Population Estimation

• Robust inference of parameters with no variability



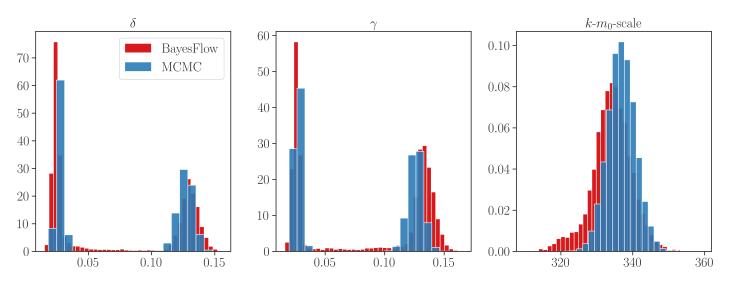
Comparison to MCMC





Comparison to MCMC

For ODE Model



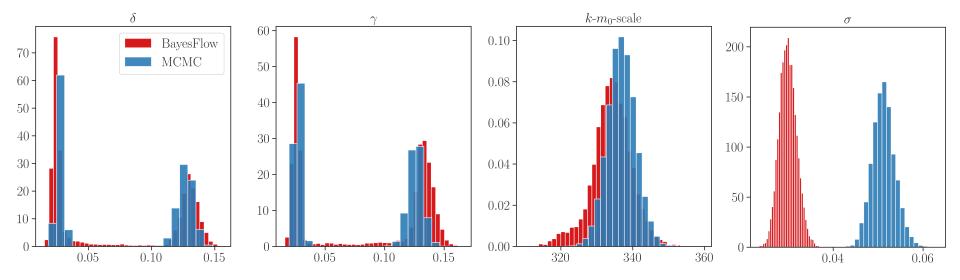


Sampling Time for Single Cell MCMC: 30min run time BayesFlow: 1s

Comparison to MCMC

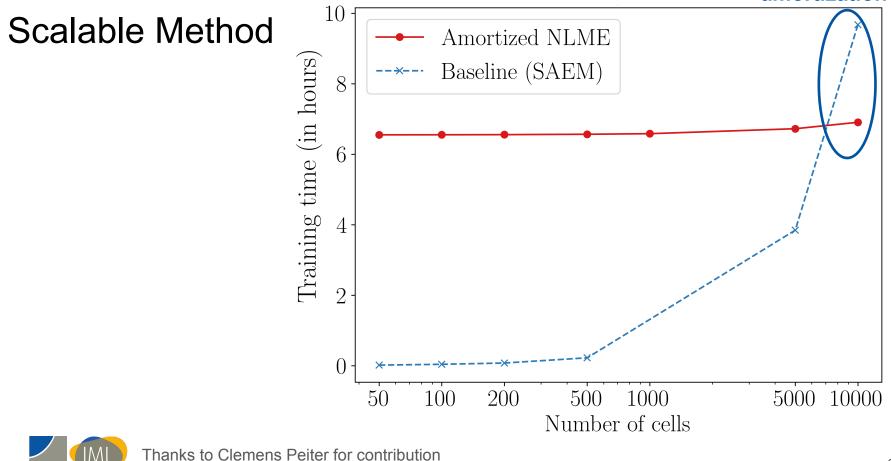
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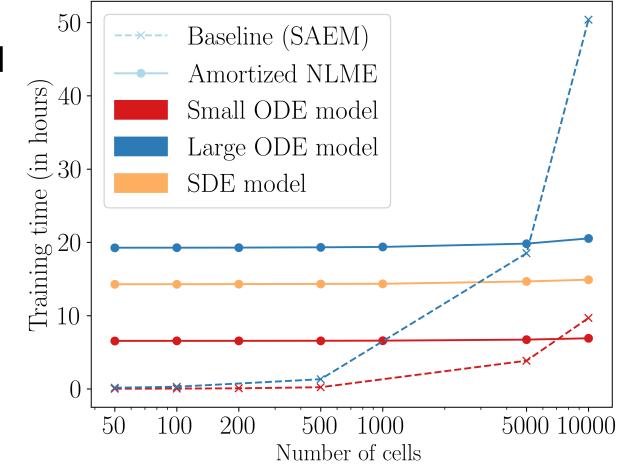


amortization



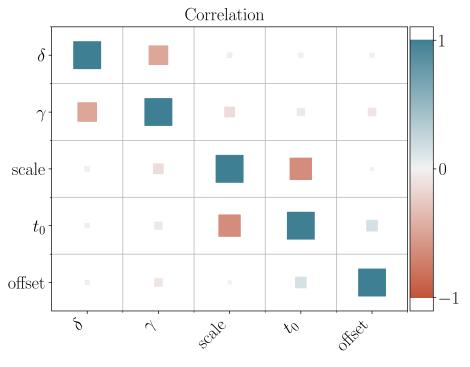
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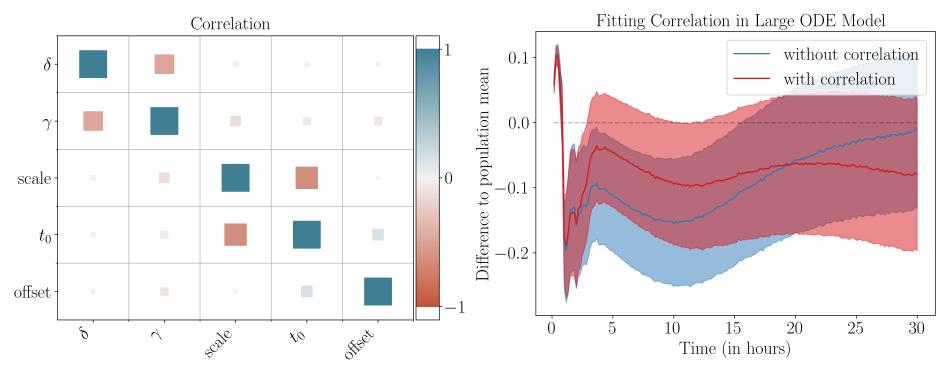


Flexible Method





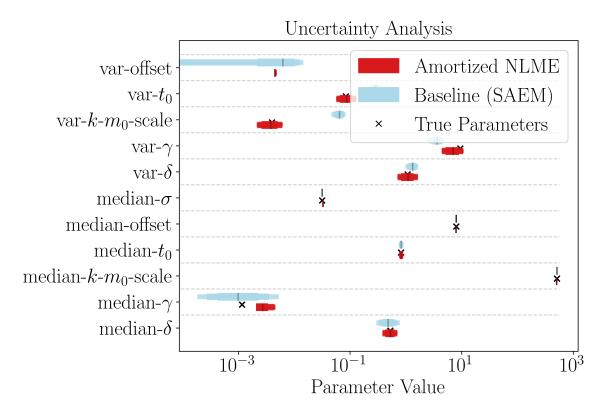
Flexible Method





Basically no additional computational cost!

Easy Uncertainty Analysis





Conclusion

Amortized Inference Phase

- Mixed effect models can describe heterogenous populations
- Scalable inference is computationally challenging
- Amortized approach by
 - Training a **neural posterior density estimator** on simulated data
 - Cheap inference
 - Flexible population model, uncertainty analysis, ...





Paper is coming soon :)

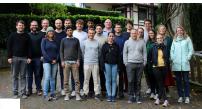








Federal Ministry of Education and Research



AG Prof. Hasenauer



jonas.arruda@uni-bonn.de



yannik.schaelte@uni-bonn.de

