# Branching Processes Reading Group Spatial Pal-Bell Equation and Moment Asymptotic

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MaTHRad PostDoc Retreat Workshop



For a measure-valued process  $(X_t)_{t\geq i}$ , we define  $X_t[g] := \int g dX_t$ . If  $X_t := \sum \delta_{x_i(t)}, X_t[g] = \sum_i g(x_i(t))$ .

	$\psi_t[g](r,v)$	$v_t[g](r,v)$
Definition	$\mathbb{E}_{\delta_{r,v}}[X_t[g]]$	$\mathbb{E}_{\delta_{r,v}}[e^{-X_t[g]}]$
Describes	First Moment	Moment generating function
Semi-group	$\psi_{t+s}[g] = \psi_t(\psi_s[g])$	$v_{t+s}[g] = v_t(v_s[g])$

Table: Two important functions

Two important functions describing branching processes  $(X_t)_{t\geq 0}$ 

First moment from moment generating function:

$$\psi_t[g](r,v) = -\frac{d}{d\theta} v_t[\theta g](r,v) \bigg|_{\theta=0}$$
(1)

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Similarly, one can derive all moments of  $X_t[g]$  given an evolution equation of  $v_t[g](r, v)$ .

# **Evolution of** $v_t[g]$

To derive the evolution of  $v_t[g]$ , we condition on the first event (fission / scatter) for our neutron transport process until time t.

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Event	Probability	Contribution
No event / Exit	$e^{-\int_0^{t\wedge\kappa^D_{r,v}}\sigma(r+v\ell,v)d\ell}$	$e^{-g(r+vt,v)}1_{t<\kappa^D_{r,v}}+1_{t>\kappa^D_{r,v}}$
Scatter at <i>s</i>	$1_{s<\kappa}\sigma(r+vs,v)$	$\frac{\sigma_s}{\sigma}\int v_{t-s}(r+vs,v')\pi_s(r+vs,v,v')dv'$
Fission at <i>s</i>	$ imes e^{-\int_0^{\mathbf{s}} \sigma(r+v\ell,v) d\ell}$	$+ \frac{\sigma_f}{\sigma} \mathcal{E}_{r+vs,v} \left[ \prod_{i=1}^N v_{t-s}(r+vs,v_i) \right]$

Table: Probability Tables

## **Evolution of** $v_t[g]$



Event	Probability	Contribution
No event / Exit	$e^{-\int_0^{t\wedge\kappa_{r,v}^D}\sigma(r+v\ell,v)d\ell}$	$e^{-g(r+vt,v)}1_{t<\kappa^D_{r,v}}+1_{t>\kappa^D_{r,v}}$
Scatter at <i>s</i>	$1_{s<\kappa}\sigma(r+vs,v)$	$U_s \left[ Sv_{t-s} \right]$
Fission at <i>s</i>	$ imes e^{-\int_0^{s} \sigma(r+v\ell,v)d\ell}$	$\left[+G\left[v_{t-s}\right]\right]$



Combining terms and defining the operators appropriately (in particular subsuming the potential terms  $e^{-\int_0^s \cdots}$  into the operators), we have

$$v_t[g] = \hat{U}_t[e^{-g}] + \int_0^t U_s\left[Sv_{t-s}[g] + G[v_{t-s}[g]]\right] ds.$$
(2)

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### **Spatial Correlation**

- If  $g = 1_A$ ,  $v_t[g]$  helps us understand all the moments, and thus the law of  $X_t(A)$ .
- How about spatial correlation  $\mathbb{E}[X_t(A)X_t(B)]$ ?
- Characterised by correlation of non-local branching, i.e,  $\mathcal{V}[f,g](r,v) = \mathbb{E}[\sum_{i \neq j} f(r,v_i)g(r,v_j)]$

## **Spatial Correlation**

#### Note that

$$2\mathbb{E}[X_t[f]X_t[g]] = \mathbb{E}[X_t[f+g]^2] - \mathbb{E}[X_t[f]^2] - \mathbb{E}[X_t[g]^2],$$
(3)

so it suffices to consider expressions for  $w_t[g](r, v) := \mathbb{E}_{\delta_{r,v}}[X_t[g]^2]$  in general. Again we condition on first fission / scattering event.

Event	Probability	Contribution
No event / Exit	$e^{-\int_0^{t\wedge\kappa^D_{r,v}}\sigma(r+v\ell,v)d\ell}$	$\underline{g^2}(r+vt,v)1_{t<\kappa^D_{r,v}}$
Scatter at s	$1_{s<\kappa}\sigma(r+vs,v)$	$\frac{\sigma_s}{\sigma}\int w_{t-s}(r+vs,v')\pi_s(r+vs,v,v')dv'$
Fission at <i>s</i>	$ imes e^{-\int_0^{\mathbf{s}}\sigma(r+\mathbf{v}\ell,\mathbf{v})d\ell}$	$+ \frac{\sigma_{f}}{\sigma} \mathcal{E}_{r+vs,v} \left[ \mathbb{E} \left[ \left( \sum_{i=1}^{N} X_{t-s}^{i}[g] \right)^{2} \right] \right]$

Table: Probability Tables



## **Spatial Correlation**



$$\mathcal{E}_{r+vs,v}\left[\mathbb{E}\left[\left(\sum_{i=1}^{N} X_{t-s}^{i}[g]\right)^{2}\right]\right] = \mathcal{E}_{r+vs,v}\left[\mathbb{E}\left[\sum_{i\neq j} X_{t-s}^{i}[g]X_{t-s}^{j}[g] + \sum_{i=1}^{N} X_{t-s}^{i}[g]^{2}\right]\right]\right]$$
$$= \sum_{i\neq j} \psi_{t-s}[g](r+vs,v_{i})\psi_{t-s}[g](r+vs,v_{j})$$
$$+ \sum_{i=1}^{N} w_{t-s}[g](r+vs,v_{i})$$
(4)

### **Spatial Correlation**



Combining the terms above, we have that  $w_t[g](r, v)$  must solve

$$w_{t}[g](r,v) = U_{t}[g^{2}](r,v) + \int_{0}^{t} U_{s}\left[(S+F)w_{t-s}[g]\right](r,v)ds + \int_{0}^{t} U_{s}\left[\sigma_{f}\mathcal{V}[\psi_{t-s}[g]]\right](r,v)ds$$
$$= U_{t}[g^{2}](r,v) + \int_{0}^{t} U_{s}\left[\sigma_{f}\mathcal{V}[\psi_{t-s}[g]] + (S+F)w_{t-s}[g]\right](r,v)ds.$$
(5)

One could interpret the term  $\sigma_f \mathcal{V}[\psi_{t-s}[g]]$  as independent masses / contribution immigrated into the system at time s. Therefore,

$$w_t[g](r,v) = \psi_t[g^2](r,v) + \int_0^t \psi_s \bigg[ \sigma_f \mathcal{V}[\psi_{t-s}[g]] \bigg](r,v) ds.$$
(6)



Interpretation: The variance of the system at time t, given by,

 $w_t[g](r,v) - \psi_t[g^2](r,v),$ 

is the sum  $(\int)$  of the mean evolution  $(\psi_s)$  of the local branching correlation  $(\sigma_f \mathcal{V}[\psi_{t-s}[g]])$  along the process.

#### Asymptotic of 2nd Moments



If 
$$\lambda_* > 0$$
, for  $w_t[g](r, v) = \psi_t[g^2](r, v) + \int_0^t \psi_s \left[ \sigma_f \mathcal{V}[\psi_{t-s}[g]] \right](r, v) ds$ ,

$$\lim_{t \to \infty} e^{-2\lambda_* t} w_t[g](r, v) = \langle \tilde{\varphi}, g \rangle^2 \int_0^\infty e^{-2\lambda_* s} \psi_s[\sigma_f \mathcal{V}[\varphi]](r, v) ds \tag{7}$$

Heuristics: By Perron-Frobenius results,  $\psi_t[g^2] \sim e^{\lambda_* t}$ , so first term goes to zero. Furthermore,  $\psi_{t-s}[g] = e^{\lambda_*(t-s)} \langle \tilde{\varphi}, g \rangle \varphi + o(e^{\lambda_* t})$ ,  $\mathcal{V}$  is symmetric bilinear form, so  $\mathcal{V}[\psi_{t-s}[g]] = e^{2\lambda_*(t-s)} \langle \tilde{\varphi}, g \rangle^2 \mathcal{V}[\varphi] + o(e^{2\lambda_* t})$ . Therefore

$$e^{-2\lambda_*t}\int_0^t\psi_s\bigg[\sigma_f\mathcal{V}[\psi_{t-s}[g]]\bigg](r,v)ds=\int_0^te^{2\lambda_*(-s)}\langle\tilde{\varphi},g\rangle^2\psi_s[\mathcal{V}[\varphi]]ds+o(1)$$

## Asymptotic of 2nd Moments

If 
$$\lambda_* < 0$$
, we write  $\int_0^t \psi_s \left[ \sigma_f \mathcal{V}[\psi_{t-s}[g]] \right](r, v) ds = \int_0^t \psi_{t-s} \left[ \sigma_f \mathcal{V}[\psi_s[g]] \right](r, v) ds$ , then

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$$e^{-\lambda_{*}t} \int_{0}^{t} \psi_{t-s} \left[ \sigma_{f} \mathcal{V}[\psi_{s}[g]] \right](r, v) ds$$
  
$$= e^{-\lambda_{*}t} \int_{0}^{t} e^{\lambda_{*}(t-s)} \varphi(r, v) \langle \tilde{\varphi}, \sigma_{f} \mathcal{V}[\psi_{s}[g]] \rangle + o(e^{\lambda_{*}(t-s)}) ds$$
  
$$= \int_{0}^{t} e^{\lambda_{*}(-s)} \varphi(r, v) \langle \tilde{\varphi}, \sigma_{f} \mathcal{V}[\psi_{s}[g]] \rangle ds + o(1) \quad (8)$$

Finally,  $e^{-\lambda_* t} \psi_t[g^2](r, v) \rightarrow \varphi \langle \tilde{\varphi}, g^2 \rangle$ , so

$$e^{-\lambda_* t} w_t[g](r,v) o arphi \langle ilde{arphi}, g^2 
angle + \int_0^t e^{-\lambda_* s} arphi(r,v) \langle ilde{arphi}, \sigma_f \mathcal{V}[\psi_s[g]] 
angle ds.$$

#### Asymptotic of 2nd Moments



If  $\lambda_*=$  0, first term goes to 0 after rescaling by 1/t, and

$$\frac{1}{t} \int_{0}^{t} \psi_{t-s} \left[ \sigma_{f} \mathcal{V}[\psi_{s}[g]] \right](r, v) ds$$

$$= \frac{1}{t} \int_{0}^{t} \left\{ \varphi(r, v) \langle \tilde{\varphi}, \sigma_{f} \mathcal{V}[\varphi \langle \tilde{\varphi}, g \rangle] \right\} + o(1) \right\} ds$$

$$= \frac{1}{t} \int_{0}^{t} \varphi(r, v) \langle \tilde{\varphi}, g \rangle^{2} \langle \tilde{\varphi}, \sigma_{f} \mathcal{V}[\varphi] \rangle ds + o(1)$$

$$= \varphi(r, v) \langle \tilde{\varphi}, g \rangle^{2} \langle \tilde{\varphi}, \sigma_{f} \mathcal{V}[\varphi] \rangle. \quad (9)$$



What about k-th moment?

$$\psi_t^{(k)}[g](r,v) = (-1)^k \frac{d^k}{d\theta^k} v_t[\theta g](r,v) \bigg|_{\theta=0}$$
(10)

- The evolution equation of the k-th moment can be written in terms of that for lower moments through applying product rule k-times
- Moral of the story: Growth of k-th moment is e<sup>λ<sub>\*</sub>kt</sup> for supercritical, e<sup>-λ<sub>\*</sub>t</sup> for subcritical, t<sup>-k</sup> for critical processes.
- More exotic results for the occupational measure: e<sup>λ<sub>\*</sub>kt</sup> for supercritical, O(1) for subcritical, O(t<sup>-2k-1</sup>) for critical



## **Optional Extra Discussion - Applications in Nuclear Engineering**



▶ *I* precursors, neutron source of strength  $S_d(s)$ 



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- >  $N_S(t|s)$ : descendent neutrons at t from immigrated neutrons at s



#### **Perron-Frobenius:**

▶ There exists a  $\mathbb{R}$ -valued  $Z_\infty$  and  $\rho > 0$  such that  $N_S(t|s) \to e^{\rho t} Z_\infty$ 

**Operation Requirement:** For some threshold  $n^*$ , and  $\epsilon = 10^{-8}$ , find appropriate  $S_d(s)$  such that

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- ▶ for large  $t \ge t_{mat}$ ,  $\mathbb{P}[N_S(t|s) \le n] \approx \mathbb{P}[Z_{\infty} < \frac{n}{e^{\rho t}}]$
- ▶ The maturity time  $t_{mat}$  defined when for all  $t \ge t_{mat}$ ,

$$rac{\sqrt{Var[N_{\mathcal{S}}(t|s)]}}{\mathbb{E}[N_{\mathcal{S}}(t|s)]} < 0.001$$

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$$-\frac{\partial G(z,t|s)}{\partial s} = \lambda_c(s) - (\lambda_c(s) + \lambda_f(s))G(z,t|s) + \lambda_f(s)f(G(z,t|s))\prod_{i=1}^{I} f_i(G_{di}(z,t|s))$$
(7)

$$-\frac{\partial G_{di}(z,t|s)}{\partial s} = -\lambda_i G_{di}(z,t|s) + \lambda_i G(z,t|s), \quad i = 1, 2, \dots I$$
(8)

$$-\frac{\partial G_{\rm S}(z,t|s)}{\partial s} = S_d(s)[f_q(G(z,t|s)) - 1]G_{\rm S}(z,t|s)$$
(9)

Pal-Bell equation [WE17]



Operation Requirement: In [WE17], one can show that

$$\mathbb{P}[N_{S}(t|s) \leq n^{*}] = \sum_{k=1}^{n^{*}} \frac{1}{n!} \frac{\partial^{n}}{\partial z^{n}} G_{S}(z, t|s) \Big|_{z=0}$$
  
$$= \frac{1}{2\pi i} \oint G_{S}(z, t|s) \sum_{k=1}^{n^{*}} \frac{1}{z^{k+1}} dz \qquad (11)$$
  
$$= \frac{1}{2\pi i} \oint G_{S}(z, t|s) \sum_{k=1}^{n^{*}} \frac{z}{(1-z)z^{n^{*}+1}} dz,$$

which can be calculated with numerical methods (saddle point methods).



## **OPEN PROBLEMS**



# There is a similar Pal-Bell equation for the spatial case, with the PGF $G(z, t, R | \vec{r_0}, \vec{v_0}, s)$ . **Problems solved:**

Characterising spatial variations (achieved only through diffusion approximation)



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- Establishing Perron-Frobenius limiting results



#### General theory of BPS with Immigration

Construct general multi-type spatial branching process with immigration (DONE)



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## **Branching Particle System theory**



## General theory of BPS with Immigration

- Construct general multi-type spatial branching process with immigration (DONE)
- Moment calculations of system (Partial Done)
- Doob's L<sup>p</sup>-inequality to control running supremum
- Calculate spatial clustering by computing  $\mathbb{E}[\langle f, \mu \rangle \langle g, \mu \rangle]$



Implementation of simulations in SCONE



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- Characterise spatial variations



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