

Goals (of EP/T004134/1)

https://www.turing.ac.uk/research/research-projects/robust-inference-air-quality-monitoring

- ► To develop methodology to allow:
 - Fusion of observations from disparate sensor networks: different spatial and temporal scales.
 - Incorporate information from other sources.
 - Statistical modelling to allow estimation and prediction of pollutant¹ models and attendant uncertainty.
 - Scale methodology up to allow full uncertainty quantification on city-scale models.
- ► To apply this methodology in liaison with the GLA.
- To make a high quality software implementation available.
- Utilize the above, for example, in route planning.

¹Including PM2.5, PM10, CO, NO₂ and O₃.

Starting Point 1: London Air Quality Project I

https://www.turing.ac.uk/research/research-projects/london-air-quality



Sensors:

- ► 100 sensors: 5 pollutants every 15 minutes
- ▶ 1,100 provide NO₂ measurements at monthly intervals
- Satellite-derived measurements at hourly resolution for NO₂ at lower spatial resolution

Other information: weather, traffic flows, construction activity and street "canyons"...

Variational approaches to approx. inference via Gaussian processes.

The main challenges of this work are:

Starting Point 1: London Air Quality Project II

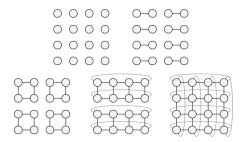
https://www.turing.ac.uk/research/research-projects/london-air-quality

- ► To ensure that data from a wide range of networks can be brought together to a single place for analysis
- ➤ To bring data into air quality models from a range of quality of sensors
- ► To ensure that we monitor the effectiveness of the different interventions planned across London
- ► To present the best estimates and forecasts in a way that app and web developers can then use to inform Londoners
- ► To accurately find low pollution routes for Londoners to follow when walking, cycling or running through the city

Starting Point 2: Statistical Methods

https://www.turing.ac.uk/research/research-projects/sequential-sampling-methods-difficult-problems

- ► Robustness: generalized Bayesian inference.
- ► Time series: (generalized) particle filters.
- Spatial inference: divide and conquer methods:



Robust spatiotemporal inference: all of the above + more.

Research Team and Collaborators

Current Team:





Indirectly: others from LAQP, RSEM projects & elsewhere.

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Recruiting:

Two PDRAs from April 1st 2020.

Partners:

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