

Equilibrium Selection and the Dynamic Evolution of Preferences

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Evolutionary Game Theory

- A population P is an *evolutionarily stable state* (ESS) if, for every “mutation” Q , there is an *invasion barrier* $\varepsilon(Q) > 0$ such that, for all $0 < \eta \leq \varepsilon(Q)$,

$$E(P, (1 - \eta)P + \eta Q) > E(Q, (1 - \eta)P + \eta Q).$$

If the inequality is weak, P is a *neutrally stable state* (NSS).

- ESS \Rightarrow Nash.
- Seen as appealing by virtue of their foundations in **dynamic models**,
- specifically the **replicator dynamics**, an example of the more general class of **payoff-monotone dynamics**.



Dynamic Analysis

- Letting $\sigma(x, Q) := E(\delta_x, Q) - E(Q, Q)$ be the success of strategy x if the population is Q ,
- the **replicator dynamics** increase the frequency of strategies that are successful relative to the prevailing average fitness:

$$\frac{Q'(t)(x)}{Q(t)(x)} = \sigma(x, Q(t)),$$

or, more generally,

$$Q'(t)(A) = \int_A \sigma(x, Q(t)) Q(t)(dx), \quad \forall A \in \mathcal{B}.$$



Static–Dynamic Links

- Symmetric Nash equilibria are stationary under the replicator dynamics.
- Moreover, in the finite case with pairwise interactions, every ESS is **asymptotically stable** in the replicator dynamics, and every NSS is **Lyapunov stable**.
- In the infinite case, this is no longer true and we require stronger concepts.
- Bomze’s “strong uninvadability,” for example, is like evolutionary stability with respect to mutations that are “close” in the strong topology.



Preference Evolution

- “Indirect evolutionary approach”: players play **rationally** for given preferences,
- but those preferences are free and subject to evolutionary selection according to their success in an underlying game of biological fitness.
- Specifically, a population of players is repeatedly matched to play a finite, symmetric 2-player **fitness game**.
- However, play is determined by a transformed **payoff game**.
- The payoffs $u \in U^2$ in this payoff game evolve according to the fitnesses induced by play in the payoff game.



Bias Example

(a)	<table border="1" style="border-collapse: collapse; text-align: center;"> <tr> <td></td> <td style="padding: 5px;"><i>L</i></td> <td style="padding: 5px;"><i>R</i></td> </tr> <tr> <td style="padding: 5px;"><i>U</i></td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">0</td> </tr> <tr> <td style="padding: 5px;"></td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">0</td> </tr> <tr> <td style="padding: 5px;"><i>D</i></td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> </tr> <tr> <td style="padding: 5px;"></td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> </tr> </table>		<i>L</i>	<i>R</i>	<i>U</i>	2	0		2	0	<i>D</i>	0	1		0	1
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(b)	<table border="1" style="border-collapse: collapse; text-align: center;"> <tr> <td></td> <td style="padding: 5px;"><i>L</i></td> <td style="padding: 5px;"><i>R</i></td> </tr> <tr> <td style="padding: 5px;"><i>U</i></td> <td style="padding: 5px;">$2 + x_c$</td> <td style="padding: 5px;">0</td> </tr> <tr> <td style="padding: 5px;"></td> <td style="padding: 5px;">$2 + x_r$</td> <td style="padding: 5px;">x_r</td> </tr> <tr> <td style="padding: 5px;"><i>D</i></td> <td style="padding: 5px;">x_c</td> <td style="padding: 5px;">1</td> </tr> <tr> <td style="padding: 5px;"></td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> </tr> </table>		<i>L</i>	<i>R</i>	<i>U</i>	$2 + x_c$	0		$2 + x_r$	x_r	<i>D</i>	x_c	1		0	1
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Figure 1: (a) Coordination in fitnesses (b) Payoffs given biases



Results

- Divergence from fitness-maximizing preferences is then possible because of the resulting effect on opponents' play.
- Two key questions:
 - 1 What preferences would emerge if the whole range of possible preferences were allowed to compete, rather than some subset chosen for the example at hand?
 - 2 Can non-fitness-maximizing preferences emerge in the absence of preference observability?
- Dekel, Ely & Yilankaya (*REStud* 2007):
 - Efficient strict Nash (in fitnesses) \Rightarrow stability (e.g. $\{U, L\}$).
 - Stability \Rightarrow efficiency, given observability.
 - Absent observability, stability \Rightarrow Nash in fitness game; strict Nash \Rightarrow stability.

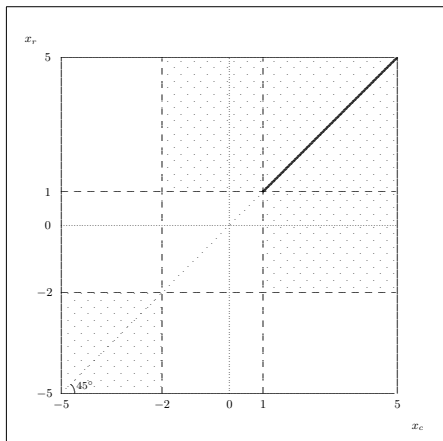


A Dynamic Model

- Let biases be shaped by the replicator dynamics.
- Given biases, Nash equilibrium in the payoff game determines play, and thus underlying fitnesses.
- If there is more than one equilibrium, each of them is assumed to be played with some given, strictly positive probability.
- Many biases are equivalent in terms of resulting fitnesses, so use **setwise** stability concepts (Norman, *GEB* 2008).



Bias Example



Equilibrium Selection

- More generally, we can think about any transformation from fitnesses to payoffs (not just biases),
- and we can think of numerous other rules for play in the presence of multiple equilibria;
- specifically, we can allow for any **equilibrium-selection mechanism**—e.g. global games.
- Gives a well-defined replicator dynamics (rather than a differential inclusion).



Results

- In common-interest fitness games, maximal efficient **face** \rightsquigarrow asymptotically stable.
- For general fitness games, any face enforcing efficient strict Nash through dominant strategies is Lyapunov stable.
- and any face supporting a Pareto-dominated outcome is not Lyapunov stable for an appropriately chosen equilibrium-selection mechanism.
- For doubly symmetric fitness games (including some Hawk–Dove), “purified p^* -populations,” p^* an efficient MSE of the fitness game, satisfy a weaker form of stability.
- With unobservable preferences, maximal face supporting symmetric strict Nash outcome \rightsquigarrow asymptotically stable.

