#### Predictive Coarse-Graining

#### M. Schöberl<sup>1</sup>, N. Zabaras<sup>2,3</sup>, P.S. Koutsourelakis<sup>1</sup>

<sup>1</sup>Continuum Mechanics Group Technische Universität München <sup>2</sup>Institute for Advanced Study Technische Universität München

<sup>3</sup>Warwick Centre of Predictive Modeling University of Warwick

November 27, 2015

## Motivation Coarse-Graining

Atomistic simulation for obtaining insights of chemical and physical process of complex systems.

#### Difficulty

- Complex interactions
- Long-range interactions
- Small time- and length-scales
- $\rightarrow$  Exceeding computational tractability

#### A coarse description allows us

- to evaluate larger systems during larger time intervals
- to gain understanding of physics of the system.



Figure : Coarse-graining water

#### Motivation

#### Approach

- Describing system with less degrees of freedom
- Determining optimal parameter set for given parametrization of a coarse-grained potential
- Leading to point estimates of its parametrization and thus also in predictions
- Predictions performed on coarse scale

# How can we quantify the uncertainty induced by a coarse description and the loss of information?

# How can we reconstruct fine configurations given a coarse configuration?

Fine-scale degrees of freedom  $\mathbf{x} \in \mathcal{M}$  with  $\mathcal{M} \subset \mathbb{R}^n$ ,  $n \gg 1$  in equilibrium described by a Boltzmann-type PDF:

Fine-scale description

$$p_{\mathsf{f}}(\mathsf{x}|eta) = rac{\exp\left\{-eta U(\mathsf{x})
ight\}}{Z(eta)}$$

- Potential U(x)
- Inverse Temperature  $\beta = \frac{1}{k_b T}$ , with temperature T
- Partition function  $Z(\beta) = \int_{\mathcal{M}} \exp\{-\beta U(\mathbf{x})\} d\mathbf{x}$

## General coarse-graining problem

Coarse-scale description

$$p_{\mathsf{c}}(\mathbf{X}|\beta) = \frac{\exp\left\{-\beta U_{\mathsf{c}}(\mathbf{X}, \boldsymbol{\theta}_{\mathsf{c}})\right\}}{Z_{\mathsf{c}}(\boldsymbol{\theta}_{\mathsf{c}}, \beta)}$$

- ▶ Coarse variables  $\mathbf{X} \in \mathcal{M}_{c}$ ,  $\mathcal{M}_{c} \subset \mathbb{R}^{n_{c}}$ ,  $n_{c} \ll n$
- ▶ Coarse-grained potential selected  $\hat{U}_c$  selected out of candidate potentials  $\hat{U}_c \in \mathcal{U}_c$
- Parametrization and shape selected by assuming U<sub>c</sub>(X, θ<sub>c</sub>) but any potential possible

#### How are fine and coarse configurations connected?

Connecting fine variables x with coarse variables X with coarse-graining map  $\pmb{\xi}:\mathcal{M}\longrightarrow\mathcal{M}_c$ 

$$\mathbf{X} = \boldsymbol{\xi}(\mathbf{x})$$

#### How to determine the effective coarse potential $U_c$ ?

Analytical solution for the effective coarse-grained potential:

$$U_{\mathrm{c}}(\mathbf{X}) = -eta^{-1} \ln \int_{\mathcal{M}} \exp\left\{-eta U(\mathbf{x})
ight\} \delta(\boldsymbol{\xi}(\mathbf{x}) - \mathbf{X}) d\mathbf{x}$$

Potential of mean force with respect to coarse-grained coordinates  $\xi(\mathbf{x})$ .  $\rightarrow$  intractable!

Numerical coarse-graining strategies:

- iterative Boltzmann inversion [5]
- inverse Monte Carlo [8]
- force matching [6]
- variational mean-field theory [9]
- relative entropy [10]

## The relative entropy method<sup>[10]</sup>

 $\rightarrow$  minimize a distance metric between  $p_f(\mathbf{X}|\beta)$  and  $p_c(\mathbf{X}|\beta)$  with the PDF  $p_f(\mathbf{X}|\beta)$  sampling configuration **x** that maps to configuration **X** 

$$p_{\mathsf{f}}(\mathbf{X}|eta) \propto \int_{\mathcal{M}} p_{\mathsf{f}}(\mathbf{x}|eta) \delta(\boldsymbol{\xi}(\mathbf{x}) - \mathbf{X}) d\mathbf{x}$$

Relative entropy method<sup>[10, 4, 2]</sup> (or KL-divergence)

$$\mathsf{KL}(p_{\mathsf{f}}||p_{\mathsf{c}}) = \int_{\mathcal{M}_{\mathsf{c}}} p_{\mathsf{f}}(\mathbf{X}|\beta) \ln\left(\frac{p_{\mathsf{f}}(\mathbf{X}|\beta)}{p_{\mathsf{c}}(\mathbf{X}|\beta)}\right) d\mathbf{X}$$

Formulation in  $\mathcal{M}$ :

$$\mathsf{KL}(p_f||p_{\mathsf{c}}) = \int_{\mathcal{M}} p_{\mathsf{f}}(\mathbf{x}|\beta) \ln\left(\frac{p_{\mathsf{f}}(\mathbf{x}|\beta)}{p_{\mathsf{c}}\left(\boldsymbol{\xi}(\mathbf{x})|\beta\right)}\right) d\mathbf{x} + \mathcal{S}_{\mathsf{map}}(\boldsymbol{\xi}(\mathbf{x}))$$

▶ with  $S_{map} = \langle \int_{\mathcal{M}} \delta(\boldsymbol{\xi}(\mathbf{x}) - \mathbf{X}) d\mathbf{x} \rangle_{p_{f}(\mathbf{x}|\beta)}$  measures the information loss induced by mapping  $\boldsymbol{\xi}(\mathbf{x})$ .

#### Relative entropy method

 $S_{map}(\boldsymbol{\xi}(\mathbf{x}))$  is independent of  $\hat{U}_c$ , the minimization of the KL-divergence is equivalent to minimization of

$$\mathcal{F}(\hat{U}_{\mathsf{c}}) = \left\langle \ln \frac{p_{\mathsf{f}}(\mathsf{x}|\beta)}{p_{\mathsf{c}}(\boldsymbol{\xi}(\mathsf{x})|\beta)} \right\rangle_{p_{\mathsf{f}}(\mathsf{x}|\beta)}$$

For any given m-dimensional parametrization  $heta_{\mathsf{c}}\in oldsymbol{\Theta}_{\mathsf{c}}\subset \mathbb{R}^m$  of the potential, the

optimization problem follows:

$$\boldsymbol{\theta}_{\mathsf{c}}^{*} = \arg\min_{\boldsymbol{\theta}_{\mathsf{c}} \in \boldsymbol{\Theta}_{\mathsf{c}}} \mathcal{F}(U_{\mathsf{c}}(\boldsymbol{\mathsf{X}}, \boldsymbol{\theta}_{\mathsf{c}}))$$

#### Relative entropy method

#### Model Restrictions

- Relative entropy method has no capability to predict fine-scale configurations (no mapping coarse to fine)
  - Eg. for predicting correlations within fine configurations
- Predicting quantities of interest (Qol) by evaluating on fine-scale

$$\langle f(x) \rangle_{p_{\mathsf{f}}(\mathsf{x}|eta)} = \int_{\mathcal{M}} f(x) p_{\mathsf{f}}(\mathsf{x}|eta) d\mathsf{x}$$

- With coarse-grained description p<sub>c</sub>(X|β) predictions in M<sub>c</sub> but not in M Difficulty:
  - How to define observable  $g(\mathbf{X})$  for desired QoI in  $\mathcal{M}_c$ ?
  - Are you able to predict same QoI with  $\langle g(\mathbf{X}) \rangle_{p_{c}(\mathbf{X}|\beta)} = \int_{\mathcal{M}_{c}} g(\mathbf{X}) p_{c}(\mathbf{X}|\beta) d\mathbf{X}$
- ▶ No quantification of epistemic uncertainty: determine  $S_{map}(\xi(x))$

## Proposed Model

Framework following generative probabilistic models and builds upon:

- **1** Coarse-scale PDF  $p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c},\beta) \propto \exp\{-\beta U_{c}(\mathbf{X},\boldsymbol{\theta}_{c})\}$ 
  - Describing statistics of coarse variables X
  - Parametrized by  $\theta_{c}$ , no restrictions in shape of  $p_{c}$

**2** Probabilistic mapping from coarse to fine  $p_{cf}(\mathbf{x}|\mathbf{X}, \theta_{cf})$ 

- Conditional PDF of x given the coarse variables X
- ▶ Parametrization of the probabilistic mapping by  $m{ heta}_{cf} \in m{\Theta}_{cf} \subset \mathbb{R}^{m_{cf}}$
- Deterministic mapping  $\xi(\mathbf{x})$  is not invertible (many to one map)

 $\rightarrow$  Probabilistic relation necessary

•  $S_{map}$  not fixed for per definition.  $\rightarrow$  Optimization with respect to  $\theta_{cf}$  possible.

#### 3 Prior PDF for model parametrization

- ► *p*(*θ*<sub>c</sub>)
- $p(\theta_{cf})$

- Proposed model describes a Bayesian perspective of coarse-graining equilibrium atomistic ensembles
- ► Model is data driven by N data points x<sup>(i)</sup> in the fine-scale, denoted as x<sup>(1:N)</sup> = {x<sup>(1)</sup>, · · · , x<sup>(N)</sup>}

Given the data  $\mathbf{x}^{(1:N)}$  a posterior distribution on the model parameters  $\theta_{cf}$ ,  $\theta_{c}$  and the **latent** variables  $\mathbf{X}^{(1:N)}$  can be defined.

- Coarse variables seen as latent
- To each observable  $\mathbf{x}^{(i)}$  one latent Variable  $\mathbf{X}^{(i)}$  is assigned
- $\mathbf{X}^{(i)}$  represents pre-image of the fine-scale observation  $\mathbf{x}^{(i)}$

#### Bayesian coarse-graining - posterior

#### Posterior distribution

$$p(\theta_{cf}, \theta_{cf}, \mathbf{X}^{(1:N)} | \mathbf{x}^{(1:N)}) \propto p(\mathbf{x}^{(1:N)} | \theta_{cf}, \theta_{c}, \mathbf{X}^{(1:N)}) p(\theta_{cf}, \theta_{c}, \mathbf{X}^{(1:N)})$$
$$= \left(\prod_{i=1}^{N} p_{cf}(\mathbf{x}^{(i)} | \theta_{cf}, \mathbf{X}^{(i)}) p_{c}(\mathbf{X}^{(i)} | \theta_{c})\right) p(\theta_{cf}) p(\theta_{c})$$

Use given data  $\mathbf{x}^{(1:N)}$  for inferring the the posterior distribution or for determining MAP estimates of the model parameters  $\theta_{cf}^*$ ,  $\theta_c^*$ .

- Bayesian formulation answers the questions of
  - model validation and
  - prediction



The posterior distribution leads to the predictive distribution for fine-scale configurations **x**:

Predictive distribution

$$p(\mathbf{x}|\mathbf{x}^{(1:N)}) = \int p_{\rm cf}(\mathbf{x}|\mathbf{X}, \theta_{\rm cf}) p_{\rm c}(\mathbf{X}|\theta_{\rm c}) p(\theta_{\rm c}, \theta_{\rm cf}|\mathbf{x}^{(1:N)}) d\mathbf{X} d\theta_{\rm cf} d\theta_{\rm cf}$$

#### Simulate fine-scale system

- 1 Draw sample  $\theta_{c}^{*}$ ,  $\theta_{cf}^{*} \sim p(\theta_{c}, \theta_{cf} | \mathbf{x}^{(1:N)})$
- **②** Draw sample of coarse-scale description  $\mathbf{X}^* \sim p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c}^*)$
- **③** Draw sample of fine-scale description  $\mathbf{x}^* \sim p_{cf}(\mathbf{x}^* | \mathbf{X}^*, \boldsymbol{\theta}_{cf}^*)$

#### Bayesian coarse-graining: ensemble averages

Approximating ensemble averages by

$$\begin{split} \langle f(\mathbf{x}) \rangle_{p_{f}(\mathbf{x})} &= \int_{\mathcal{M}} f(\mathbf{x}) p_{f}(\mathbf{x}) d\mathbf{x} \\ &= E[f(\mathbf{x})] \approx E[f(\mathbf{x}) |\mathbf{x}^{(1:N)}] \\ &= \int_{\mathcal{M}} f(\mathbf{x}) p(\mathbf{x} | \mathbf{x}^{(1:N)}) d\mathbf{x} \\ &= \int f(\mathbf{x}) p_{cf}(\mathbf{x} | \mathbf{X}, \theta_{cf}) p_{c}(\mathbf{X} | \theta_{c}) p(\theta_{c}, \theta_{cf} | \mathbf{x}^{(1:N)}) d\mathbf{x} d\mathbf{X} d\theta_{c} d\theta_{cf} \end{split}$$

• Error arising from discrepancy between  $E[f(\mathbf{x})]$  and  $E[f(\mathbf{x})|\mathbf{x}^{(1:N)}]$ 

#### Bayesian coarse-graining: coarse-scale model $p_c$

# Coarse-scale model $p_{c}(\mathbf{X}|\boldsymbol{\theta}_{cf}) = \frac{\exp\left\{-\beta U_{c}(\mathbf{X},\boldsymbol{\theta}_{c})\right\}}{Z_{c}(\boldsymbol{\theta}_{c})}$

Requirements

- Allow sufficient flexibility of  $p_c(\mathbf{X})$
- $U_c$  built from high-order interactions affording flexibility in  $p_c(X)$

#### Bayesian coarse-graining: reconstruction map $p_{cf}$

#### Map from coarse to fine: $p_{cf}(\mathbf{x}|\mathbf{X}, \boldsymbol{\theta}_{cf})$

- ▶ Several fine-configurations map to same coarse-configuration
  - Probabilistic relation between a given coarse-configuration and a fine-configuration takes account of it. [7]
- ► Fast reconstruction ([7, 1]) of fine-scale configurations x given a coarse-configuration X desired.

#### Influence of $p_{cf}$

- ► What is expected from the coarse variables X in terms of predicting the given data x<sup>(1:N)</sup>?
- ► Adjusting p<sub>c</sub>(X|θ<sub>c</sub>) so that X agrees best with data x<sup>(1:N)</sup> connected with probabilistic mapping p<sub>cf</sub>.



## Optimization

For learning the model parameters  $\theta_c$  and  $\theta_{cf}$  the expectation maximization algorithm is applied.

- Point estimates for maximizing the likelihood or posterior distribution are obtained.
- Approximation of posterior on θ<sub>cf</sub> by Laplace (validated by full posterior sampling)

#### MAP estimate

$$\begin{split} \boldsymbol{\theta}^{MAP} &= \arg \max_{\boldsymbol{\theta}} \left[ \log p(\boldsymbol{\theta}_{c}, \boldsymbol{\theta}_{cf}, \mathbf{x}^{(1:N)}) \right] \\ &= \arg \max_{\boldsymbol{\theta}} \left[ \log p(\mathbf{x}^{(1:N)} | \boldsymbol{\theta}_{cf}, \boldsymbol{\theta}_{cf}) + \log p(\boldsymbol{\theta}_{c}) + \log p(\boldsymbol{\theta}_{cf}) \right] \end{split}$$

In the following the ML-estimate is shown and will be extended by prior distributions p(θ) in a next step by adding log-priors log p(θ<sub>c</sub>) + log p(θ<sub>cf</sub>).

#### Optimization

- To obtain point estimates with MLE for the model parameters θ<sub>c</sub> and θ<sub>cf</sub> we maximize the log-likelihood by using the EM algorithm.
- The likelihood is defined as

$$\begin{split} p(\mathbf{x}^{(1:N)}|\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}) &= \int p(\mathbf{x}^{(1:N)},\mathbf{X}^{(1:N)}|\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf})d\mathbf{X}^{(1:N)} \\ &= \int p_{cf}(\mathbf{x}^{(1:N)}|\mathbf{X}^{(1:N)},\boldsymbol{\theta}_{cf})p_{c}(\mathbf{X}^{(1:N)}|\boldsymbol{\theta}_{c})d\mathbf{X}^{(1:N)} \\ &= \int \prod_{i=1}^{N} p_{cf}(\mathbf{x}^{(i)}|\mathbf{X}^{(i)},\boldsymbol{\theta}_{cf})p_{c}(\mathbf{X}^{(i)}|\boldsymbol{\theta}_{c})d\mathbf{X}^{(1:N)} \end{split}$$

• augmenting the log-likelihood with an arbitrary density  $q(\mathbf{X}^{(1:N)})$ 

$$\begin{split} \log p(\mathbf{x}^{(1:N)}|\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}) &= \log \int q(\mathbf{X}^{(1:N)}) \frac{p_{cf}(\mathbf{x}^{(1:N)}|\mathbf{X}^{(1:N)},\boldsymbol{\theta}_{cf})p_{c}(\mathbf{X}^{(1:N)}|\boldsymbol{\theta}_{c})}{q(\mathbf{X}^{(1:N)})} d\mathbf{X}^{(1:N)} \\ &\geq \int q(\mathbf{X}^{(1:N)}) \log \frac{p_{cf}(\mathbf{x}^{(1:N)}|\mathbf{X}^{(1:N)},\boldsymbol{\theta}_{cf})p_{c}(\mathbf{X}^{(1:N)}|\boldsymbol{\theta}_{c})}{q(\mathbf{X}^{(1:N)})} d\mathbf{X}^{(1:N)} \\ &= \mathcal{L}(q(\mathbf{X}^{(1:N)}),\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}) \end{split}$$

#### Expectation maximization

It holds the following decomposition for the lower bound:

$$\begin{split} \mathcal{L}(q(\mathbf{X}^{(1:N)}), \boldsymbol{\theta}_{c}, \boldsymbol{\theta}_{cf}) &= \int q(\mathbf{X}^{(1:N)}) \log \frac{p(\mathbf{x}^{(1:N)} | \mathbf{X}^{(1:N)}, \boldsymbol{\theta}_{cf}) p(\mathbf{X}^{(1:N)} | \boldsymbol{\theta}_{c})}{q(\mathbf{X}^{(1:N)})} d\mathbf{X} \\ &= - \mathsf{KL}(q(\mathbf{X}^{(1:N)}) || p(\mathbf{X}^{(1:N)} | \mathbf{x}^{(1:N)}, \boldsymbol{\theta}_{cf}, \boldsymbol{\theta}_{cf})) + \log p(\mathbf{x}^{(1:N)}) \end{split}$$

Decomposition of the log likelihood

$$\log p(\mathbf{x}^{(1:N)}|\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}) = \mathcal{L}(q(\mathbf{X}^{(1:N)}),\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}) + \mathcal{K}L(q(\mathbf{X}^{(1:N)})||p(\mathbf{X}^{(1:N)}|\mathbf{x}^{(1:N)},\boldsymbol{\theta}_{c},\boldsymbol{\theta}_{cf}))$$

Maximizing  $\mathcal{L}(q(\mathbf{X}^{(1:N)}), \theta_{c}, \theta_{cf})$  is equal to minimizing  $KL(q(\mathbf{X}^{(1:N)})||p(\mathbf{X}^{(1:N)}|\mathbf{x}^{(1:N)}, \theta_{cf}, \theta_{cf}))$ 

 $p(\mathbf{X}^{(1:N)}|\mathbf{x}^{(1:N)}, \boldsymbol{\theta}_{cf}, \boldsymbol{\theta}_{cf})$  PDF over pre-images for **X** for the given data  $\mathbf{x}^{(1:N)}$  and parameters  $\boldsymbol{\theta}$ .

#### Expectation maximization

For given parameters  $\theta_{cf}$ ,  $\theta_{c}$  the lower bound is maximized if we choose  $q(\mathbf{X}^{(1:N)}) \propto p_{cf}(\mathbf{x}^{(1:N)}|\mathbf{X}^{(1:N)}, \theta_{cf})p_{c}(\mathbf{X}^{(1:N)}|\theta_{c})$ .

Therefore,

$$\Rightarrow \textit{KL}(q(\mathbf{X}^{(1:N)})||p(\mathbf{X}^{(1:N)}|\mathbf{x}^{(1:N)}, \boldsymbol{\theta}_{c}, \boldsymbol{\theta}_{cf})) = 0.$$

#### Expectation maximization

- **1** Initial parameter setting for iteration t = 0:  $\theta_{cf}^{0}$  and  $\theta_{c}^{0}$
- **2** E-step:  $q^{(t+1)} = \arg \max_{q} \mathcal{L}(q, \theta^{t})$ Involves MCMC to obtain samples  $\mathbf{X} \sim q(\mathbf{X}^{(1:N)} | \mathbf{x}^{(1:N)}, \theta_{cf}^{t}, \theta_{cf}^{t})$ **3** M-step:  $\theta^{t+1} = \arg \max_{q} \mathcal{L}(q^{t+1}, \theta^{t})$

#### Derivatives

#### First order derivatives

$$\frac{\partial \mathcal{L}}{\partial \boldsymbol{\theta}_{c}} = \beta \left( N \left\langle \frac{\partial U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \boldsymbol{\theta}_{c}} \right\rangle_{\boldsymbol{p}_{c}(\mathbf{X}^{(i)} | \boldsymbol{\theta}_{c}^{t})} - \sum_{i=1}^{N} \left\langle \frac{\partial U_{c}(\mathbf{X}^{(i)}, \boldsymbol{\theta}_{c})}{\partial \boldsymbol{\theta}_{c}} \right\rangle_{\boldsymbol{q}(\mathbf{X}^{(i)} | \mathbf{x}^{(i)}, \boldsymbol{\theta}_{cf}^{t}, \boldsymbol{\theta}_{c}^{t})} \right\rangle$$
$$\frac{\partial \mathcal{L}}{\partial \boldsymbol{\theta}_{cf}} = \left\langle \frac{1}{\boldsymbol{p}_{cf}(\mathbf{x}^{(1:N)} | \mathbf{X}, \boldsymbol{\theta}_{cf})} \frac{\partial \boldsymbol{p}_{cf}(\mathbf{x}^{(1:N)} | \mathbf{X}, \boldsymbol{\theta}_{cf})}{\partial \boldsymbol{\theta}_{cf}} \right\rangle_{\boldsymbol{q}(\mathbf{X}^{(1:N)} | \mathbf{x}^{(1:N)}, \boldsymbol{\theta}_{cf}^{t}, \boldsymbol{\theta}_{c}^{t})}$$

#### Second order derivatives

$$\begin{split} \frac{\partial^{2} \mathcal{L}}{\partial \theta_{k} \partial \theta_{l}} &= -\beta \sum_{i=1}^{N} \left\langle \frac{\partial^{2} U_{c}(\mathbf{X}^{(i)}, \boldsymbol{\theta}_{c})}{\partial \theta_{k} \partial \theta_{l}} \right\rangle_{q(\mathbf{X}^{(i)}|\mathbf{x}^{(i)}, \boldsymbol{\theta}_{c}^{\prime}, \boldsymbol{\theta}_{c}^{\prime})} + \beta N \left\langle \frac{\partial^{2} U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \theta_{k} \partial \theta_{l}} \right\rangle_{p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c})} \\ &- \beta^{2} N \left\langle \frac{\partial U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \theta_{k}} \frac{\partial U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \theta_{l}} \right\rangle_{p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c})} \\ &+ \beta^{2} N \left\langle \frac{\partial U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \theta_{k}} \right\rangle_{p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c})} \left\langle \frac{\partial U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c})}{\partial \theta_{l}} \right\rangle_{p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c})} \end{split}$$



#### **Robbins-Monro Optimization**

Gradients are sample averages  $\rightarrow$  noise afflicted.

Robbins-Monro Algorithm

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t + \alpha_t \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}^t)$$

with

$$\alpha_t = \frac{\alpha}{(t+A)^{
ho}}, \text{ with } \frac{1}{2} < 
ho \leq 1.$$

- Convergence is guaranteed to the true optimum  $\theta^*$  if infinite steps performed.
- $\alpha_t$  is a sequence of real numbers and has to fulfill:

$$\sum_{t=1}^{\infty} \alpha_t = \infty \ \text{ and } \ \sum_{t=1}^{\infty} \alpha_t^2 < \infty$$

#### Laplace Approximation

Approximating a density function  $p(\mathbf{z}) = \frac{1}{Z}f(\mathbf{z})$  by

$$q(\mathsf{z}) = \mathcal{N}(\mathsf{z}|\mathsf{z}_0, \mathbf{\Sigma})$$

with 
$$\mathbf{\Sigma} = (-\nabla \nabla f(\mathbf{z})|_{\mathbf{z}=_0})^{-1}$$
 and  $\nabla f(\mathbf{z})|_{\mathbf{z}=\mathbf{z}_0} = 0$ .



Figure : Laplace approximation<sup>[3]</sup>

For the given problem using a noniformative prior it follows

Laplace approximation  $\frac{\partial^2 \log p(\boldsymbol{\theta}_{cf} | \mathbf{x}^{(1:N)})}{\partial \boldsymbol{\theta}_{cf}^2} = \sum_{i}^{N} \left\langle \frac{\partial^2 \log p_{cf}(\mathbf{x}^{(i)} | \mathbf{X}^{(i)}, \boldsymbol{\theta}_{cf})}{\partial \boldsymbol{\theta}_{cf}^2} \right\rangle_{q(\mathbf{X}^{(i)})}$ 

#### Predictive uncertainty

Propagate uncertainty induced by mapping

$$\begin{aligned} \bullet \ \theta_{cf}^{i} \sim \mathcal{N}(\theta_{cf}^{MAP}, \mathbf{\Sigma}) \text{ with } \mathbf{\Sigma} &= \left(-\frac{\partial^{2} \log p(\theta_{cf}|\mathbf{x}^{(1:N)})}{\partial \theta_{cf}^{2}}\right)^{-1} \\ \bullet \ \mathbf{X}^{ij} \sim p_{c}(\mathbf{X}|\boldsymbol{\theta}_{c}^{MAP}) \\ \bullet \ \mathbf{x}_{k}^{ij} \sim p_{cf}(\mathbf{x}|\mathbf{X}^{ij}, \boldsymbol{\theta}_{cf}^{i}) \end{aligned}$$

Predictice uncertainty of properties:

$$\left\langle f|_{m{ heta}_{c},m{ heta}_{cf}^{i}}=
ight
angle =\int f(\mathbf{x}) p_{cf}(\mathbf{x}|\mathbf{X},m{ heta}_{cf}^{i}) p_{c}(\mathbf{X}|m{ heta}_{c}^{MAP}) d\mathbf{X} d\mathbf{x}$$

- Applying proposed method ('predCg') for coarse-graining a one dimensional Ising Model
- Comparison between 'predCg' and the deterministic formulation of minimizing the KL-divergence ('relEntr') by Shell (2008)
- Assessed by predictive capabilities for magnetization and correlation

## Ising Model - System Setting

The Ising-model regarded in the following discussion is one dimensional. It has the properties:



- System size  $n_{\rm f}$  in fine- and  $n_{\rm c}$  in coarse-scale
- Level of coarse-graining  $I_{c} = \frac{n_{f}}{n_{c}}$
- Inverse temperature  $\beta$
- External field  $\mu$
- ▶ Regarded interaction length L<sub>f</sub> in fine- and L<sub>c</sub> in coarse scale, including all interactions k ≤ L
- $J_0 = 1$  overall interaction strength

## Ising Model - Potential in Fine-Scale

Fine variables take the values  $x_i \in \{-1, 1\}$  following  $p_f(\mathbf{x}|\beta) \propto \exp(-\beta U(\mathbf{x}, J_k, \mu))$ :

Fine-scale potential

$$U(\mathbf{x}, J_k, \mu) = -rac{1}{2} \sum_{k=1}^{L_{\mathrm{f}}} J_k \sum_{|i-j|=k} x_i x_j - \mu \sum_{i=1}^{n_{\mathrm{f}}} x_i$$

with  $i, j \in \{1, \ldots, n_f\}$  having  $n_f$  lattice sites.

- ▶ Maximal interactions of L<sub>f</sub> sites apart are regarded in the potential.
- ▶ |i j| = k interpreted as summation over neighbors k over all sites i sites apart
- $J_k$ , strength of the *k*-th interaction.

with  $J_k$  following a power law for a given overall strength  $J_0$  and exponent a,  $J_k = \frac{K}{Lk^a}$  with,

$$K = J_0 L^{1-a} \sum_{k=1}^{L} k^{-a}$$

in order to normalize the interaction strength [1].

#### Ising Model - Potential in Coarse-Scale

Coarse variables take the values  $X_i \in \{-1, 1\}$ ,  $p_c \propto \exp\{-\beta U_c(\mathbf{X}, \boldsymbol{\theta}_c, \mu)\}$ 

Coarse-scale potential

$$\begin{aligned} U_{c}(\mathbf{X}, \boldsymbol{\theta}_{c}, \mu) &= -\frac{1}{2} (\theta^{lin} \sum_{i=1}^{n_{c}} X_{i} \\ &+ \sum_{k=1}^{L_{c}} \theta_{k}^{twop} \sum_{|i-j|=k} X_{i} X_{j} \\ &+ \sum_{i=1}^{n_{c}} \theta_{mn}^{trip} \sum_{m=1}^{m} \sum_{n=1}^{x_{i}} x_{i} x_{i\pm m} x_{i\pm m\pm n}) \\ &- \mu \sum_{i=1}^{n_{c}} X_{i} \end{aligned}$$

with  $i, j \in \{1, \dots, n_c\}$  and  $n_c \ll n_f$  lattice sites.

## Ising Model - Mapping Fine to Coarse (for relative entropy)

Each coarse variable  $X_r$ ,  $r = \{1, ..., R\}$  describes S fine-scale variables  $x_{r,s}$  with  $s = \{1, ..., S\}$ . The mapping from fine-scale variables  $x_{r,s}$  to coarse variable  $X_r$  is defined as,

Fine-to-coarse mapping

$$X_r = egin{cases} +1, & rac{1}{5}\sum_{s}^{S}x_{r,s} > 0 \ -1, & rac{1}{5}\sum_{s}^{S}x_{r,s} < 0 \ U(-1,+1), & ext{otherwise} \end{cases}$$


Figure : Mapping from fine-scale x to coarse-scale X

#### Ising Model - Mapping Coarse to Fine

Coarse-to-fine mapping  $p_{cf}(\mathbf{x}|\mathbf{X}, \theta_{cf})$ 

$$p_{\rm cf}(x_{r,s}|X_r) = \theta_{\rm cf}^{\frac{1+x_{r,s}X_r}{2}} (1-\theta_{\rm cf})^{\frac{1+x_{r,s}X_r}{2}}$$

## Assumption: $x_i$ conditionally independent for given **X**:

$$\begin{split} p(\mathbf{x}^{(1:N)} | \mathbf{X}^{(1:N)}, \boldsymbol{\theta}_{cf}) &= \prod_{i=1}^{N} p_{cf}(\mathbf{x}^{(t)} | \mathbf{X}^{(t)}, \boldsymbol{\theta}_{cf}) \\ &= \prod_{i=1}^{N} \prod_{r=1}^{R} \prod_{s=1}^{S} \left( \theta_{cf}^{\frac{1+x_{r,s}^{i} X_{r}^{i}}{2}} (1 - \theta_{cf})^{\frac{1-x_{r,s}^{i} X_{r}^{i}}{2}} \right) \\ &= \theta_{cf}^{\sum_{i=1}^{N} \sum_{r=1}^{R} \sum_{s=1}^{S} \frac{1+x_{r,s}^{i} X_{r}^{i}}{2}}{(1 - \theta_{cf})^{\sum_{i=1}^{N} \sum_{s=1}^{R} \sum_{s=1}^{S} \frac{1-x_{r,s}^{i} X_{r}^{i}}{2}}} \end{split}$$



Figure : Probabilistic mapping form coarse to fine:  $p_{cf}(\mathbf{x}|\mathbf{X}, \theta_{cf})$ 

#### Which properties to predict?

The magnetization *m* is given:

Magnetization in the fine-scale

$$m_{fine} = \int \frac{1}{n} \sum_{i}^{n} x_i \ p_{f}(\mathbf{x}) d\mathbf{x}$$

Magnetization calculated with proposed method ('predcg')

$$m_{ML,fine} = \int \frac{1}{n} \sum_{i}^{n} x_{i} \ p_{cf}(\mathbf{x}|\mathbf{X}, \theta_{cf}) p_{c}(\mathbf{X}|\theta_{c}) p(\theta_{cf}, \theta_{c}|\mathbf{x}^{(1:N)}) \ d\theta_{cf} d\theta_{c} d\mathbf{X} d\mathbf{x}$$

## Quantity of Interest: Magnetization

#### Magnetization calculated with relative entropy method 'relEntr'

(deterministic mapping fine to coarse:  $X = \xi(x)$ )

- For each  $\mu$  calculate optimal model parameter  $\boldsymbol{\theta}^*_{\text{cg, det}}$
- Since we want to compare the magnetization on the same (fine) scale a mapping is introduced
  - if  $X_r = -1$ , select randomly a possible configuration  $x_{r,s}$  where either all
    - $x_{r,s} = -1$  or one is  $x_{r,s} = -1$  and the other  $x_{r,s} = 1$  (for given  $r: s \in \{1 \dots l_c\}$ )
  - ▶ if  $X_r = +1$ , select randomly a possible configuration  $x_{r,s}$  where either all  $x_{r,s} = +1$  or one is  $x_{r,s} = +1$  and the other  $x_{r,s} = -1$  (for given  $r: s \in 1, 2$ )
- $\blacktriangleright$  For a given coarse-state the selected fine-states  $x_{\text{det}}$  are used for calculating the magnetization

Relative error in magnetization,

$$\operatorname{err}_{\operatorname{mag}} = rac{\|m - m_{\operatorname{truth}}\|}{\|m_{\operatorname{truth}}\|}.$$

The correlation  $R_l$  of all sites being separated by l sites is measured as,

$$R_l = \frac{1}{n} \sum_{|i-j|=l}^n \langle x_i x_j \rangle.$$

Relative correlation error,

$$err_{corr} = \frac{\|R - R_{truth}\|}{\|R_{truth}\|}.$$

#### Ising Model - ML Algorithm

for  $\mu = \mu_{min}$  to  $\mu_{max}$  do 1: 2: set initial fine-scale parameter:  $J_0$ ,  $n_f$ ,  $\mu$ create data set:  $\mathbf{x}^{(1:S_f)} \sim p(\mathbf{x}^{(1:S_f)}|J_0, \mu, \beta)$  with  $S_f$  samples 3. set initial coarse-graining parameter:  $\theta_{c0}, \theta_{cf0}, n_{c} = \frac{n_{f}}{L}, \mu$ 4: 5:  $\theta_c^t \leftarrow \theta_{c0}$  $\theta_{rf}^t \leftarrow \theta_{cf0}$ 6: 7: while !(Convergence check passed) do  $\begin{array}{l} \text{function } \bar{E}\text{-}\text{STEP} \\ \mathbf{X} \sim a(\mathbf{X}|\mathbf{x}^{(1:N)}, \boldsymbol{\theta}^t_{-\epsilon}, \boldsymbol{\theta}_{-\epsilon}^t, \boldsymbol{\mu}) \propto p_{cf}(\mathbf{x}^{(1:N)}|\mathbf{X}, \boldsymbol{\theta}_{-\epsilon}^t)p_{c}(\mathbf{X}|\boldsymbol{\theta}_{-\epsilon}^t, \boldsymbol{\mu}) \text{ with } S_q \text{ per data point } \mathbf{x}^{(i)} \end{array}$ 7: 8: 8: function M-STEP  $\frac{\partial \mathcal{L}}{\partial \theta_{\mathsf{c}}} = -\beta \left\langle \frac{\partial U_{\mathsf{c}}(\mathbf{X}, \theta_{\mathsf{c}})}{\partial \theta_{\mathsf{c}}} \right\rangle_{q(\mathbf{X}|\mathbf{x}^{(1:N)}, \theta_{\mathsf{c}}^{\mathsf{t}}, \theta_{\mathsf{c}}^{\mathsf{t}})} + \beta \left\langle \frac{\partial U_{\mathsf{c}}(\mathbf{X}, \theta_{\mathsf{c}})}{\partial \theta_{\mathsf{c}}} \right\rangle_{P_{\mathsf{c}}(\mathbf{X}|\theta_{\mathsf{c}}^{\mathsf{t}})}$ 9:  $\frac{\partial \mathcal{L}}{\partial \boldsymbol{\theta}_{cf}} = \left\langle \frac{1}{p_{-r}(\mathbf{x}^{(1:N)} | \mathbf{X}, \boldsymbol{\theta}_{cf})} \frac{\partial p_{cf}(\mathbf{x}^{(1:N)} | \mathbf{X}, \boldsymbol{\theta}_{cf})}{\partial \boldsymbol{\theta}_{cf}} \right\rangle_{q(\mathbf{X} | \mathbf{x}, \boldsymbol{\theta}_{cf}^{t}, \boldsymbol{\theta}_{c}^{t})}$ 10:  $\boldsymbol{\theta}_{c}^{t+1} \leftarrow \boldsymbol{\theta}_{c}^{t} + \alpha_{\boldsymbol{\theta}_{c}} \frac{\partial \mathcal{L}}{\partial \boldsymbol{\theta}_{c}}$ 11:  $\boldsymbol{\theta}_{cf}^{t+1} \leftarrow \boldsymbol{\theta}_{cf}^{t} + \alpha_{\boldsymbol{\theta}_{cf}} \frac{\partial \mathcal{L}}{\partial \boldsymbol{\theta}_{cf}}$ 12: 13: end while  $\mathbf{x}_{pred} \sim \tilde{p}(\mathbf{x}_{new} | \boldsymbol{\theta}_{c}^{t}, \boldsymbol{\theta}_{cf}^{t})$  with  $S_{pred} * S_{c}$  samples 14: function EVALMAG( $x_{pred}, x^{(1:N)}$ ) 14: function EVALCORR( $x_{pred}$ ,  $x^{(1:N)}$ ) 14: 15: end for=0

#### Ising Model - Posterior and Prediction

- () Behavior of parameters with respect to  $\mu$
- 2 Influence of available data  $S_{\rm f}$  for training the model
- 3 Level of coarse-graining
- 4 Aspects of coarse-grained models

#### Behavior of parameters with respect to $\mu$

Constant attributes:

- $S_{
  m c} = 200$  (samples  $\mathbf{X} \sim p_{
  m c}(\mathbf{X}|m{ heta}_{
  m c}))$
- $S_q = 50$  (samples  $\mathbf{X} \sim q(\mathbf{X}^{(i)} | \mathbf{x}^{(i)}, \boldsymbol{ heta_c}, \boldsymbol{ heta_{cf}}))$
- $J_0 = 1$  (overall interaction strength)

•  $S_{pred} = 100S_c$  (samples for prediction step after learning the model) Furthermore:

- $n_{\rm f} = 32$ , system size fine-scale
- ▶  $L_{\rm f} = L_{\rm c} = 1$ , in fine- and coarse scale nearest-neighbor interactions are regarded

#### Behavior of parametrization with respect to $\mu$

The potentials follows to,

$$U(J,\mu) = -\frac{1}{2}J\sum_{|i-j|=1} x_i x_j - \mu \sum_{i=1}^{n_f} x_i$$
$$U_{c}(\theta_{c},\mu) = -\frac{1}{2}\theta_{c}\sum_{|i-j|=1} X_i X_j - \mu \sum_{i=1}^{n_c} X_i$$

- ▶ Learn two parameters  $\theta_{c}$  and  $\theta_{cf}$  of the mapping  $p_{cf}$
- Learning for every evaluated  $\mu$ :  $\mu = [-4.5, 4.5]$  with a step size of 0.6



Figure :  $\theta_c$ : Parameter of potential  $U_c$ 

Figure :  $\theta_{cf}$ : Parameter of the mapping  $p_{cf}(\mathbf{x}|\mathbf{X}, \theta_{cf})$ 



Figure : Magnetization

#### Key aspects

- True magnetization based on data set and predicted by 'predCg' coincides.
- Method 'relEntr' not able to predict data set due to missing mapping capabilities from coarse to fine.
- ▶ Parameters  $\theta_c$  and  $\theta_{cf}$  behave symmetrical with respect to  $\mu = 0$ .
- Stronger interaction  $\theta_c$  for bigger  $|\mu|$  but also higher probability  $\theta_{cf}$  that the coarse configuration reflects the fine configuration.

- $\blacktriangleright$  Learn  $\boldsymbol{\theta}_{\mathsf{c}}$  and  $\boldsymbol{\theta}_{\mathsf{cf}}$  at each evaluated  $\mu$
- Given different size of data-set  $S_f$  with  $S_f \in \{5, 10, 20, 50\}$ .
- ▶ Interaction length in fine-scale  $L_f = 10$  with exponential decay of overall strength  $J_0 = 1.5$

#### Potentials

$$U_{f}(J,\mu) = -\frac{1}{2} \sum_{k}^{L_{f}} J_{k} \sum_{|i-j|=k} x_{i}x_{j} - \mu \sum_{i=1}^{n_{f}} x_{i}$$
$$U_{c}(\theta_{c},\mu) = -\frac{1}{2} \theta_{c} \sum_{|i-j|=1} X_{i}X_{j} - \frac{1}{2} \theta_{c}^{lin} \sum_{i}^{n_{c}} X_{i} - \mu \sum_{i=1}^{n_{c}} X_{i}.$$



Figure : Uncertainty in magnetization  $S_f = 10$ 



Figure : Uncertainty in magnetization  $S_f = 20$ 

Figure : Uncertainty in magnetization  $S_f = 50$ 



Figure : Relative mean error of magnetization with respect to increasing amount of data  $S_{\rm f}$ ,  $S_{\rm f} \in \{5, 10, 20, 50, 100\}$ 

 $\begin{array}{l} \mbox{Figure}: \mbox{Relative mean error of correlation with} \\ \mbox{respect to increasing amount of data } S_{\rm f}, \\ \mbox{S}_{\rm f} \in \{5, 10, 20, 50, 100\} \end{array}$ 



Figure : Correlation  $R_l$  for  $\mu = 0$  with  $S_f \in \{5, 10, 20, 50, 100\}$ 

- Uncertainty decreasing with increasing amount of data available
- By using S<sub>f</sub> = 5 predictions resembling true magnetization well

#### Predictability by various levels of coarse-gaining

- Choose various level of coarse-graining I<sub>c</sub>
- ▶ Mapping  $p_{cf}(\mathbf{x}|\mathbf{X}, \boldsymbol{\theta}_{cf})$  responsible for  $I_c \in \{2, 4, 8, 16\}$  fine variables
- Coarse-grained potential  $U_{\rm c}(\mathbf{X}, \boldsymbol{\theta}_{\rm c})$  as given before



## Predictability by various levels of coarse gaining



Figure : Uncertainty in magnetization  $I_c = 8$ 

#### Predictability by various levels of coarse gaining



Figure : Uncertainty in magnetization  $I_c = 4$ 

Figure : Uncertainty in magnetization  $I_c = 2$ 

## Predictability by various levels of coarse gaining



Figure : Correlation  $R_l$  at  $\mu = 0$  with  $l_c \in \{2, 4, 8, 16\}$ 

- Applying l<sub>c</sub> = 8 leads already to good predictions in magnetization
- Predicting correlations needs finer resolution in coarse-scale

## Model Comparison

- Assumption before: Model is given for potential  $U_{\rm c}(\mathbf{X}, \boldsymbol{\theta}_{\rm c})$
- Using different order of interactions and interaction lengths



## Model Comparison



#### Model [abc]

- (a) a = 0 no linear term, a = 1 linear term
- (b) b = 0 no 2nd order term, b = x 2nd order term up to interaction length  $L_c = x$
- (c) c = 0 no third order term, c = 1 third order term on (nearest correlation)

- Linear term necessary to describe data
- Second order interaction necessary
- ► In correlation: errors decreasing for including 2nd order interactions with higher interaction lengths *L*<sub>c</sub>
- No further improvement for longer ranged third order interactions

#### Outline

Numerical issues / efficiency

- Use advanced sampling methods / optimization methods, using curvature information (in progress)
- Variational approximations
- Coarse-Graining
  - Hierarchical coarse-graining
  - How to select mappings from coarse to fine?
- Probit- or Logit-classification model, O model for coarse variables
   Algorithmic
  - Approach with sparsity priors for model selection (in progress).

## Bibliography I



#### S. Are, M. A. Katsoulakis, P. Plecháč, and L. R. Bellet.

Multibody Interactions in Coarse-Graining Schemes for Extended Systems. SIAM Journal on Scientific Computing, 31(2):987-1015, 2008.



I. Bilionis and N. Zabaras

A stochastic optimization approach to coarse-graining using a relative-entropy framework. The Journal of chemical physics, 138(4):044313, Jan. 2013.



#### C. M. Bishop.

Pattern Recognition and Machine Learning. Springer, 2006.



A. Chaimovich and M. S. Shell.

Coarse-graining errors and numerical optimization using a relative entropy framework. The Journal of chemical physics, 134(9):094112, Mar. 2011.



#### F. Ercolessi and J. B. Adams.

Interatomic potentials from first-principles calculations: The force-matching method. EPL (Europhysics Letters), 26(8):583, 1994.



#### S. Izvekov and G. A. Voth.

Multiscale coarse graining of liquid-state systems. J. Chem. Phys., 123(13):134105, 2005.



#### M. Katsoulakis, P. Plecháč, and L. Rey-Bellet.

Numerical and statistical methods for the coarse-graining of many-particle stochastic systems. Journal of Scientific Computing, 37(1):43-71, 2008.



#### A. P. Lyubartsev and A. Laaksonen.

Calculation of effective interaction potentials from radial distribution functions: A reverse Monte Carlo approach. Phys. Rev. E. 52:3730-3737. Oct 1995.

## Bibliography II



#### D. Ming and M. E. Wall.

Allostery in a coarse-grained model of protein dynamics. *Phys. Rev. Lett.*, 95:198103, Nov 2005.



#### M. S. Shell.

The relative entropy is fundamental to multiscale and inverse thermodynamic problems. J. Chem. Phys., 129(14):144108, 2008.