



Monotonicity of the value function for a two-dimensional optimal stopping problem

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Introduction

Setting: consider a two-dimensional strong Markov process (X, Y) on $(\Omega, \mathcal{F}, P_{x,y}, (x, y) \in \mathbf{R} \times \mathbf{S})$ with $\mathbf{S} \subseteq (0, \infty)$, such that

$$dX = a(X)YdB \quad (1)$$

and Y is any of the two classes:

Regime-switching: Y is a continuous-time MC, independent of B .

Diffusion: Y solves a stochastic differential equation of the type

$$dY = \eta(Y)dB^Y + \theta(Y)dt \quad (2)$$

where $B^Y = (B_t^Y)_{t \geq 0}$ is a standard Brownian motion such that $\langle B, B^Y \rangle_t = \delta t$, $t \geq 0$, for some real parameter $\delta \in [-1, 1]$.

Aim: our main focus is on proving the monotonicity of $y \mapsto v(x, y)$,

$$v(x, y) = \sup_{0 \leq \tau \leq T} E_{x,y}[e^{-q\tau}g(X_\tau)], \quad (x, y) \in \mathbf{R} \times \mathbf{S}, \quad (3)$$

where $q > 0$, $T \in [0, \infty]$, the gain function $g: \mathbf{R} \rightarrow \mathbf{R}$ is a general measurable function and the supremum is taken over all finite stopping times with respect to the filtration generated by (X, Y) .

As a consequence of the monotonicity, we are also able to show continuity of $y \mapsto v(x, y)$, in both finite and infinite horizon.

Application: pairs (X, Y) as above are common in mathematical finance:

► $X \rightsquigarrow$ discounted price of an asset

► $Y \rightsquigarrow$ stochastic volatility.

The results can be applied to prices of American options in popular models such as Heston or Hull-White.

Some background: the monotonicity property was investigated for

► European options with convex gain function by Hobson [2] with (1)-(2),

► American options by Ekström [1] in the case that $Y = 1$ and $a = a(x, t)$.

Note: in this presentation we concentrate on the diffusion case and $g \geq 0$.

[1] Ekström, E., Properties of American options prices, *Stoch. Proc. Appl.* **114**, 265-278 (2004).

[2] Hobson, D., Comparison results for stochastic volatility models via coupling, *Finance and Stochastics* **14**, 129-152 (2010).

Theorem 1 (Monotonicity)

Assumptions: let (X, Y) be as in (1)-(2) and assume that

a) Y takes values in $\mathbf{S} = (0, \infty)$ and for $(x, y) \in \mathbf{R} \times \mathbf{S}$,

$$P_{x,y}\left(\int_0^t Y_s^2 ds < \infty, \forall t \geq 0\right) = 1, \quad P_{x,y}\left(\lim_{t \rightarrow \infty} \int_0^t Y_s^2 ds = \infty\right) = 1. \quad (4)$$

b) The measurable functions a, η, θ are such that the system

$$(*) \begin{cases} dG = a(G)dW \\ d\xi = \eta(\xi)\xi^{-1}dW^\xi + \theta(\xi)\xi^{-2}dt \end{cases}$$

has a unique non-exploding strong solution with $\xi_t \in \mathbf{S}$, $t \geq 0$.

Result: for every $x \in \mathbf{R}$ and $y, y' \in \mathbf{S}$ with $y \leq y'$, $v(x, y) \leq v(x, y')$.

Idea of proof: we sketch the proof in three steps (see middle column):

1. Construct a weak solution (\tilde{X}, \tilde{Y}) of (1)-(2) by time-changing $(*)$.
2. Formulate an equivalent optimal stopping problem in the time-changed setting.
3. Use coupling to make path comparison of processes.

Step 1: constructing a weak solution (\tilde{X}, \tilde{Y}) .

► Choose $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$, complete, big enough to carry a pair of BM's (W, W^ξ) with $\langle W, W^\xi \rangle_t = \delta t$, and denote by $\tilde{\mathcal{F}}_t$ the augmentation of the filtration generated by (W, W^ξ) .

► Let (G, ξ) be the unique solution of $(*)$ starting from (x, y) .

► Setting $M_t := \int_0^t Y_u dB_u$, we verify that $Y \circ \langle M \rangle^{-1}$ solves weakly the second component of $(*)$, then ξ has the same law as $Y \circ \langle M \rangle^{-1}$ under $P_{x,y}$.

► Define $\Gamma_t := \int_0^t \xi_u^{-2} du$. Since $\int_0^t (Y \circ \langle M \rangle^{-1})^{-2} du$ is the inverse of $\int_0^t Y_u^2 du$, the previous step and (4) imply

$$\tilde{P}(\Gamma_t < \infty, \forall t \geq 0) = 1 \quad \text{and} \quad \tilde{P}\left(\lim_{t \rightarrow \infty} \Gamma_t = \infty\right) = 1. \quad (5)$$

► As Γ_t is continuous and strictly increasing, so is $A_t = \Gamma_t^{-1}$, and

(P1) $\Gamma_{A_t} = A_{\Gamma_t} = t$ for all $t \geq 0$ \tilde{P} -a.s. and

(P2) $s < \Gamma_t$ if and only if $A_s < t$ for all $0 \leq s, t < \infty$ \tilde{P} -a.s.

► As ξ is $\tilde{\mathcal{F}}_t$ -adapted, we have that $\tilde{M}_t = \int_0^t \xi_u^{-1} dW_u$ and $\tilde{M}_t^\xi = \int_0^t \xi_u^{-1} dW_u^\xi$ are $\tilde{\mathcal{F}}_t$ -local martingales (which do exist by (5)), and then the $\tilde{\mathcal{F}}_{A_t}$ -adapted processes

$$\tilde{X} = G \circ A, \quad \tilde{Y} = \xi \circ A \quad (6)$$

constitute a non-exploding weak solution of (1)-(2), with driving BM's

$$\tilde{B} = \tilde{M} \circ A, \quad \tilde{B}^Y = \tilde{M}^\xi \circ A.$$

Step 2: formulating an equivalent optimal stopping problem.

► The solution (\tilde{X}, \tilde{Y}) constructed in Step 1, must have the same law as (X, Y) under $P_{x,y}$ by the assumption b). Then we can write

$$v(x, y) = \sup_{\tau \in \mathcal{T}_T} \tilde{E}[e^{-q\tau}g(\tilde{X}_\tau)]$$

where $\mathcal{T}_T = \{ \text{finite stopping times } \tau \text{ w.r.t. } (\tilde{\mathcal{F}}_{A_t})_{t \geq 0} \text{ such that } 0 \leq \tau \leq T \}$.

Remark that even though $\mathcal{F}_t^{\tilde{X}, \tilde{Y}} \subseteq \tilde{\mathcal{F}}_{A_t}$, (\tilde{X}, \tilde{Y}) is a strong Markov process w.r.t. $\tilde{\mathcal{F}}_{A_t}$ and so we may take stopping times w.r.t this filtration.

► Using the properties (P1)-(P2) above is not difficult to verify that

$$v(x, y) = \sup_{\rho \in \mathcal{M}_T} \tilde{E}[e^{-q\rho}g(G_\rho)], \quad (7)$$

where $\mathcal{M}_T = \{ \text{finite stopping times } \rho \text{ w.r.t. } (\tilde{\mathcal{F}})_{t \geq 0} \text{ such that } 0 \leq \rho \leq A_T \}$.

Step 3: coupling of stochastic processes.

► Fix $x \in \mathbf{R}$ and $y, y' \in \mathbf{S}$ such that $y \leq y'$. Let (G, ξ) and (G, ξ') be the solutions of $(*)$ starting from (x, y) and (x, y') respectively.

► Define $C = \inf\{t \geq 0 : \xi_t > \xi'_t\}$ and set $\tilde{\xi}_t = \xi_t I(t < C) + \xi'_t I(t \geq C)$. Then $(G, \tilde{\xi})$ solves $(*)$ with $(G_0, \tilde{\xi}_0) = (x, y)$ and hence $\xi_t = \tilde{\xi}_t \leq \xi'_t$, $t \geq 0$, a.s. by strong uniqueness.

► Construct $\tilde{X} = G \circ A$, $\tilde{X}' = G \circ A'$ on $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ as in Step 1. It follows from $0 \leq \xi_t \leq \xi'_t$ that $\Gamma_t \geq \Gamma'_t$, $t \geq 0$, a.s.

► Using that $A_t \leq A'_t$, we have $\mathcal{M}_T \subseteq \mathcal{M}'_T$. Thus by (7) one obtains $v(x, y) \leq v(x, y')$, Q.E.D.

Theorem 2 (Continuity)

Assumptions: let the assumptions of Theorem 1 hold and let the ξ component of $(*)$ result in a Feller process with state space $\mathbf{S} = (0, \infty)$.

Result:

i) If the horizon $T = \infty$ then $v(x, \cdot)$ is continuous (although for right-continuity one has to assume a stronger integrability condition).

ii) If the horizon $T < \infty$ AND g is continuous then $v(x, \cdot)$ is continuous.

Idea of proof:

► Fix $(y_n)_{n=1}^\infty \subseteq (0, \infty)$ such that $y_n \rightarrow y_0$, $y_0 \in (0, \infty)$.

► Let (G, ξ^n) be the solution of $(*)$ starting from (x, y_n) , $n = 1, 2, \dots$, and construct Γ^n , A^n and $(\tilde{X}^n, \tilde{Y}^n)$ as in Step 1.

► If the sequence $(y_n)_{n=1}^\infty$ is monotone, then the coupling argument and the Feller property of ξ imply

$$\Gamma_t^n \rightarrow \Gamma_t^0 \quad \text{and} \quad A_t^n \rightarrow A_t^0 \quad \text{if } n \rightarrow \infty$$

for all $t \geq 0$, a.s.

► The previous fact and the monotonicity of $v(x, \cdot)$ are the key tools to show left-continuity and right-continuity of $v(x, \cdot)$.

Example: Hull and White model

► The SV model proposed by Hull and White (after a change of variable) is of the form

$$\begin{aligned} dX &= XYdB & X_0 &= x > 0, \\ dY &= \eta YdB^Y + \theta Ydt & Y_0 &= y > 0, \end{aligned}$$

where η, θ are positive constants.

► The time-changed volatility takes the form $d\xi_t = \eta dW_t^\xi + \theta\xi^{-1} dt$. The process $Z_t = \xi_t/\eta$ is a Bessel process of dimension $\phi = 1 + 2\theta/\eta^2$. Thus the condition b) is satisfied if and only if $\phi \geq 2$.

► Also, $\phi \geq 2$ implies that $\Gamma_t = \int_0^t (\xi_u)^{-2} du = \eta^2 \int_0^t (Z_u)^{-2} du$ satisfies (5).

► That ξ is a Feller process with state space \mathbf{S} is a known property of Bessel processes.

Some extensions

► All the previous results can be stated for a general measurable gain function g which may take negative values, in the case $T = \infty$.

We assume that $\{g \geq 0\} \neq \emptyset$ and $P_{x,y}(\inf\{t \geq 0 : g(X_t) \geq 0\} < \infty) = 1$, which is sufficient for $v(x, y) = \sup_{\tau \in \mathcal{K}_\infty^g} E_{x,y}e^{-q\tau}g(X_\tau)$, where \mathcal{K}_∞^g consists of all the finite stopping times such that $g(X_\tau) \geq 0$.

► In the context of American option pricing, the payoff takes the form $g(e^{r\tau}X_\tau)$ if exercised at τ . The setup becomes

$$P(x, y) = \sup_{0 \leq \tau \leq T} E_{x,y}[e^{-r\tau}g(e^{r\tau}X_\tau)].$$

Monotonicity of $P(x, \cdot)$ will follow if g is a non-increasing function, while continuity carries over if we further assume that g is continuous.

► Our results would not change in principle if $\mathbf{S} \subseteq (-\infty, 0)$ instead. What would change is only that increasing would turn into decreasing.