

OPTIMAL CO-ADAPTED COUPLING FOR THE SYMMETRIC RANDOM WALK ON THE HYPERCUBE

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Abstract

Let X and Y be two simple symmetric continuous-time random walks on the vertices of the n -dimensional hypercube, \mathbb{Z}_2^n . We consider the class of co-adapted couplings of these processes, and describe an intuitive coupling which is shown to be the fastest in this class.

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1. Introduction

Let \mathbb{Z}_2^n be the group of binary n -tuples under coordinate-wise addition modulo 2: this can be viewed as the set of vertices of an n -dimensional hypercube. For $x \in \mathbb{Z}_2^n$, we write $x = (x(1), \dots, x(n))$, and define elements $\{e_i\}_{i=1}^n$ by

$$e_0 = (0, \dots, 0); \quad e_i(k) = \mathbf{1}_{[i=k]}, \quad i = 1, \dots, n,$$

where $\mathbf{1}$ denotes the indicator function. For $x, y \in \mathbb{Z}_2^n$ let

$$|x - y| = \sum_{i=1}^n |x(i) - y(i)|$$

denote the Hamming distance between x and y .

A continuous-time random walk X on \mathbb{Z}_2^n may be defined using a marked Poisson process Λ of rate n , with marks distributed uniformly on the set $\{1, 2, \dots, n\}$: the i^{th} coordinate of X is flipped to its opposite value (zero or one) at incident times of Λ for which the corresponding mark is equal to i . We write $\mathcal{L}(X_t)$ for the law of X at time t . The unique equilibrium distribution of X is the uniform distribution on \mathbb{Z}_2^n .

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Suppose that we now wish to couple two such random walks, X and Y , starting from different states.

Definition 1.1. A *coupling* of X and Y is a process (X', Y') on $\mathbb{Z}_2^n \times \mathbb{Z}_2^n$ such that

$$X' \stackrel{\mathcal{D}}{=} X \quad \text{and} \quad Y' \stackrel{\mathcal{D}}{=} Y.$$

That is, viewed marginally, X' behaves as a version of X , and Y' as a version of Y .

For any coupling strategy c , write (X_t^c, Y_t^c) for the value at t of the pair of processes X^c and Y^c driven by strategy c , although this superscript notation may be dropped when no confusion can arise. (We assume throughout that (X^c, Y^c) is a coupling of X and Y .) We then define the coupling time by

$$\tau^c = \inf \{t \geq 0 : X_s^c = Y_s^c \quad \forall s \geq t\}.$$

Note that in general this is not necessarily a stopping time for either of the marginal processes, nor even for the joint process. For $t \geq 0$, let

$$U_t^c = \{1 \leq i \leq n : X_t^c(i) \neq Y_t^c(i)\}$$

denote the set of unmatched coordinates at time t , and let

$$M_t^c = \{1 \leq i \leq n : X_t^c(i) = Y_t^c(i)\}$$

be its complement. A simple coupling technique appears in [1], and may be described as follows:

- if $X(i)$ flips at time t , with $i \in M_t$, then also flip coordinate $Y(i)$ at time t (matched coordinates are always made to move synchronously);
- if $|U_t| > 1$ and $X(i)$ flips at time t , with $i \in U_t$, also flip coordinate $Y(j)$ at time t , where j is chosen uniformly at random from the set $U_t \setminus \{i\}$;
- else, if $U_t = \{i\}$ contains only one element, allow coordinates $X(i)$ and $Y(i)$ to evolve independently of each other until this final match is made.

This defines a valid coupling of X and Y , for which existing coordinate matches are maintained and new matches made in pairs when $|U_t| \geq 2$. It is also an example of a *co-adapted* coupling.

Definition 1.2. A coupling (X^c, Y^c) is called *co-adapted* if there exists a filtration $(\mathcal{F}_t)_{t \geq 0}$ such that

1. X^c and Y^c are both adapted to $(\mathcal{F}_t)_{t \geq 0}$
2. for any $0 \leq s \leq t$,

$$\mathcal{L}(X_t^c | \mathcal{F}_s) = \mathcal{L}(X_t^c | X_s^c) \quad \text{and} \quad \mathcal{L}(Y_t^c | \mathcal{F}_s) = \mathcal{L}(Y_t^c | Y_s^c) .$$

In other words, (X^c, Y^c) is co-adapted if X^c and Y^c are both Markov with respect to a common filtration, $(\mathcal{F}_t)_{t \geq 0}$. Note that this definition does *not* imply that the joint process (X^c, Y^c) is Markovian, however. If (X^c, Y^c) is co-adapted then the coupling time is a randomised stopping time with respect to the individual chains, and it suffices to study the first *collision* time of the two chains (since it is then always possible to make X^c and Y^c agree from this time onwards).

In this paper we search for the best possible coupling of the random walks X and Y on \mathbb{Z}_2^n within the class \mathcal{C} of all co-adapted couplings.

2. Co-adapted couplings for random walks on \mathbb{Z}_2^n

In order to find the optimal co-adapted coupling of X and Y , it is first necessary to be able to describe a general coupling strategy $c \in \mathcal{C}$. To this end, let Λ_{ij} ($0 \leq i, j \leq n$) be independent unit-rate marked Poisson processes, with marks W_{ij} chosen uniformly on the interval $[0, 1]$. We let $(\mathcal{F}_t)_{t \geq 0}$ be any filtration satisfying

$$\sigma \left\{ \bigcup_{i,j} \Lambda_{ij}(s), \bigcup_{i,j} W_{ij}(s) : s \leq t \right\} \subseteq \mathcal{F}_t, \quad \forall t \geq 0 .$$

The transitions of X^c and Y^c will be driven by the marked Poisson processes, and controlled by a process $\{Q^c(t)\}_{t \geq 0}$ which is adapted to $(\mathcal{F}_t)_{t \geq 0}$. Here, $Q^c(t) = \{q_{ij}^c(t) : 1 \leq i, j, \leq n\}$ is a $n \times n$ doubly sub-stochastic matrix. Such a matrix implicitly defines terms $\{q_{0j}^c(t) : 1 \leq j \leq n\}$ and $\{q_{i0}^c(t) : 1 \leq i \leq n\}$ such that

$$\sum_{i=0}^n q_{ij}^c(t) = 1 \quad \text{for all } 1 \leq j \leq n \text{ and } t \geq 0, \quad (2.1)$$

$$\text{and} \quad \sum_{j=0}^n q_{ij}^c(t) = 1 \quad \text{for all } 1 \leq i \leq n \text{ and } t \geq 0. \quad (2.2)$$

For convenience we also define $q_{00}^c(t) = 0$ for all $t \geq 0$.

Note that any co-adapted coupling (X^c, Y^c) must satisfy the following three constraints, all of which are due to the marginal processes $X^c(i)$ ($i = 1, \dots, n$) being independent unit rate Poisson processes (and similarly for the processes $Y^c(i)$):

1. At any instant the number of jumps by the process (X^c, Y^c) cannot exceed two (one on X^c and one on Y^c);
2. All single and double jumps must have rates bounded above by one;
3. For all $i = 1, \dots, n$, the *total* rate at which $X^c(i)$ jumps must equal one.

A general co-adapted coupling for X and Y may therefore be defined as follows: if there is a jump in the process Λ_{ij} at time $t \geq 0$, and the mark $W_{ij}(t)$ satisfies $W_{ij}(t) \leq q_{ij}(t)$, then set $X_t^c = X_{t-}^c + e_i \pmod{2}$ and $Y_t^c = Y_{t-}^c + e_j \pmod{2}$. Note that if i (respectively j) equals zero, then $X_t^c = X_{t-}^c$ (respectively, $Y_t^c = Y_{t-}^c$), since $e_0 = (0, \dots, 0)$.

From this construction it follows directly that X^c and Y^c both have the correct marginal transition rates to be continuous-time simple random walks on \mathbb{Z}_2^n as described above, and are co-adapted.

3. Optimal coupling

Our proposed optimal coupling strategy, \hat{c} , is very simple to describe, and depends only upon the number of unmatched coordinates of X and Y . Let $N_t = |U_t|$ denote the value of this number at time t . Strategy \hat{c} may be summarised as follows:

- matched coordinates are always made to move synchronously (thus $N^{\hat{c}}$ is a decreasing process);
- if N is odd, all unmatched coordinates of X and Y are made to evolve independently until N becomes even;
- if N is even, unmatched coordinates are coupled in pairs - when an unmatched coordinate on X flips (thereby making a new match), a different, uniformly chosen, unmatched coordinate on Y is forced to flip at the same instant (making a total of two new matches).

Note the similarity between \hat{c} and the coupling of Aldous described in Section 1: if N is even these strategies are identical; if N is odd however, \hat{c} seeks to restore the parity of N as fast as possible, whereas Aldous's coupling continues to couple unmatched coordinates in pairs until $N = 1$.

Definition 3.1. The matrix process \hat{Q} corresponding to the coupling \hat{c} is as follows:

- $\hat{q}_{ii}(t) = 1$ for all $i \in M_t$ and for all $t \geq 0$;
- if N_t is odd, $\hat{q}_{i0}(t) = \hat{q}_{0i}(t) = 1$ for all $i \in U_t$;
- if N_t is even, $\hat{q}_{i0}(t) = \hat{q}_{0i}(t) = \hat{q}_{ii}(t) = 0$ for all $i \in U_t$, and

$$\hat{q}_{ij} = \frac{1}{|U_t| - 1} \quad \text{for all distinct } i, j \in U_t.$$

The coupling time under \hat{c} , when $(X_0, Y_0) = (x, y)$, can thus be expressed as follows:

$$\hat{\tau} = \tau^{\hat{c}} = \begin{cases} E_0 + E_1 + E_2 + \cdots + E_{m-1} + E_m & \text{if } |x - y| = 2m \\ E_0 + E_1 + E_2 + \cdots + E_{m-1} + E_m + E_{2m+1} & \text{if } |x - y| = 2m + 1, \end{cases} \quad (3.1)$$

where $\{E_k\}_{k \geq 0}$ form a set of independent Exponential random variables, with E_k having rate $2k$. (Note that $E_0 \equiv 0$: it is included merely for notational convenience.)

Now define

$$\hat{v}(x, y, t) = \mathbb{P}[\hat{\tau} > t \mid X_0 = x, Y_0 = y] \quad (3.2)$$

to be the tail probability of the coupling time under \hat{c} . The main result of this paper is the following.

Theorem 3.1. For any states $x, y \in \mathbb{Z}_2^n$ and time $t \geq 0$,

$$\hat{v}(x, y, t) = \inf_{c \in \mathcal{C}} \mathbb{P}[\tau^c > t \mid X_0 = x, Y_0 = y]. \quad (3.3)$$

In other words, $\hat{\tau}$ is the stochastic minimum of all co-adapted coupling times for the pair (X, Y) .

It is clear from the representation in (3.1) that $\hat{v}(x, y, t)$ only depends on (x, y) through $|x - y|$, and so we shall usually simply write

$$\hat{v}(k, t) = \mathbb{P}[\hat{\tau} > t \mid N_0 = k],$$

with the convention that $\hat{v}(k, t) = 0$ for $k \leq 0$. Note, again from (3.1), that $\hat{v}(k, t)$ is strictly increasing in k . For a strategy $c \in \mathcal{C}$, define the process S_t^c by

$$S_t^c = \hat{v}(X_t^c, Y_t^c, T - t),$$

where $T > 0$ is some fixed time. This is the conditional probability of X and Y not having coupled by time T , when strategy c has been followed over the interval $[0, t]$ and \hat{c} has then been used from time t onwards. The optimality of \hat{c} will follow by Bellman's principle (see, for example, [7]) if it can be shown that $S_{t \wedge \tau^c}^c$ is a submartingale for all $c \in \mathcal{C}$, as demonstrated in the following lemma. (Here and throughout, $s \wedge t = \min\{s, t\}$.)

Lemma 3.1. *Suppose that for each $c \in \mathcal{C}$ and each $T \in \mathbb{R}_+$,*

$$(S_{t \wedge \tau^c}^c)_{0 \leq t \leq T} \quad \text{is a submartingale.}$$

Then equation (3.3) holds.

Proof. Notice that, with $(X_0, Y_0) = (x, y)$, $S_0^c = \hat{v}(x, y, T)$ and $S_{T \wedge \tau^c}^c = \mathbf{1}_{[T < \tau^c]}$. If $S_{\cdot \wedge \tau^c}^c$ is a submartingale it follows by the Optional Sampling Theorem that

$$\mathbb{P}[\tau^c > T] = \mathbb{E}[S_{T \wedge \tau^c}^c] \geq S_0^c = \hat{v}(x, y, T) = \mathbb{P}[\hat{\tau} > T],$$

and hence the infimum in (3.3) is attained by \hat{c} .

Now, (point process) stochastic calculus yields:

$$dS_t^c = dZ_t^c + \left(\mathcal{A}_t^c \hat{v} - \frac{\partial \hat{v}}{\partial t} \right) dt, \quad (3.4)$$

where Z_t^c is a martingale, and \mathcal{A}_t^c is the ‘‘generator’’ corresponding to the matrix $Q^c(t)$. Since the Poisson processes Λ_{ij} are independent, the probability of two or more jumps occurring in the superimposed process $\bigcup \Lambda_{ij}$ in a time interval of length δ is $O(\delta^2)$. Hence, for any function $f : \mathbb{Z}_2^n \times \mathbb{Z}_2^n \times \mathbb{R}^+ \rightarrow \mathbb{R}$, \mathcal{A}_t^c satisfies

$$\mathcal{A}_t^c f(x, y, t) = \sum_{i=0}^n \sum_{j=0}^n q_{ij}^c(t) \left[f(x + e_i, y + e_j, t) - f(x, y, t) \right].$$

Setting $f = \hat{v}$ gives:

$$\begin{aligned} \mathcal{A}_t^c \hat{v}(x, y, t) &= \sum_{i=0}^n \sum_{j=0}^n q_{ij}^c(t) \left[\hat{v}(x + e_i, y + e_j, t) - \hat{v}(x, y, t) \right] \\ &= \sum_{i=0}^n \sum_{j=0}^n q_{ij}^c(t) \left[\hat{v}(|x - y + e_i + e_j|, t) - \hat{v}(|x - y|, t) \right]. \end{aligned}$$

In particular, since \hat{v} is invariant under coordinate permutation, if $N_t^c = |x - y| = k$ then

$$\mathcal{A}_t^c \hat{v}(x, y, t) = \sum_{m=-2}^2 \lambda_t^c(k, k+m) \left[\hat{v}(k+m, t) - \hat{v}(k, t) \right], \quad (3.5)$$

where $\lambda_t^c(k, k+m)$ is the rate (according to $Q^c(t)$) at which N_t^c jumps from k to $k+m$.

More explicitly,

$$\lambda_t^c(k, k+2) = \sum_{\substack{i,j \in M_t \\ i \neq j}} q_{ij}^c(t), \quad \lambda_t^c(k, k+1) = \sum_{i \in M_t} (q_{i0}^c(t) + q_{0i}^c(t)), \quad (3.6)$$

$$\lambda_t^c(k, k-2) = \sum_{\substack{i,j \in U_t \\ i \neq j}} q_{ij}^c(t), \quad \lambda_t^c(k, k-1) = \sum_{i \in U_t} (q_{i0}^c(t) + q_{0i}^c(t)), \quad (3.7)$$

and

$$\lambda_t^c(k, k) = \sum_{i \in U_t, j \in M_t} (q_{ij}^c(t) + q_{ji}^c(t)) + \sum_{i=1}^n q_{ii}^c(t). \quad (3.8)$$

It follows from the definition of Q and equations (3.6) to (3.8) that these terms must satisfy the linear constraints:

$$\begin{aligned} \lambda_t^c(k, k-2) + \frac{1}{2} \lambda_t^c(k, k-1) &\leq k, \quad \text{and} \\ \lambda_t^c(k, k-2) + \frac{1}{2} \lambda_t^c(k, k-1) + \lambda_t^c(k, k) + \frac{1}{2} \lambda_t^c(k, k+1) + \lambda_t^c(k, k+2) &= n. \end{aligned}$$

Denote by L_n the set of non-negative λ satisfying the constraints

$$\lambda(k, k-2) + \frac{1}{2} \lambda(k, k-1) \leq k, \quad \text{and} \quad (3.9)$$

$$\lambda(k, k-2) + \frac{1}{2} \lambda(k, k-1) + \lambda(k, k) + \frac{1}{2} \lambda(k, k+1) + \lambda(k, k+2) = n. \quad (3.10)$$

Returning to equation (3.4):

$$dS_t^c = dZ_t^c + \left(\mathcal{A}_t^c \hat{v} - \frac{\partial \hat{v}}{\partial t} \right) dt.$$

We wish to show that $S_{t \wedge \tau^c}^c$ is a submartingale for all couplings $c \in \mathcal{C}$. We shall do this by showing that $\mathcal{A}_t^c \hat{v}$ is minimised by setting $c = \hat{c}$. This is sufficient because $S_{t \wedge \hat{\tau}}^{\hat{c}}$ is a martingale (and so $\mathcal{A}_t^{\hat{c}} \hat{v} - \partial \hat{v} / \partial t = 0$). Now, from equation (3.5) we know that

$$\mathcal{A}_t^c \hat{v}(k, t) = \sum_{m=-2}^2 \lambda_t^c(k, k+m) \left[\hat{v}(k+m, t) - \hat{v}(k, t) \right].$$

Thus we seek to show that, for all $k \geq 0$ and for all $t \geq 0$,

$$\max_{\lambda \in L_n} \sum_{m=-2}^2 \lambda(k, k+m) \left[\hat{v}(k, t) - \hat{v}(k+m, t) \right] \geq 0. \quad (3.11)$$

For each t , this is a linear function of non-negative terms of the form $\lambda(k, k+m)$. Thanks to the monotonicity in its first argument of \hat{v} , the terms appearing in the left-hand-side of (3.11) are non-positive if and only if m is non-negative. Hence we must set

$$\lambda(k, k+1) = \lambda(k, k+2) = 0 \quad (3.12)$$

in order to achieve the maximum in (3.11).

It now suffices to maximise

$$\lambda(k, k-1) \left[\hat{v}(k, t) - \hat{v}(k-1, t) \right] + \lambda(k, k-2) \left[\hat{v}(k, t) - \hat{v}(k-2, t) \right], \quad (3.13)$$

subject to the constraint in (3.9).

Combining (3.9) and (3.13) yields the final version of our optimisation problem:

$$\text{maximise} \quad \lambda(k, k-1) \left(\left[\hat{v}(k, t) - \hat{v}(k-1, t) \right] - \frac{1}{2} \left[\hat{v}(k, t) - \hat{v}(k-2, t) \right] \right) \quad (3.14)$$

$$\text{subject to} \quad 0 \leq \lambda(k, k-1) \leq 2k. \quad (3.15)$$

The solution to this problem is clearly given by:

$$\lambda(k, k-1) = \begin{cases} 2k & \text{if } \left[\hat{v}(k, t) - \hat{v}(k-1, t) \right] > \frac{1}{2} \left[\hat{v}(k, t) - \hat{v}(k-2, t) \right] \\ 0 & \text{otherwise.} \end{cases} \quad (3.16)$$

These observations may be summarised as follows:

Proposition 3.1. *For $\lambda \in L_n$, the maximum value of*

$$\sum_{m=-2}^2 \lambda(k, k+m) \left[\hat{v}(k, t) - \hat{v}(k+m, t) \right],$$

is achieved at λ^* , where λ^* satisfies the following:

$$\begin{aligned} \lambda^*(k, k+1) &= \lambda^*(k, k+2) = 0; \\ \lambda^*(k, k-2) + \frac{1}{2}\lambda^*(k, k-1) &= k; \\ \lambda^*(k, k-1) &= \begin{cases} 2k & \text{if } [\hat{v}(k, t) - \hat{v}(k-1, t)] > \frac{1}{2}[\hat{v}(k, t) - \hat{v}(k-2, t)] \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

Our final proposition shows that $\lambda^*(k, k-1) = 2k$ if and only if k is odd.

Proposition 3.2. *For any fixed $t \geq 0$,*

$$2[\hat{v}(k, t) - \hat{v}(k-1, t)] - [\hat{v}(k, t) - \hat{v}(k-2, t)] \geq 0 \quad \text{if } k \text{ is odd, and} \quad (3.17)$$

$$2[\hat{v}(k, t) - \hat{v}(k-1, t)] - [\hat{v}(k, t) - \hat{v}(k-2, t)] \leq 0 \quad \text{if } k \text{ is even.} \quad (3.18)$$

Proof. Define \hat{V}_α by

$$\hat{V}_\alpha(k) = \int_0^\infty e^{-\alpha t} \hat{v}(k, t) dt = \frac{1}{\alpha} (1 - \mathbb{E}[e^{-\alpha \hat{\tau}}]).$$

We also define $d(k, t) = \hat{v}(k, t) - \hat{v}(k-1, t)$, and for $\alpha \geq 0$ let

$$D_\alpha(k) = \int_0^\infty e^{-\alpha t} d(k, t) dt$$

be the Laplace transform of $d(k, \cdot)$. Given the representation in equation (3.1) of $\hat{\tau}$ as a sum of independent Exponential random variables, it follows that

$$\hat{V}_\alpha(k) = \begin{cases} \frac{1}{\alpha} \left(1 - \prod_{i=1}^m \frac{2i}{2i + \alpha} \right) & \text{if } k = 2m \\ \frac{1}{\alpha} \left(1 - \frac{2(2m+1)}{2(2m+1) + \alpha} \prod_{i=1}^m \frac{2i}{2i + \alpha} \right) & \text{if } k = 2m + 1. \end{cases} \quad (3.19)$$

To ease notation, let

$$\phi_\alpha(m) = \prod_{i=1}^m \frac{2i}{2i + \alpha}.$$

The following equality then follows directly from consideration of the transition rates corresponding to strategy \hat{c} :

for all $\alpha \geq 0$ and $m \geq 1$,

$$\begin{aligned} 1 - \alpha \hat{V}_\alpha(2m) + 2m \left[\hat{V}_\alpha(2m-2) - \hat{V}_\alpha(2m) \right] &= \phi_\alpha(m) + \frac{2m}{\alpha} [\phi_\alpha(m) - \phi_\alpha(m-1)] \\ &= \phi_\alpha(m) + \frac{2m}{\alpha} \phi_\alpha(m) \left[1 - \frac{2m+\alpha}{2m} \right] \\ &= 0. \end{aligned} \tag{3.20}$$

Similarly,

$$1 - \alpha \hat{V}_\alpha(2m-1) + 2(2m-1) \left[\hat{V}_\alpha(2m-2) - \hat{V}_\alpha(2m-1) \right] = 0. \tag{3.21}$$

Now suppose that $k = 2m$, and hence is even. We wish to prove that

$$d(2m-1, t) - d(2m, t) \geq 0 \quad \text{for all } t \geq 0,$$

which is equivalent to showing that $D_\alpha(2m-1) - D_\alpha(2m)$ is totally (or completely) monotone (by the Bernstein-Widder Theorem; Theorem 1a of [3], Ch. XIII.4).

We proceed by subtracting equation (3.21) from (3.20):

$$\begin{aligned} 0 &= -\alpha \left[\hat{V}_\alpha(2m) - \hat{V}_\alpha(2m-1) \right] + 2m \left[\hat{V}_\alpha(2m-2) - \hat{V}_\alpha(2m) \right] \\ &\quad + 2(2m-1) \left[\hat{V}_\alpha(2m-1) - \hat{V}_\alpha(2m-2) \right] \\ &= -\alpha D_\alpha(2m) - 2m [D_\alpha(2m) + D_\alpha(2m-1)] + 2(2m-1) D_\alpha(2m-1), \end{aligned}$$

and so

$$D_\alpha(2m-1) - D_\alpha(2m) = \frac{2+\alpha}{2m-2} D_\alpha(2m). \tag{3.22}$$

It therefore suffices to show that $(2+\alpha)D_\alpha(2m)$ is completely monotone.

Now note from the form of \hat{V} in equation (3.19), that

$$(2+\alpha)D_\alpha(2m) = 2\Theta_\alpha(2m),$$

where $\Theta_\alpha(2m)$ is the Laplace transform of

$$\theta(2m, t) = \mathbb{P} \left[\sum_{i=0}^m E_i > t \right] - \mathbb{P} \left[\sum_{i=0}^{m-1} E_i + E_{2m-1} > t \right],$$

where $\{E_i\}_{i \geq 0}$ form a set of independent Exponential random variables, with E_i having parameter $2i$. But since $\theta(2m, t)$ is strictly positive for all t , it follows that

$(2 + \alpha)D_\alpha(2m)$ is completely monotone, as required. This proves that, for any fixed $t \geq 0$,

$$2\left[\hat{v}(k, t) - \hat{v}(k-1, t)\right] - \left[\hat{v}(k, t) - \hat{v}(k-2, t)\right] \leq 0 \quad (3.23)$$

whenever k is even. Thus inequality (3.18) holds in this case.

Now suppose that $k = 2m + 1$, and hence is odd. In this case we wish to show that inequality (3.17) holds, which is equivalent to showing that $D_\alpha(2m + 1) - D_\alpha(2m)$ is completely monotone. Now, substituting $m + 1$ for m in equation (3.21) yields

$$1 - \alpha\hat{V}_\alpha(2m + 1) + 2(2m + 1)\left[\hat{V}_\alpha(2m) - \hat{V}_\alpha(2m + 1)\right] = 0. \quad (3.24)$$

Proceeding as above, we subtract equation (3.20) from (3.24):

$$\begin{aligned} 0 &= -\alpha\left[\hat{V}_\alpha(2m + 1) - \hat{V}_\alpha(2m)\right] + 2(2m + 1)\left[\hat{V}_\alpha(2m) - \hat{V}_\alpha(2m + 1)\right] \\ &\quad + 2m\left[\hat{V}_\alpha(2m) - \hat{V}_\alpha(2m - 2)\right] \\ &= -\alpha D_\alpha(2m + 1) - 2(2m + 1)D_\alpha(2m + 1) + 2m[D_\alpha(2m) + D_\alpha(2m - 1)]. \end{aligned} \quad (3.25)$$

Then it follows from equation (3.22) that

$$(2m - 2)D_\alpha(2m - 1) = (2m + \alpha)D_\alpha(2m). \quad (3.26)$$

Substitution of equation (3.26) into (3.25) gives

$$0 = (4m + 2 - \alpha)[D_\alpha(2m) - D_\alpha(2m + 1)] + 2[D_\alpha(2m - 1) - D_\alpha(2m)],$$

and so

$$D_\alpha(2m + 1) - D_\alpha(2m) = \frac{2}{4m + 2 + \alpha}[D_\alpha(2m - 1) - D_\alpha(2m)]. \quad (3.27)$$

But, since we have already seen that $D_\alpha(2m - 1) - D_\alpha(2m)$ is completely monotone, the right-hand-side of equation (3.27) is the product of two completely monotone functions, and so is itself completely monotone [3], as required.

Now we may complete the

Proof of Theorem 3.1. Thanks to Lemma 3.1 and Proposition 3.1, Proposition 3.2, along with equations (3.12) and (3.16), shows that any optimal choice of $Q(t)$, $Q^*(t)$, is of the following form:

- when N_t is odd:

$$q_{i0}^*(t) = q_{0i}^*(t) = 1 \text{ for all } i \in U_t, \text{ (and so } \lambda_t^*(N_t, N_t - 1) = 2N_t),$$

$$q_{ii}^*(t) = 1 \text{ for all } i \in M_t;$$

- when N_t is even:

$$q_{i0}^*(t) = q_{0i}^*(t) = q_{ii}^*(t) = 0 \text{ for all } i \in U_t, \text{ (and so } \lambda_t^*(N_t, N_t - 1) = 0), \quad (3.28)$$

$$q_{ii}^*(t) = 1 \text{ for all } i \in M_t.$$

This is in agreement with our candidate strategy \hat{Q} (recall Definition 3.1). From equation (3.28) it follows that the values of $q_{ij}^*(t)$ for distinct $i, j \in U_t$ must satisfy

$$\sum_{\substack{i, j \in U_t \\ i \neq j}} q_{ij}^*(t) = |U_t|,$$

but are not constrained beyond this. Our choice of

$$\hat{q}_{ij}(t) = \frac{1}{|U_t| - 1}$$

satisfies this bound, and so \hat{c} is truly an optimal co-adapted coupling, as claimed.

Remark 3.1. Observe that when $k = 1$, equation (3.1) implies that $\hat{v}(1, t) = \hat{v}(2, t)$ for all t . The optimisation problem in (3.14) and (3.15) simplifies in this case to the following:

$$\text{maximise} \quad \lambda(1, 0)\hat{v}(1, t) \quad (3.29)$$

$$\text{subject to} \quad \frac{1}{2}\lambda(1, 0) + \lambda(1, 1) + \frac{1}{2}\lambda(1, 2) \leq n. \quad (3.30)$$

As above, this is achieved by setting $\lambda(1, 0) = 2$. Note from equation (3.30), however, that when $k = 1$ there is no obligation to set $\lambda(1, 2) = 0$ in order to attain the required maximum. Indeed, due to the equality between $\hat{v}(1, t)$ and $\hat{v}(2, t)$, when $k = 1$ it is not sub-optimal to allow *matched* coordinates to evolve independently (corresponding to $\lambda_t^c(1, 2) > 0$), so long as strategy \hat{c} is used once more as soon as $k = 2$.

4. Maximal coupling

Let X and Y be two copies of a Markov chain on a countable space, starting from different states. The coupling inequality (see, for example, [8]) bounds the tail

distribution of *any* coupling of X and Y by the total variation distance between the two processes:

$$\|\mathcal{L}(X_t) - \mathcal{L}(Y_t)\|_{TV} \leq \mathbb{P}[\tau > t]. \quad (4.1)$$

Griffeath [5] showed that, for discrete-time chains, there always exists a *maximal* coupling of X and Y : that is, one which achieves equality for all $t \geq 0$ in the coupling inequality. This result was extended to general continuous-time stochastic processes with paths in Skorohod space in [11]. However, in general such a coupling is not co-adapted. In light of the results of Section 3, where it was shown that \hat{c} is the optimal co-adapted coupling for the symmetric random walk on \mathbb{Z}_2^n , a natural question is whether \hat{c} is also a maximal coupling.

This is certainly not the case in general. Suppose that X and Y are once again random walks on \mathbb{Z}_2^n , with $X_0 = (0, 0, \dots, 0)$ and $Y_0 = (1, 1, \dots, 1)$: calculations as in [2] show that the total variation distance between X_t and Y_t exhibits a cutoff phenomenon, with the cutoff taking place at time $T_n = \frac{1}{4} \log n$ for large n . This implies that a maximal coupling of X and Y has expected coupling time of order T_n . However, it follows from the representation of $\hat{\tau}$ in equation (3.1) that

$$\mathbb{E}[\hat{\tau} ; |X_0 - Y_0| = n = 2m] = \mathbb{E}[E_1 + E_2 + \dots + E_{m-1} + E_m] \sim \frac{1}{2} \log(n). \quad (4.2)$$

It follows that \hat{c} is not, in general, a maximal coupling.

A faster coupling of X and Y was proposed by [9]. This coupling also makes new coordinate matches in pairs, but uses information about the future evolution of one of the chains in order to make such matches in a more efficient manner. This coupling is very near to being maximal (it captures the correct cutoff time), but is of course not co-adapted. Further results related to the construction of maximal couplings for general Markov chains may be found in [4, 6, 10].

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