

Optimal scaling for conditional sequential Monte Carlo methods in high dimensions

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Problem formulation

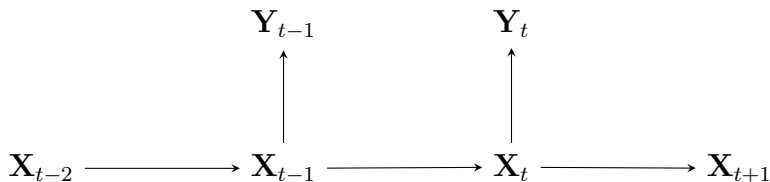
Background: CSMC algorithms (D fixed)

Breakdown of CSMC as $D \rightarrow \infty$

Novel 'random-walk' CSMC algorithm

Motivation: High-dimensional state-space model

- D -dimensional latent states: $\mathbf{X}_t = \begin{bmatrix} X_{t,1} \\ \vdots \\ X_{t,D} \end{bmatrix}$,
- T observations: $\mathbf{Y}_1, \dots, \mathbf{Y}_T$.



- want to approximate $\pi_{T,D}(\mathbf{x}_{1:T}) = p(\mathbf{x}_{1:T} | \mathbf{y}_{1:T})$,
- needs MCMC updates on $(T \times D)$ -dimensional space.

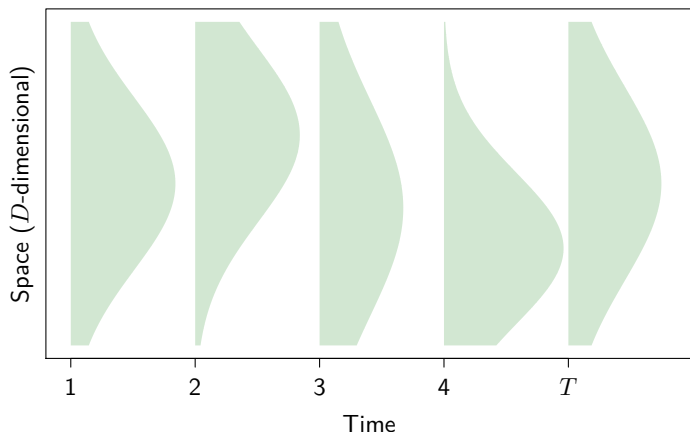
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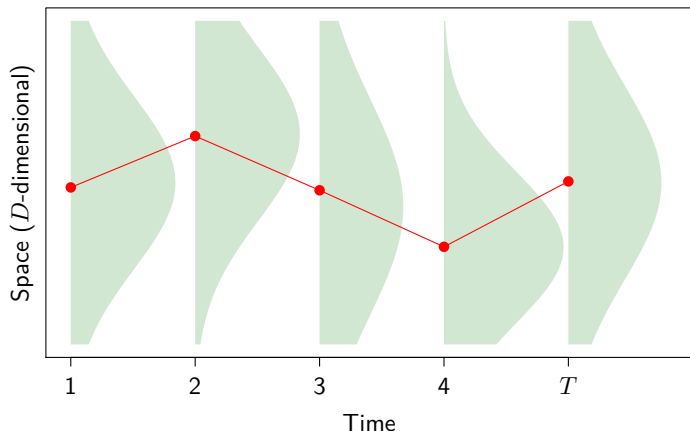
Novel 'random-walk' CSMC algorithm

CSMC algorithm



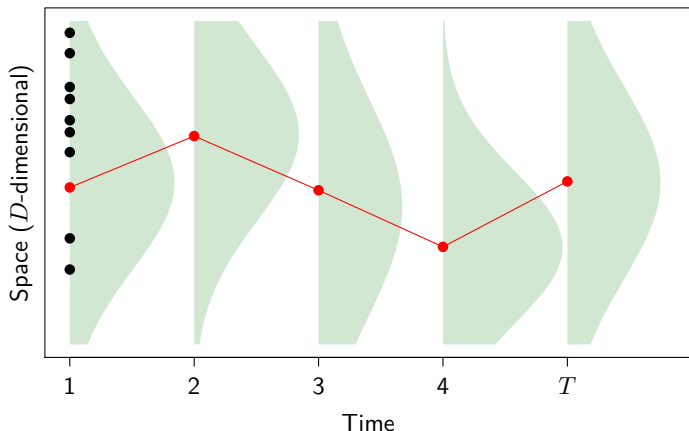
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- propagate N particles/particle lineages via
 - sampling ('mutation') from the model dynamics,
 - resampling ('selection') according to importance weights.

CSMC algorithm



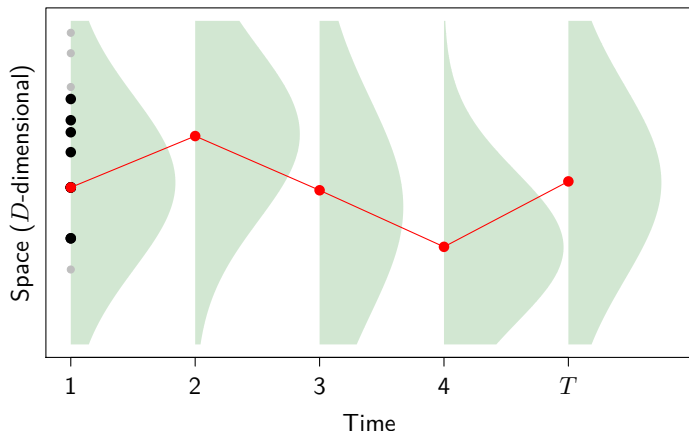
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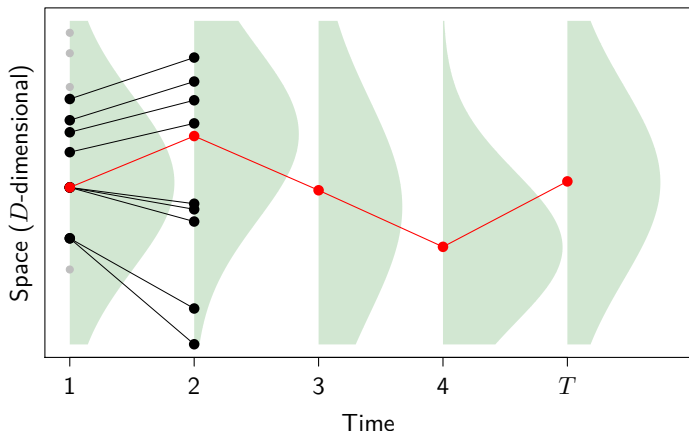
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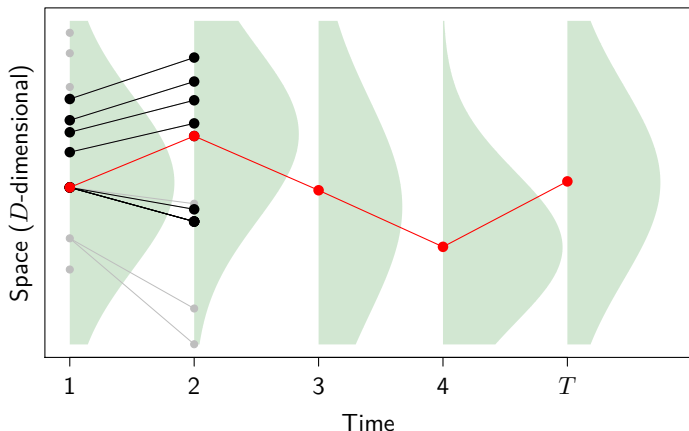
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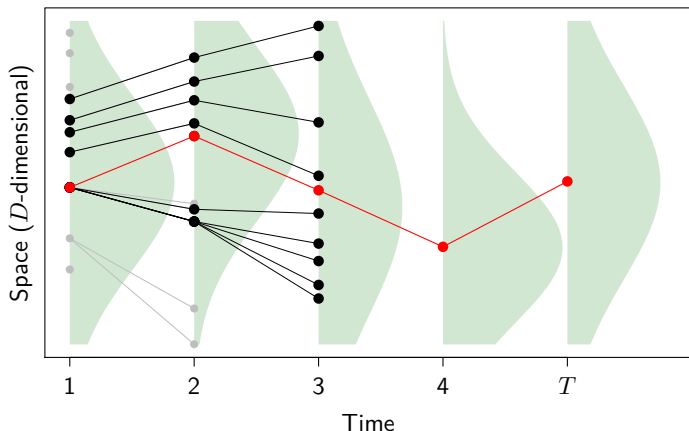
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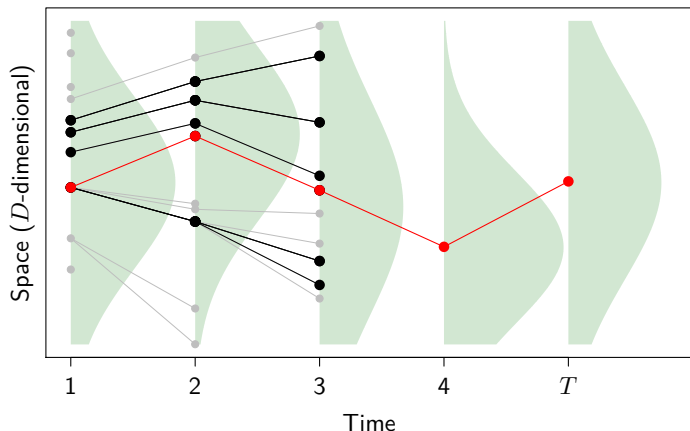
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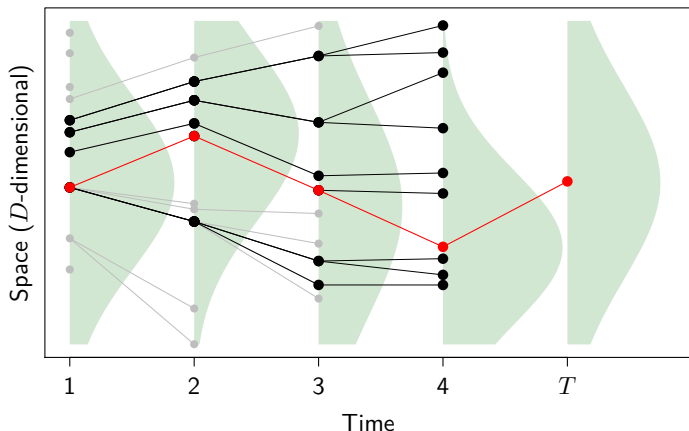
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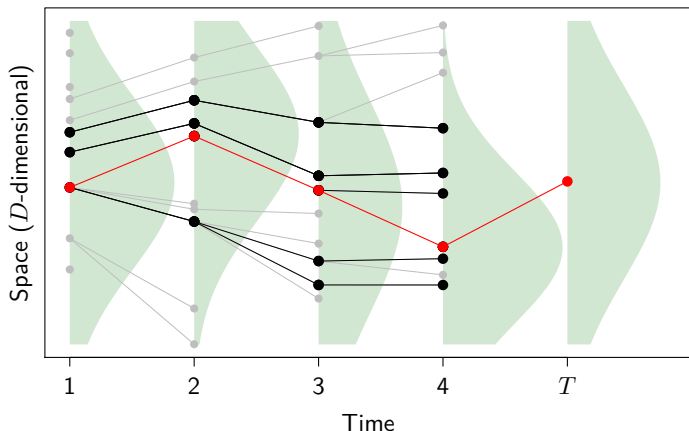
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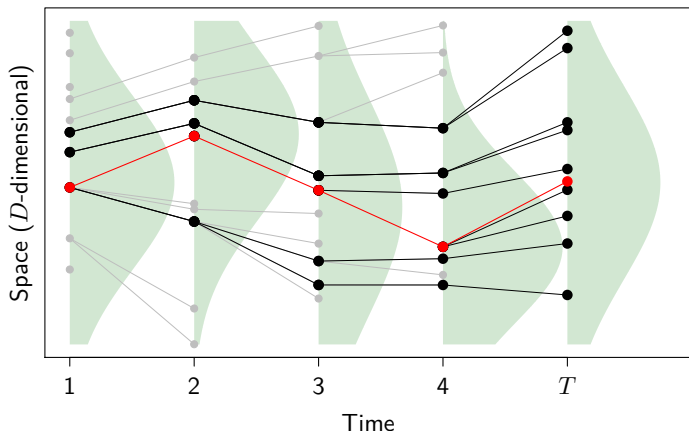
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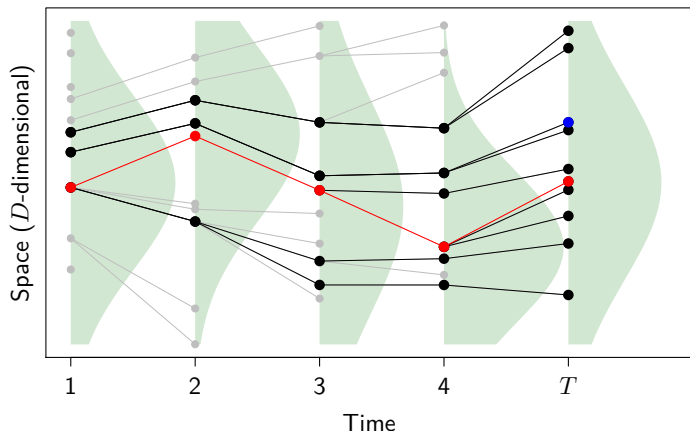
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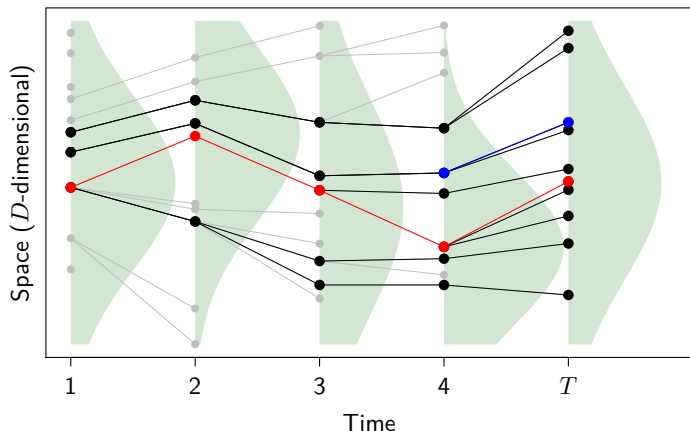
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CSMC algorithm: Selecting new reference path



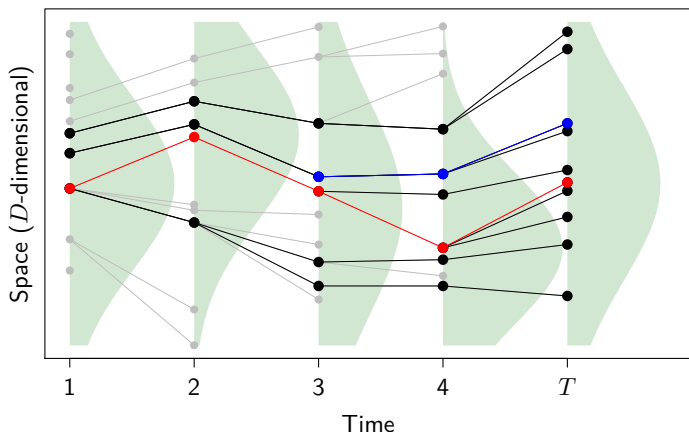
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- Problem: $\mathbf{x}_{1:T}$ coalescing with $\mathbf{x}_{1:T}$
 - controlling the ‘acceptance rates’ requires $N = O(T)$
(Andrieu et al., 2018; Koskela et al., 2018)

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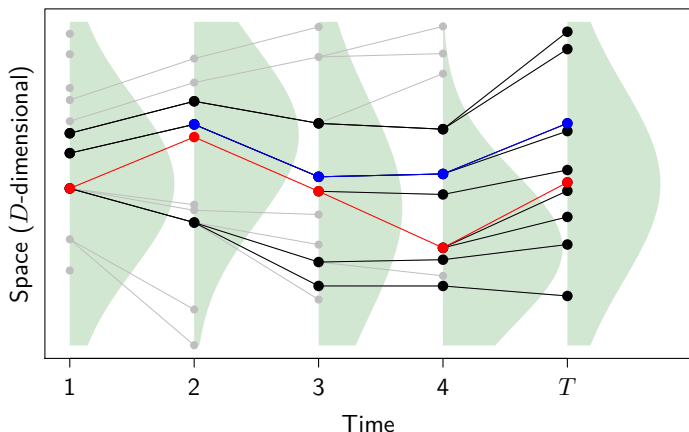
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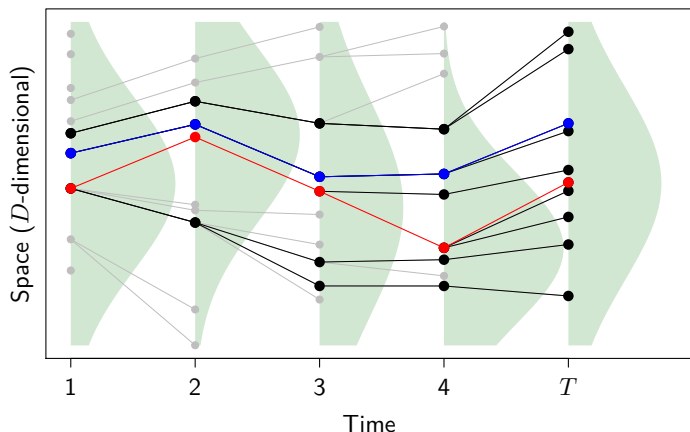
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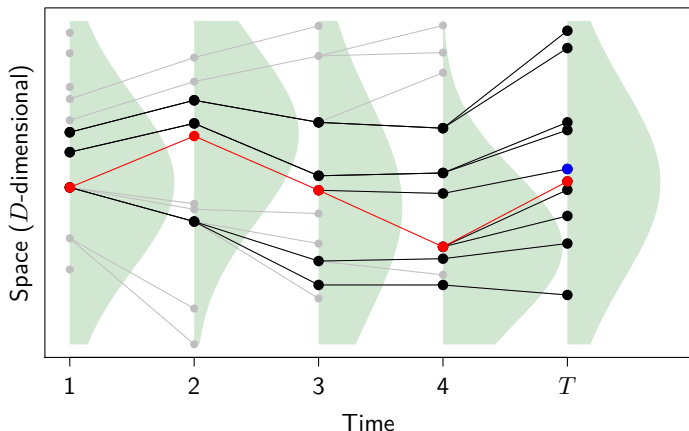
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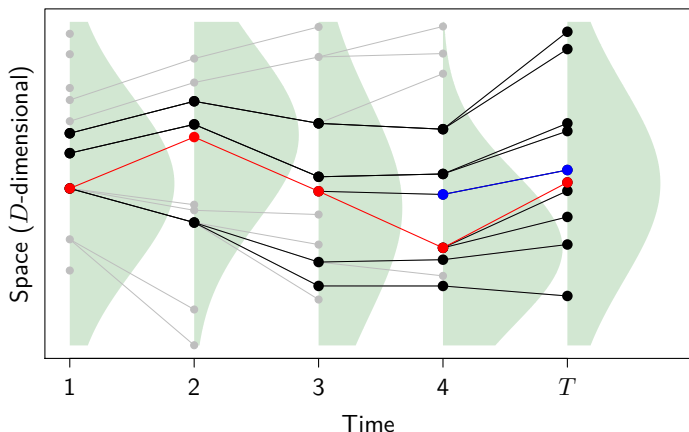
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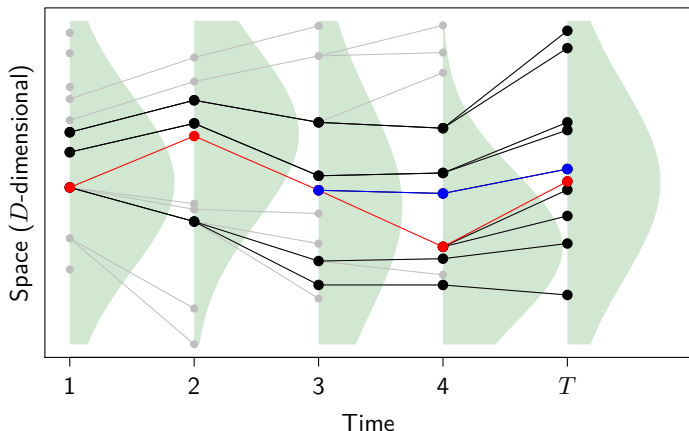
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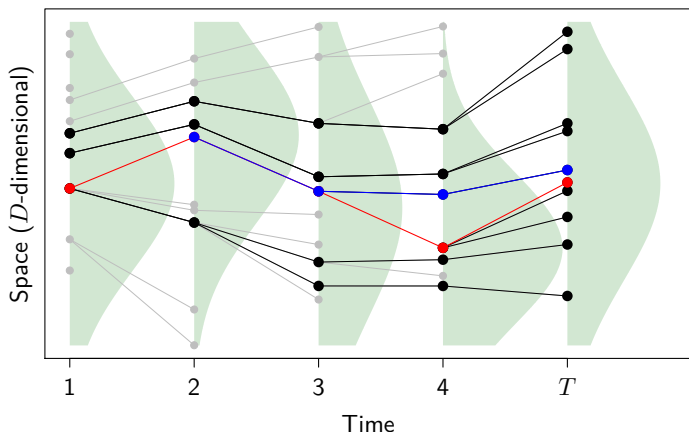
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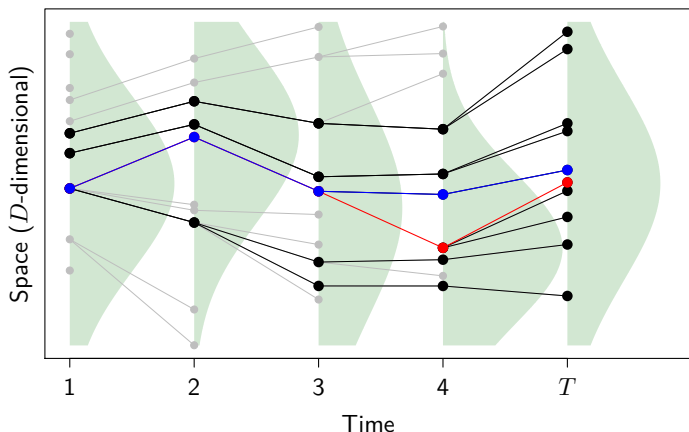
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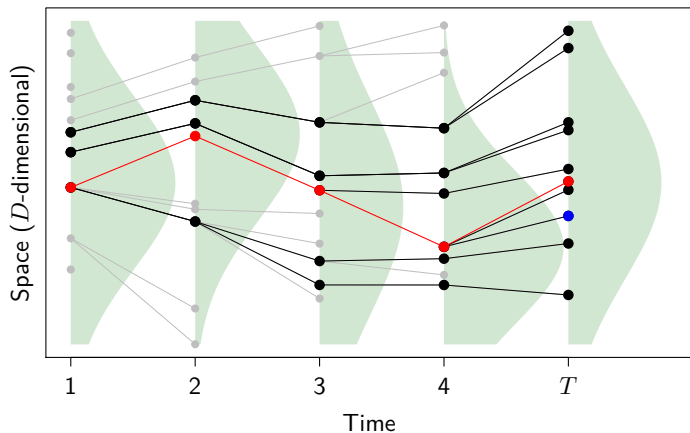
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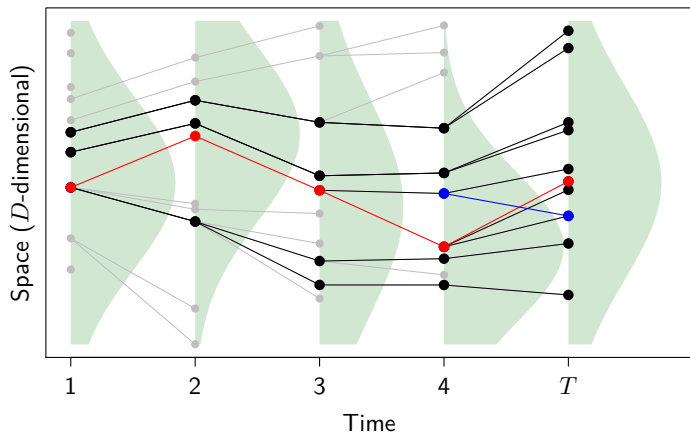
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CSMC algorithm: Backward-sampling extension



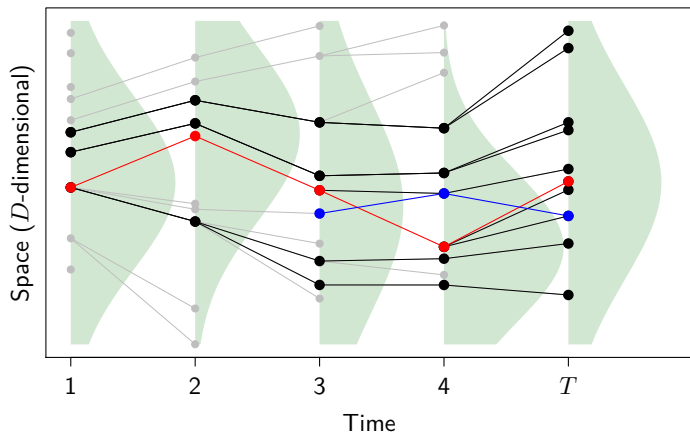
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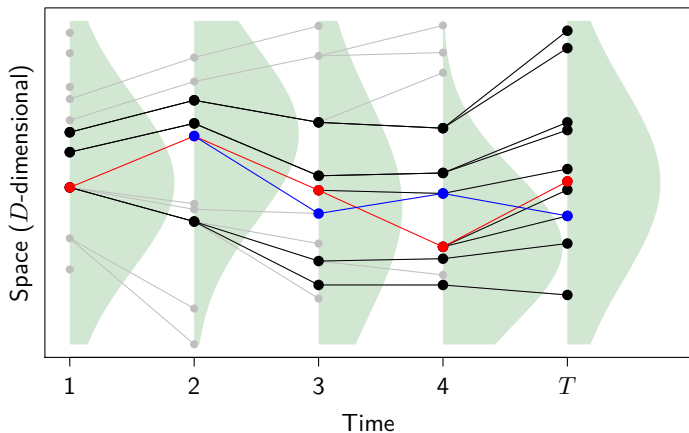
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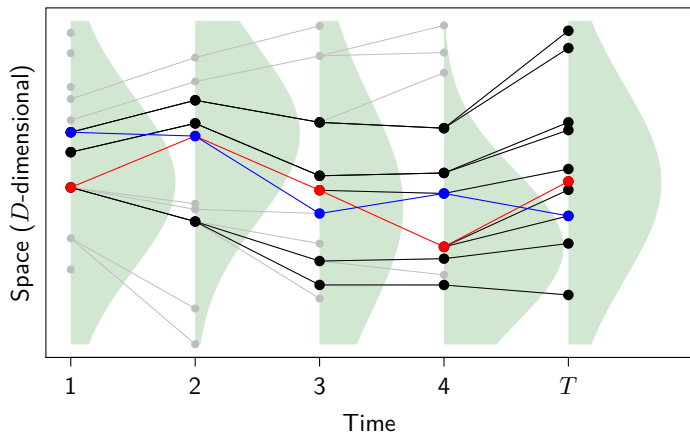
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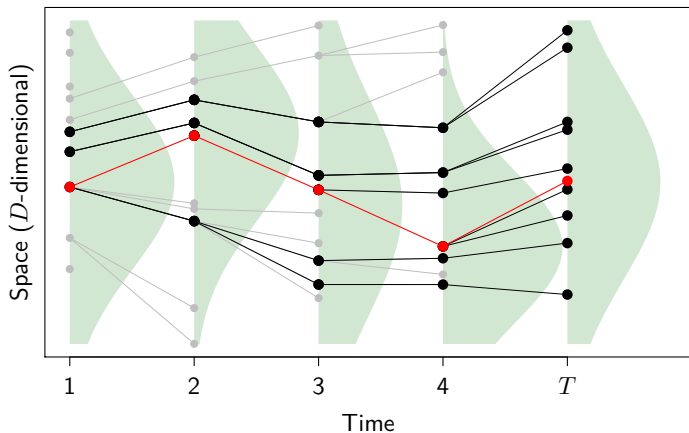
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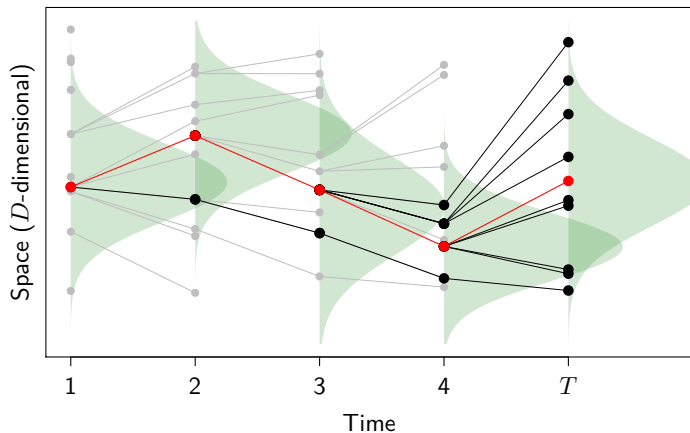
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CSMC in high dimensions ($D \rightarrow \infty$)



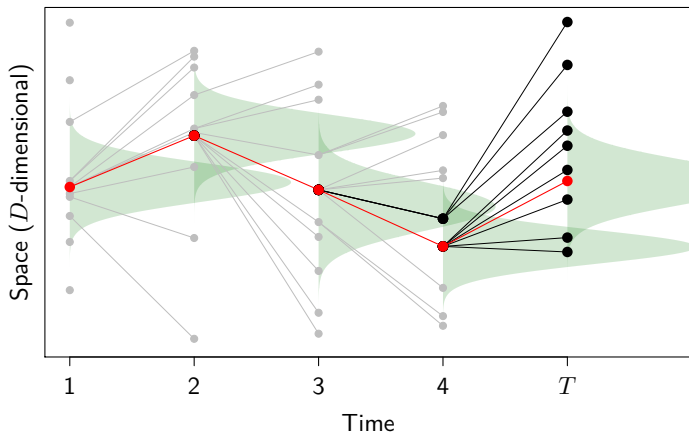
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CSMC in high dimensions ($D \rightarrow \infty$)



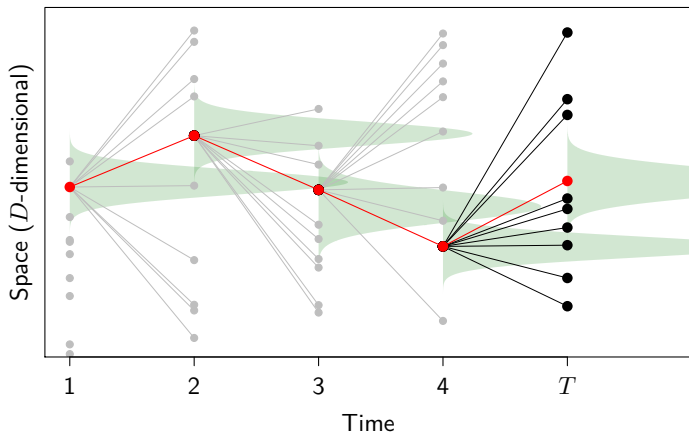
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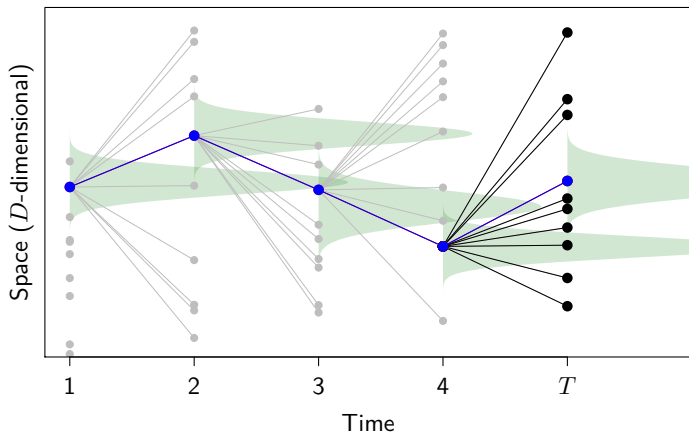
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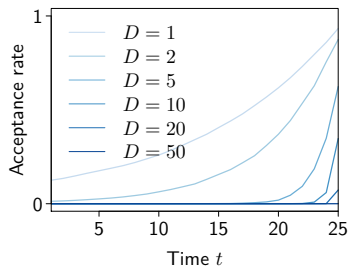
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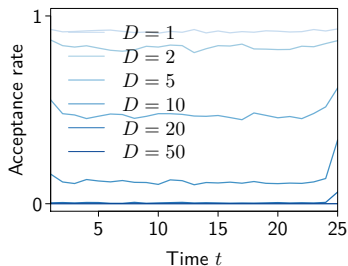


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Numerical illustration (state-space model)



CSMC



CSMC + backward sampling

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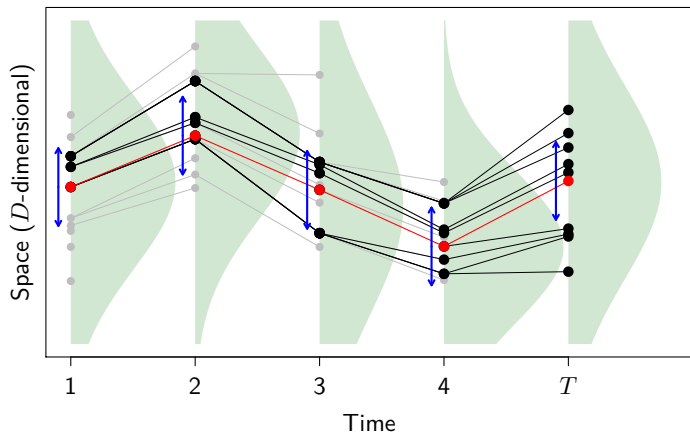
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Simple case: $T = N = 1$

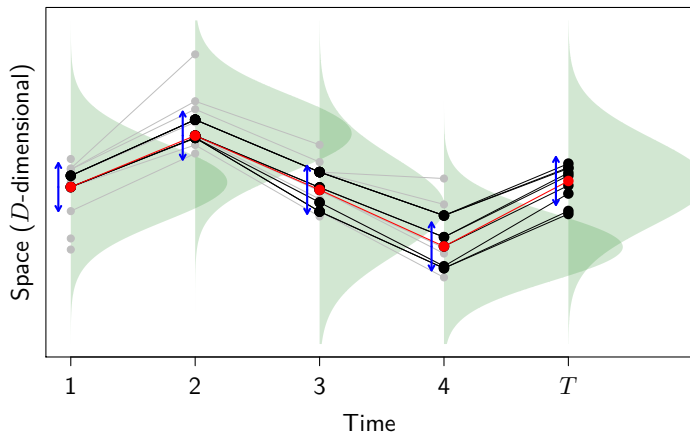
- CSMC reduces to **Independent Metropolis–Hastings**,
- **Problem:** ‘**global**’ proposals are difficult to design;
 - acceptance rate is typically $O(e^{-D})$.
- **Remedy:** suitably scaled ‘**local**’ proposals
 - e.g. random walk with variance σ^2/D ,
 - stabilises acceptance rate as $D \rightarrow \infty$.
- ‘**No free lunch**’: need $O(D)$ iterations
 - non-trivial (diffusion) limit (**Roberts et al., 1997**).
- Extension to $N > 1$ proposals in **Bédard et al. (2012)**.

Random-walk CSMC algorithm ($D \rightarrow \infty$)



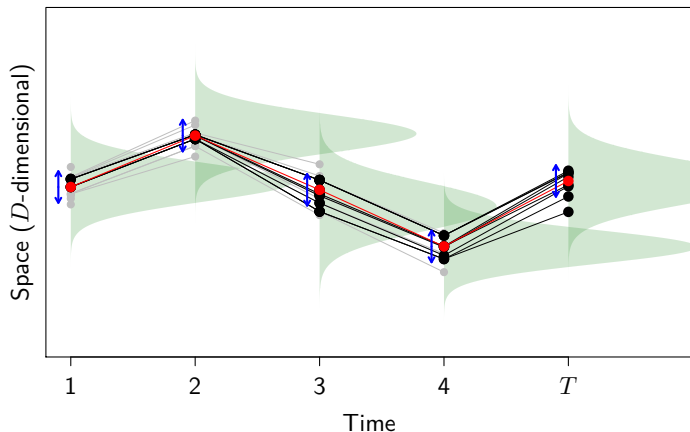
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Random-walk CSMC algorithm ($D \rightarrow \infty$)



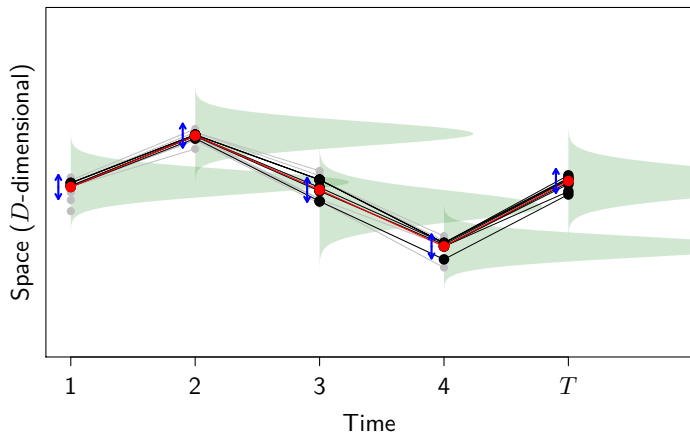
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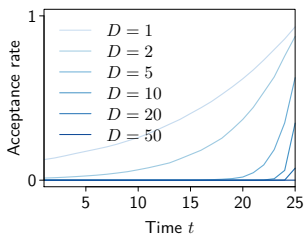
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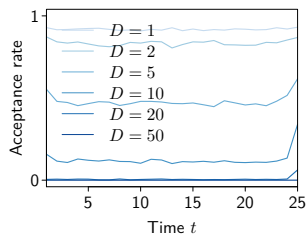


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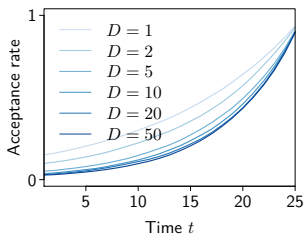
Numerical illustration (state-space model), ctd



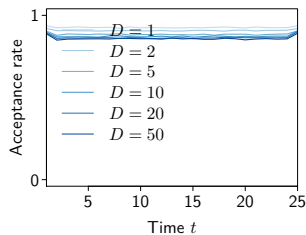
CSMC



CSMC + backward sampling

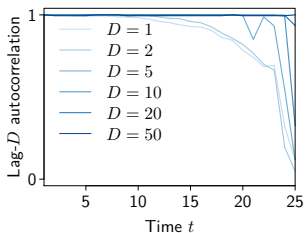


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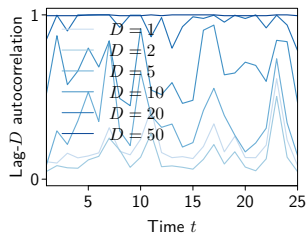


Random-walk CSMC
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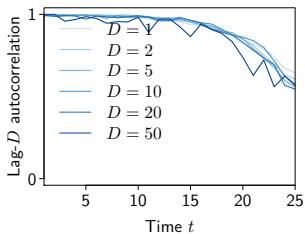
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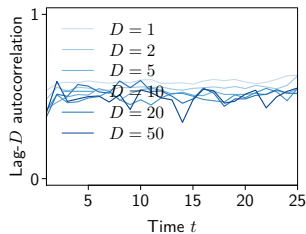
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Random-walk CSMC



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- Andrieu, C., Lee, A., and Vihola, M. (2018). Uniform ergodicity of the iterated conditional SMC and geometric ergodicity of particle Gibbs samplers. *Bernoulli*, 24(2):842–872.
- Bédard, M., Douc, R., and Moulines, E. (2012). Scaling analysis of multiple-try MCMC methods. *Stochastic Processes and their Applications*, 122(3):758–786.
- Koskela, J., Jenkins, P. A., Johansen, A. M., and Spano, D. (2018). Asymptotic genealogies of interacting particle systems with an application to sequential Monte Carlo. *ArXiv e-prints*, 1804.01811.
- Lee, A., Singh, S. S., and Vihola, M. (2018). Coupled conditional backward sampling particle filter. *ArXiv e-prints*, 1806.05852.
- Roberts, G. O., Gelman, A., and Gilks, W. R. (1997). Weak convergence and optimal scaling of random walk Metropolis algorithms. *The Annals of Applied Probability*, 7(1):110–120.